

(L, M) –Smooth Ideal Structures

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Abstract

In this paper we establish the concept of (L, M) –smooth ideal and (L, M) –smooth local map of (L, M) –smooth ideals with (L, M) –smooth topologies. We study a new sort of (L, M) –smooth ideal and (L, M) –smooth local map namely (L, M) –smooth ideal and r –smooth open local map. Many of its characterizations, properties and connections between it and other corresponding fuzzy notions are studied.

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1 Introduction

. Šostak [16] introduced the notion of $(L, \wedge)$ –fuzzy topological spaces as a generalization of L –topological spaces. Höhle and Šostak [11] substitute a complete quasi-monoidal lattice (or GL-monoid) instead of a completely distributive lattice or a unit interval. Also they introduced the concept of L –filters for a complete quasi-monoidal lattice L which is the dual of fuzzy ideals. Many authors [1-10, 12-15, 17, 18, 19, 20] studied the structures of fuzzy topology and the structures of fuzzy filters, fuzzy ideals and fuzzy smooth ideals. Ramadan, Abdel-Sattar and Kim [14] studied the concept of a smooth

ideals in $[0,1]$ -smooth topological spaces. Abdel-Sattar [2] studied some structures of $(L, \odot)$ -smooth topological spaces and their properties. In [6] he studied the concept of L -smooth ideals and L -smooth ideal bases in $(L, \odot)$ -smooth topological spaces. In [19] we study some results of fuzzy ideals since the lattice is the closed interval $I = [0, 1]$. In this paper we establish the structures of (L, M) -smooth ideal by (L, M) -smooth topological spaces [22]. The concept of r -smooth open local map, new space namely (L, M) -smooth ideal topological spaces and many of its characterizations are studied.

2 Preliminaries

Throughout this paper, let X be a nonempty set. $L = (L, \leq, \vee, \odot, ', 0, 1)$ denotes a completely distributive lattice with order-reversing involution $'$ which has the least and greatest elements, say 0 and 1, respectively. Let L^X be the family of all L -fuzzy subsets of X . For $\alpha \in L$, $\underline{\alpha}(x) = \alpha$ for all $x \in X$. A

fuzzy point, x_t for $t \in L$ is an element of L^X such that, for $y \in X$,

$$x_t(y) = \begin{cases} t & \text{if } y = x, \\ 0 & \text{if } y \neq x. \end{cases}$$

The set of all fuzzy points in X is denoted by $Pt(X)$. A fuzzy point $x_t \in \lambda$ iff $t \leq \lambda(x)$. A fuzzy set λ is quasi-coincident with μ , denoted by $\lambda q \mu$, if there exists $x \in X$ such that $\lambda(x) + \mu(x) > 1$. If λ is not quasi-coincident with μ , we denote $\lambda \bar{q} \mu$. All the other notations and the other definitions are standard in fuzzy set theory.

Definition 2.1. [11] A triple $(L, \leq, \odot)$ is called a strictly two-sided, commutative quantale (stsc-quantale, for short) iff it satisfies the following properties:

- (L1) $L = (L, \leq, 1, 0)$ is a complete lattice.
- (L2) $(L, \odot)$ is a commutative semigroup.
- (L3) $a = a \odot 1$, for each $a \in L$.
- (L4) $\odot$ is distributive over arbitrary joins, i.e. $(\bigvee_{i \in \Gamma} a_i) \odot b = \bigvee_{i \in \Gamma} (a_i \odot b)$.

Example 2.2 [11] (1) Each frame is a stsc-quantale. In particular, the unit interval $([0, 1], \leq, \vee, \wedge, 0, 1)$ is a stsc-quantale.

(2) The unit interval with a left-continuous t-norm t , $([0, 1], \leq, t)$, is a stsc-quantale.

(3) Every GL-monoid is a stsc-quantale.

(4) Define a binary operation $\odot$ on $[0, 1]$ by $x \odot y = \max\{0, x + y - 1\}$. Then $([0, 1], \leq, \odot)$ is a stsc-quantale.

Lemma 2.3 [21] **For each** $x, y, z, x_i, y_i, w \in L$, we have the following properties:

- (1) $\top \rightarrow x = x$, $\perp \odot x = \perp$,
- (2) if $y \leq z$, then $x \odot y \leq x \odot z$, $x \oplus y \leq x \oplus z$, $x \rightarrow y \leq x \rightarrow z$ and $z \rightarrow x \leq y \rightarrow x$,
- (3) $x \leq y$ iff $x \rightarrow y = \top$,
- (4) $(\wedge_i y_i)^* = \vee_i y_i^*$, $(\vee_i y_i)^* = \wedge_i y_i^*$,
- (5) $x \rightarrow (\wedge_i y_i) = \wedge_i (x \rightarrow y_i)$,
- (6) $(\vee_i x_i) \rightarrow y = \wedge_i (x_i \rightarrow y)$,
- (7) $x \odot (\vee_i y_i) = \vee_i (x \odot y_i)$,
- (8) $(\wedge_i x_i) \oplus y = \wedge_i (x_i \oplus y)$,
- (9) $(x \odot y) \rightarrow z = x \rightarrow (y \rightarrow z) = y \rightarrow (x \rightarrow z)$,
- (10) $(x \odot y) = (x \rightarrow y^*)^*$, $x \oplus y = x^* \rightarrow y$ and $x \rightarrow y = y^* \rightarrow x^*$,
- (11) $(x \rightarrow y) \odot (z \rightarrow w) \leq (x \odot z) \rightarrow (y \odot w)$,
- (12) $x \rightarrow y \leq (x \odot z) \rightarrow (y \odot z)$ and $(x \rightarrow y) \odot (y \rightarrow z) \leq x \rightarrow z$,
- (13) $(x \rightarrow y) \odot (z \rightarrow w) \leq (x \oplus z) \rightarrow (y \oplus w)$,
- (14) $x \odot (x \rightarrow y) \leq y$ and $y \leq x \rightarrow (x \odot y)$,
- (15) $(x \vee y) \odot (z \vee w) \leq (x \vee z) \vee (y \odot w) \leq (x \oplus z) \vee (y \odot w)$,
- (16) $\vee_{i \in \Gamma} x_i \rightarrow \vee_{i \in \Gamma} y_i \geq \wedge_{i \in \Gamma} (x_i \rightarrow y_i)$, $\wedge_{i \in \Gamma} x_i \rightarrow \wedge_{i \in \Gamma} y_i \geq \wedge_{i \in \Gamma} (x_i \rightarrow y_i)$,
- (17) $(x \odot y) \odot (z \oplus w) \leq (x \odot z) \oplus (y \odot w)$,
- (18) $z \rightarrow x \leq (x \rightarrow y) \rightarrow (z \rightarrow y)$ and $(y \rightarrow z) \leq (x \rightarrow y) \rightarrow (x \rightarrow z)$.
- (19) $(x^*)^* = x$

All algebraic operations on L can be extended pointwise to the set L^X as follows: $\forall x \in X, \forall \lambda, \mu \in L^X$

- (1) $\lambda \leq \mu \iff \lambda(x) \leq \mu(x)$,
- (2) $(\lambda \odot \mu)(x) = \lambda(x) \odot \mu(x)$,
- (3) $(\lambda \rightarrow \mu)(x) = \lambda(x) \rightarrow \mu(x)$.

Definition 2.4. [2,11,12] A mapping $\mathcal{T} : L^X \rightarrow M$ is called (L, M) –smooth topology on X if it satisfies the following conditions:

- (O1) $\mathcal{T}(\underline{0}) = \mathcal{T}(\underline{1}) = 1$, where $\underline{0}(x) = 0$ and $\underline{1}(x) = 1$ for all $x \in X$.
- (O2) $\mathcal{T}(\mu_1 \odot \mu_2) \geq \mathcal{T}(\mu_1) \odot \mathcal{T}(\mu_2)$, for any $\mu_1, \mu_2 \in L^X$.
- (O3) $\mathcal{T}(\vee_{i \in \Gamma} \mu_i) \geq \wedge_{i \in \Gamma} \mathcal{T}(\mu_i)$, for any $\{\mu_i\}_{i \in \Gamma} \subset L^X$.

An (L, M) –smooth topological spaces is called enriched if

- (P) $\mathcal{T}(\alpha \odot \mu) \geq \mathcal{T}(\mu)$, for any $\mu \in L^X$, and $\alpha \in M$.

The pair $(X, \mathcal{T})$ is called (L, M) – smooth topological spaces (resp. enriched (L, M) – smooth topological spaces)

Let $(X, \mathcal{T})$ and $(Y, \mathcal{T}')$ be two (L, M) –smooth topological spaces and $f : X \rightarrow Y$ be a mapping. Then f is said to be smooth continuous iff $\mathcal{T}'(\mu) \leq \mathcal{T}(f^{-1}(\mu))$ for each $\mu \in L^Y$.

Definition 2.5. [11] Let $(L, *)$ and $(L, \odot)$ be a stsc-quantale. An operation $\odot$ dominates $*$ if it satisfies: $\forall x_1, x_2, y_1, y_2 \in L \Rightarrow (x_1 * y_1) \odot (x_2 * y_2) \geq (x_1 \odot x_2) * (y_1 \odot y_2)$

Definition 2.6. [11] Let $(L, *)$ and $(L, \odot)$ be a stsc-quantale. An operation $\odot$ dominates $*$ if it satisfies: $\forall x_1, x_2, y_1, y_2 \in L \Rightarrow (x_1 * y_1) \odot (x_2 * y_2) \geq (x_1 \odot x_2) * (y_1 \odot y_2)$

Example 2.7. [11]

(1) For any left-continuous t-norm $*$, $\wedge$ dominates $*$ because $(x_1 * y_1) \wedge (x_2 * y_2) \geq (x_1 \wedge x_2) * (y_1 \wedge y_2)$.

(2) Define t-norm as $x \odot y = \frac{x \cdot y}{x + y - x \cdot y}$ and $x * y = x \cdot y$. Then $\odot$ dominates $*$.

Definition 2.8. [14] If X is a set, then an ideal on X is a nonempty $D^* \subset 2^X$ satisfying the following conditions:

- 1- $X \notin D^*$.
- 2- If $A, B \in D^* \Rightarrow A \cup B \in D^*$.
- 3- If $B \in D^*$ and $A \subset B \Rightarrow A \in D^*$, i.e., D^* is a lower set.

Definition 2.9. [14] If X is a set, then a preideal on X is a nonempty $D \subset I^X$ satisfying the following conditions:

- 1- $\underline{1} \notin D$.
- 2- If $\lambda, \mu \in D \Rightarrow \lambda \vee \mu \in D$.
- 3- If $\mu \in D$ and $\lambda \leq \mu \Rightarrow \lambda \in D$.

Definition 2.10. A map $I : L^X \times M \rightarrow L^X$ is called (L, M) -smooth interior operator on X iff I satisfies the following conditions :

- (I1) $I(\underline{1}, r) = \underline{1}$ for all $r \in M$.
- (I2) $I(\lambda, r) \leq \lambda$ for all $r \in M$.
- (I3) If $\lambda \leq \mu$ and $r \leq s$, then $I(\lambda, s) \leq I(\mu, r)$.
- (I4) $I(\lambda \odot \mu, r \odot s) \geq I(\lambda, r) \odot I(\mu, s)$.

The pair (X, I) is called (L, M) -smooth interior space.

The (L, M) -smooth interior operator I is called topological if

$$I(I(\lambda, r)) \geq I(\lambda, r), \forall \lambda \in L^X, r \in M.$$

Let I_1 and I_2 be two (L, M) -smooth interior operators on X . We say that I_1 is finer than I_2 (I_2 is coarser than I_1), denoted by $I_2 \leq I_1$, if $I_2(\lambda, r) \leq I_1(\lambda, r)$ for all $\lambda \in L^X, r \in M$.

Theorem 2.11. Let (X, τ) be (L, M) -smooth topological spaces. Then for each $r \in M, \mathcal{A} \in L^X$, we define the operator $C_\tau : L^X \times M \rightarrow L^X$ as follows:

$$C_\tau(\mathcal{A}, r) = \bigwedge \{ \mathcal{B} \in L^X \mid \mathcal{A} \leq \mathcal{B}, \tau(\underline{1} - \mathcal{B}) \geq r \}.$$

For each $\mathcal{A}, \mathcal{B} \in L^X$ and $r, s \in M$, the operator C_τ satisfies the following conditions:

- (C1) $C_\tau(\underline{0}, r) = \underline{0}$.
- (C2) $\mathcal{A} \leq C_\tau(\mathcal{A}, r)$.
- (C3) $C_\tau(\mathcal{A}, r) \vee C_\tau(\mathcal{B}, r) = C_\tau(\mathcal{A} \vee \mathcal{B}, r)$.
- (C4) $C_\tau(\mathcal{A}, r) \leq C_\tau(\mathcal{A}, s)$ if $r \leq s$.
- (C5) $C_\tau(C_\tau(\mathcal{A}, r), r) = C_\tau(\mathcal{A}, r)$.
- (C6) If $s = \bigvee \{r \in L_0 \mid C_\tau(\mathcal{A}, r) = \mathcal{A}\}$, then $C_\tau(\mathcal{A}, s) = \mathcal{A}$.

Definition 2.12. Let (X, τ) be (L, M) –smooth topological spaces, for each $\mathcal{A} \in L^X, r \in M$. Then:

- (1) $\mathcal{A}$ is called r -smooth regular open (**r-SRO**, for short) iff $\mathcal{A} = \text{int}_\tau(C_\tau(\mathcal{A}, r), r)$.
- (2) $\mathcal{A}$ is called r -smooth preopen (**r-SPO**, for short) iff $\mathcal{A} \leq \text{int}_\tau(C_\tau(\mathcal{A}, r), r)$.

Definition 2.13. An (L, M) –smooth topological spaces (X, τ) is called r –smooth regular iff for each $\tau(\mathcal{A}) \geq r$ and $r \in M$, $\mathcal{A} = \bigvee \{\mathcal{B} \in L^X \mid \tau(\mathcal{B}) \geq r, C_\tau(\mathcal{B}, r) = \mathcal{A}\}$.

Definition 2.14. Let (X, τ) be (L, M) –smooth topological spaces, for each $\mathcal{A} \in L^X, x_t \in P_t(X)$ and $r \in M$. Then, $\mathcal{A}$ is called r –open Q_τ -neighborhood of x_t (for short, $Q_\tau(x_t, r)$) if $x_t q \mathcal{A}$ with $\tau(\mathcal{A}) \geq r$.

Definition 2.15. Let $\underline{0} \notin \Theta$ be a subset of L^X . A mapping $\beta : \Theta \rightarrow M$ is called (L, M) –smooth base on X if it satisfies the following conditions:

- (1) $\beta(\underline{1}) = 1$,
- (2) $\beta(\mathcal{A}_1 \odot \mathcal{A}_2) \geq \beta(\mathcal{A}_1) \odot \beta(\mathcal{A}_2)$, for all $\mathcal{A}_1, \mathcal{A}_2 \in \Theta$.

Definition 2.16. Let $f : (X, \tau) \rightarrow (Y, \eta)$ be a mapping. Then,

- (1) f is called smooth continuous (S-continuous, for short) iff $\eta(\mathcal{A}) \leq \tau(f^{-1}(\mathcal{A}))$, for each $\mathcal{A} \in L^Y$.
- (2) f is called smooth precontinuous (SP-continuous, for short) iff $f^{-1}(\mathcal{A})$ is **r-SPO** set for each $\eta(\mathcal{A}) \geq r$.
- (3) f is called smooth almost continuous iff $\tau(f^{-1}(\mathcal{A})) \geq r$, for each $\mathcal{A} \in L^Y$ with $\mathcal{A} = \text{int}_\eta(C_\eta(\mathcal{A}, r), r)$.
- (4) f is called smooth weakly continuous iff $f^{-1}(\mathcal{A}) \leq \text{int}_\tau(f^{-1}(C_\eta(\mathcal{A}, r)), r)$ for each $\mathcal{A} \in L^Y$ and $r \in M$ with $\eta(\mathcal{A}) \geq r$.
- (5) f is called smooth strongly continuous iff $f(C_\tau(\mathcal{A}, r)) \leq f(\mathcal{A})$ for each $\mathcal{A} \in L^X$ and $r \in M$.

3 (L, M) – Smooth ideal and r –smooth open local map

Definition 3.1. A mapping $\mathcal{I} : L^X \rightarrow M$ is called (L, M) –smooth ideal on X if it satisfies the following conditions:

- (I_1) $\mathcal{I}(\underline{0}) = 1, \mathcal{I}(\underline{1}) = 0$.
- (I_2) If $\mathcal{A} \leq \mathcal{B}$, then $\mathcal{I}(\mathcal{B}) \leq \mathcal{I}(\mathcal{A})$, for each $\mathcal{A}, \mathcal{B} \in L^X$.
- (I_3) $\mathcal{I}(\mathcal{A} \vee \mathcal{B}) \geq \mathcal{I}(\mathcal{A}) \odot \mathcal{I}(\mathcal{B})$, for $\mathcal{A}, \mathcal{B} \in L^X$.

If $\mathcal{I}_1$ and $\mathcal{I}_2$ are (L, M) –smooth ideals on X , we say that $\mathcal{I}_1$ is finer than $\mathcal{I}_2$ ($\mathcal{I}_2$ is coarser than $\mathcal{I}_1$), denoted by $\mathcal{I}_2 \leq \mathcal{I}_1$, iff $\mathcal{I}_1(\mathcal{A}) \leq \mathcal{I}_2(\mathcal{A})$ for $\mathcal{A} \in L^X$.

The triple $(X, \tau, \mathcal{I})$ is called (L, M) –smooth ideal topological space ((L, M) –sits, for short). For $\alpha \in M$, $(X, \tau_\alpha, \mathcal{I}_\alpha)$ is fuzzy ideal topological space in the sense of Sarkar [18].

Definition 3.2. Let $(X, \tau, \mathcal{I})$ be (L, M) –sits and $\mathcal{A} \in L^X$. Then the r –smooth open local map $\mathcal{A}_r^*(\tau, \mathcal{I})$ of $\mathcal{A}$ is the union of all fuzzy points x_t such that if $\mathcal{B} \in Q(x_t, r)$ and $\mathcal{I}(\mathcal{C}) \geq r$ then there is at least one $y \in X$ for which $\mathcal{B}(y) + \mathcal{A}(y) - 1 > \mathcal{C}(y)$.

there exists $\mathcal{B} \in Q(x_t, r)$ such that for every $y \in X$, $\mathcal{B}(y) + \mathcal{A}(y) - 1 \leq \mathcal{C}(y)$, for some $\mathcal{I}(\mathcal{C}) \geq r$. $\mathcal{A}_r^*(\tau, \mathcal{I})$ is the set of fuzzy points at which $\mathcal{A}$ does not have the property r –fuzzy open locally.

We will occasionally write $\mathcal{A}_r^*$ or $\mathcal{A}_r^*(\mathcal{I})$ for $\mathcal{A}_r^*(\tau, \mathcal{I})$ and it will cause no ambiguity.

Example 3.3. Let $(X, \tau, \mathcal{I})$ be (L, M) –sits. The simplest fuzzy ideal on X is $\mathcal{I}^0 : L^X \rightarrow M$ where

$$\mathcal{I}^0(\mathcal{C}) = \begin{cases} 1, & \text{if } \mathcal{C} = \underline{0}, \\ 0, & \text{otherwise.} \end{cases}$$

If we take $\mathcal{I} = \mathcal{I}^0$, for each $\mathcal{A} \in L^X$ we have $\mathcal{A}_r^* = C_\tau(\mathcal{A}, r)$.

Theorem 3.4. Let (X, τ) be (L, M) –smooth topological space and $\mathcal{I}_1, \mathcal{I}_2$ be two (L, M) –smooth ideals of X . Then for each $r \in M$ and $\mathcal{A}, \mathcal{B} \in L^X$.

- (1) If $\mathcal{A} \leq \mathcal{B}$, then $\mathcal{A}_r^* \leq \mathcal{B}_r^*$.
- (2) If $\mathcal{I}_1 \leq \mathcal{I}_2$, then $\mathcal{A}_r^*(\mathcal{I}_1, \tau) \geq \mathcal{A}_r^*(\mathcal{I}_2, \tau)$.
- (3) $\mathcal{A}_r^* = C_\tau(\mathcal{A}_r^*, r) \leq C_\tau(\mathcal{A}, r)$.
- (4) $(\mathcal{A}_r^*)_r^* \leq \mathcal{A}_r^*$.
- (5) $(\mathcal{A}_r^* \vee \mathcal{B}_r^*)_r^* = (\mathcal{A} \vee \mathcal{B})_r^*$.
- (6) If $\mathcal{I}(\mathcal{B}) \geq r$, then $(\mathcal{A} \vee \mathcal{B})_r^* = \mathcal{A}_r^* \vee \mathcal{B}_r^* = \mathcal{A}_r^*$.
- (7) If $\tau(\mathcal{B}) \geq r$, then $(\mathcal{B} \odot \mathcal{A}_r^*) \leq (\mathcal{B} \odot \mathcal{A})_r^*$.

$$(8) (\mathcal{A}_r^* \odot \mathcal{B}_r^*) \geq (\mathcal{A} \odot \mathcal{B})_r^*.$$

Proof. (1) Suppose there exist $\mathcal{A} \in L^X$ and $r \in M$ such that $\mathcal{A}_r^* \not\leq \mathcal{B}_r^*$, there exist $x \in X$ and $t \in M$ such that

$$\mathcal{A}_r^*(x) \geq t > \mathcal{B}_r^*(x).$$

Since $\mathcal{B}_r^*(x) < t$, there exists $\mathcal{D} \in Q(x_t, r)$ with $\mathcal{I}(\mathcal{C}) \geq r$ such that for every $y \in X$, we have,

$$\mathcal{D}(y) + \mathcal{B}(y) - 1 \leq \mathcal{C}(y).$$

Since $\mathcal{A} \leq \mathcal{B}$, $\mathcal{D}(y) + \mathcal{A}(y) - 1 \leq \mathcal{C}(y)$. So, $\mathcal{A}_r^*(x) < t$, and this is a contradiction. Thus, $\mathcal{A}_r^* \leq \mathcal{B}_r^*$.

(2) Suppose that, $\mathcal{A}_r^*(\mathcal{I}_1, \tau) \not\leq \mathcal{A}_r^*(\mathcal{I}_2, \tau)$, then there exist $x \in X$ and $t \in M$ such that

$$\mathcal{A}_r^*(\mathcal{I}_1, \tau)(x) < t \leq \mathcal{A}_r^*(\mathcal{I}_2, \tau)(x).$$

Since $\mathcal{A}_r^*(\mathcal{I}_1, \tau)(x) < t$, there exists $\mathcal{D} \in Q(x_t, r)$ with $\mathcal{I}_1(\mathcal{C}) \geq r$ such that for every $y \in X$, we have, $\mathcal{D}(y) + \mathcal{A}(y) - 1 \leq \mathcal{C}(y)$. Since $\mathcal{I}_2(\mathcal{C}) \geq \mathcal{I}_1(\mathcal{C}) \geq r$, $\mathcal{D}(y) + \mathcal{A}(y) - 1 \leq \mathcal{C}(y)$. Thus, $\mathcal{A}_r^*(\mathcal{I}_2, \tau)(x) < t$. It is a contradiction. Thus, $\mathcal{A}_r^*(\mathcal{I}_1, \tau) \geq \mathcal{A}_r^*(\mathcal{I}_2, \tau)$.

(3) We show that $\mathcal{A}_r^* \leq C_\tau(\mathcal{A}, r)$. Suppose that, $\mathcal{A}_r^* \not\leq C_\tau(\mathcal{A}, r)$, then there exist $x \in X$ and $t \in M$ such that

$$\mathcal{A}_r^*(x) \geq t > C_\tau(\mathcal{A}, r)(x).$$

Since $\mathcal{A}_r^*(x) \geq t$, $x_t \in \mathcal{A}_r^*$. So there is at least one $y \in X$ for each $\mathcal{D} \in Q(x_t, r)$ and $\mathcal{I}(\mathcal{C}) \geq r$ such that $\mathcal{D}(y) + \mathcal{A}(y) > \mathcal{C}(y) + 1$. Therefore, $x_t \in C_\tau(\mathcal{A}, r)$. It is a contradiction. Hence, $\mathcal{A}_r^* \leq C_\tau(\mathcal{A}, r)$.

Now we show that $\mathcal{A}_r^* \geq C_\tau(\mathcal{A}_r^*, r)$. Suppose that, $\mathcal{A}_r^* \not\geq C_\tau(\mathcal{A}_r^*, r)$, then there exist $x \in X$ and $t \in M$ such that

$$\mathcal{A}_r^*(x) < t < C_\tau(\mathcal{A}_r^*, r)(x).$$

Since $C_\tau(\mathcal{A}_r^*, r)(x) > t$, $x_t \in C_\tau(\mathcal{A}_r^*, r)$. So, there at last one $y \in X$ with $\mathcal{B} \in Q(x_t, r)$ such that $\mathcal{B}(y) + \mathcal{A}_r^*(y) > 1$. Therefore, $\mathcal{A}_r^*(y) \neq 0$. Let $s = \mathcal{A}_r^*(y)$. Then $y_s \in \mathcal{A}_r^*$ and $s + \mathcal{B}(y) > 1$, so that $\mathcal{B} \in Q(y_s, r)$. Now $y_s \in \mathcal{A}_r^*$ implies there is at least one $x' \in X$ such that $\mathcal{D}(x') + \mathcal{A}(x') - 1 > \mathcal{C}(x')$ for all $\mathcal{I}(\mathcal{C}) \geq r$ and $\mathcal{D} \in Q(y_s, r)$. This is also true for $\mathcal{B}$. So there is at least one $x'' \in X$ such that $\mathcal{B}(x'') + \mathcal{A}(x'') - 1 > \mathcal{C}(x'')$. Since $\mathcal{B}$ is an arbitrary and $\mathcal{B} \in Q(x_t, r)$, then, $\mathcal{A}_r^*(x) > t$. It is a contradiction. Thus $\mathcal{A}_r^* \geq C_\tau(\mathcal{A}_r^*, r)$.

(4) Form (3), we have $(\mathcal{A}_r^*)^* = C_\tau((\mathcal{A}_r^*)^*, r) \leq C_\tau(\mathcal{A}_r^*, r) = \mathcal{A}_r^*$.

(5) $(\Rightarrow)$ Since $\mathcal{A}, \mathcal{B} \leq \mathcal{A} \vee \mathcal{B}$. By (1), we have $\mathcal{A}_r^* \leq (\mathcal{A} \vee \mathcal{B})_r^*$ and $\mathcal{B}_r^* \leq (\mathcal{A} \vee \mathcal{B})_r^*$. Hence $\mathcal{A}_r^* \vee \mathcal{B}_r^* \leq (\mathcal{A} \vee \mathcal{B})_r^*$.

$(\Leftarrow)$ Suppose that $(\mathcal{A}_r^* \vee \mathcal{B}_r^*) \not\leq (\mathcal{A} \vee \mathcal{B})_r^*$, then there exist $x \in X$ and $t \in M$ such that

$$(\mathcal{A}_r^* \vee \mathcal{B}_r^*)(x) < t \leq (\mathcal{A} \vee \mathcal{B})_r^*(x).$$

Since $(\mathcal{A}_r^* \vee \mathcal{B}_r^*)(x) < t$, $\mathcal{A}_r^*(x) < t$ or $\mathcal{B}_r^*(x) < t$. So, there exists $\mathcal{D}_1 \in Q(x_t, r)$ such that for every $y \in X$ and for some $\mathcal{I}(\mathcal{C}_1) \geq r$ we have,

$$\mathcal{D}_1(y) + \mathcal{A}(y) - 1 \leq \mathcal{C}_1(y).$$

Similarly there exists $\mathcal{D}_2 \in Q(x_t, r)$ such that for every $y \in X$ and for some $\mathcal{I}(\mathcal{C}_2) \geq r$ we have,

$$\mathcal{D}_2(y) + \mathcal{B}(y) - 1 \leq \mathcal{C}_2(y).$$

Since $\mathcal{D} = \mathcal{D}_1 \odot \mathcal{D}_2 \in Q(x_t, r)$ and by (I_3) , $\mathcal{I}(\mathcal{C}_1 \vee \mathcal{C}_2) \geq r$. Thus, for every $y \in X$, $\mathcal{D}(y) + (\mathcal{A} \vee \mathcal{B})(y) - 1 \leq (\mathcal{C}_1 \vee \mathcal{C}_2)(y)$. Therefore, $(\mathcal{A} \vee \mathcal{B})_r^*(x) < t$. It is a contradiction. Hence $\mathcal{A}_r^* \vee \mathcal{B}_r^* \geq (\mathcal{A} \vee \mathcal{B})_r^*$.

(6), (7) and (8) are obvious. $\square$

Example 3.5. [19]. Define $\tau, \mathcal{I} : L^X \rightarrow M$, where $L = M = I = [0, 1]$ as follows:

$$\tau(\mathcal{B}) = \begin{cases} 1, & \text{if } \mathcal{B} \in \{\underline{1}, \underline{0}\}, \\ \frac{1}{2}, & \text{if } \mathcal{B} = \underline{0.8}, \\ \frac{1}{2}, & \text{if } \mathcal{B} = \underline{0.7}, \\ 0, & \text{otherwise,} \end{cases} \quad \mathcal{I}(\mathcal{C}) = \begin{cases} 1, & \text{if } \mathcal{C} = \underline{0}, \\ \frac{1}{2}, & \text{if } \mathcal{C} = \underline{0.3}, \\ \frac{2}{3}, & \text{if } \underline{0} < \mathcal{B} < \underline{0.3}, \\ 0, & \text{otherwise.} \end{cases}$$

Then, $\underline{0} = (\underline{0.4}^*)_{\frac{1}{2}}^* \neq \underline{0.4}^*_{\frac{1}{2}} = \underline{0.2}$.

Theorem 3.6. Let $(X, \tau, \mathcal{I})$ be (L, M) -sits, and $\{\mathcal{A}_i : i \in J\} \subset L^X$. Then:

- (1) $(\bigvee (\mathcal{A}_i)_r^* : i \in J) \leq (\bigvee \mathcal{A}_i : i \in J)_r^*$.
- (2) $(\bigwedge \mathcal{A}_i : i \in J)_r^* \leq (\bigwedge (\mathcal{A}_i)_r^* : i \in J)$.

Proof. (1) Since $\mathcal{A}_i \leq \bigvee \mathcal{A}_i$, for each $i \in J$, by Theorem 3.4(1), we have $(\mathcal{A}_i)_r^* \leq (\bigvee \mathcal{A}_i)_r^*$, for each $i \in J$. This implies $(\bigvee (\mathcal{A}_i)_r^* : i \in J) \leq (\bigvee \mathcal{A}_i : i \in J)_r^*$.

(2) Since $\bigwedge \mathcal{A}_i \leq \mathcal{A}_i$, $(\bigwedge \mathcal{A}_i)_r^* \leq (\mathcal{A}_i)_r^*$, for each $i \in J$. Thus, $(\bigwedge \mathcal{A}_i : i \in J)_r^* \leq (\bigwedge (\mathcal{A}_i)_r^* : i \in J)$. $\square$

Remark 3.7. For each $(X, \tau, \mathcal{I})$ and $\mathcal{A} \in L^X$, we can defines

$$Cl^*(\mathcal{A}, r) = \mathcal{A} \vee \mathcal{A}_r^*, \quad int^*(\mathcal{A}, r) = \mathcal{A} \odot [\underline{1} - (\underline{1} - \mathcal{A})_r^*].$$

Clearly, Cl^* is a fuzzy closure operator and $\tau^*(\mathcal{I})$ is the (L, M) – smooth topology generated by Cl^* . i.e.,

$$\tau^*(\mathcal{I})(\mathcal{A}) = \bigvee \{r \mid Cl^*(\underline{1} - \mathcal{A}, r) = \underline{1} - \mathcal{A}\}.$$

Now if, $\mathcal{I} = \mathcal{I}^0$ then $Cl^*(\mathcal{A}, r) = \mathcal{A} \vee \mathcal{A}_r^* = \mathcal{A} \vee C_\tau(\mathcal{A}, r) = C_\tau(\mathcal{A}, r)$, for $\mathcal{A} \in L^X$. So, $\tau^*(\mathcal{I}^0) = \tau$.

Theorem 3.8. Let $(X, \tau, \mathcal{I})$ be (L, M) –sits, $r \in M$ and $\mathcal{A} \in L^X$. Then

- (1) $int^*(\mathcal{A} \vee \mathcal{B}, r) \leq int^*(\mathcal{A}, r) \vee int^*(\mathcal{B}, r)$.
- (2) $int_\tau(\mathcal{A}, r) \leq int^*(\mathcal{A}, r) \leq \mathcal{A} \leq Cl^*(\mathcal{A}, r) \leq C_\tau(\mathcal{A}, r)$.
- (3) $Cl^*(\underline{1} - \mathcal{A}, r) = \underline{1} - int^*(\mathcal{A}, r)$ and $\underline{1} - Cl^*(\mathcal{A}, r) = int^*(\underline{1} - \mathcal{A}, r)$.
- (4) $int^*(\mathcal{A} \odot \mathcal{B}, r) = int^*(\mathcal{A}, r) \odot int^*(\mathcal{B}, r)$.

Proof. (1) and (2) Follows directly from definition Cl^* , int^* and C_τ .

(3) Since

$$\begin{aligned} Cl^*(\underline{1} - \mathcal{A}, r) &= \underline{1} - \mathcal{A} \vee (\underline{1} - \mathcal{A})_r^* = \underline{1} - \mathcal{A} \vee [\underline{1} - (\underline{1} - (\underline{1} - \mathcal{A})_r^*)] \\ &= \underline{1} - [\mathcal{A} \odot (\underline{1} - (\underline{1} - \mathcal{A})_r^*)] = \underline{1} - int^*(\mathcal{A}, r). \end{aligned}$$

(4) From Theorem 3.4 (5), we have

$$\begin{aligned} int^*(\mathcal{A} \odot \mathcal{B}, r) &= (\mathcal{A} \odot \mathcal{B}) \odot [\underline{1} - (\underline{1} - (\mathcal{A} \odot \mathcal{B}))_r^*] \\ &= (\mathcal{A} \odot \mathcal{B}) \odot [\underline{1} - [(\underline{1} - \mathcal{A}) \vee (\underline{1} - \mathcal{B})]_r^*] \\ &= (\mathcal{A} \odot \mathcal{B}) \odot [\underline{1} - [(\underline{1} - \mathcal{A})_r^* \vee (\underline{1} - \mathcal{B})_r^*]] \\ &= (\mathcal{A} \odot [\underline{1} - (\underline{1} - \mathcal{A})_r^*]) \odot (\mathcal{B} \odot [\underline{1} - (\underline{1} - \mathcal{B})_r^*]) \\ &= int^*(\mathcal{A}, r) \odot int^*(\mathcal{B}, r). \end{aligned} \quad \square$$

Theorem 3.9. Let $(X, \tau_1, \mathcal{I})$ and $(X, \tau_2, \mathcal{I})$ be (L, M) –sits's and $\tau_1 \leq \tau_2$. Then

- (1) $\mathcal{A}_r^*(\tau_2, \mathcal{I}) \leq \mathcal{A}_r^*(\tau_1, \mathcal{I})$.
- (2) $\tau_1^*(\mathcal{I}) \leq \tau_2^*(\mathcal{I})$.

Proof. (1) Suppose that $\mathcal{A}_r^*(\tau_2, \mathcal{I}) \not\leq \mathcal{A}_r^*(\tau_1, \mathcal{I})$, then there exist $x \in X$ and $t \in M$ such that

$$\mathcal{A}_r^*(\tau_2, \mathcal{I})(x) \geq t > \mathcal{A}_r^*(\tau_1, \mathcal{I})(x).$$

Since $\mathcal{A}_r^*(\tau_1, \mathcal{I})(x) < t$, there exist $\mathcal{D} \in Q_{\tau_1}(x_t, r)$ with $\mathcal{I}(\mathcal{C}) \geq r$ such that for every $y \in X$, $\mathcal{D}(y) + \mathcal{A}(y) - 1 \leq \mathcal{C}(y)$. Since $\tau_1 \leq \tau_2$, $\mathcal{D} \in Q_{\tau_2}(x_t, r)$. Thus, $\mathcal{A}_r^*(\tau_2, \mathcal{I})(x) < t$. It is a contradiction.

(2) Clearly, $\tau_1^*(\mathcal{I}) \leq \tau_2^*(\mathcal{I})$, as $\mathcal{A}_r^*(\tau_2, \mathcal{I}) \leq \mathcal{A}_r^*(\tau_1, \mathcal{I})$. $\square$

Theorem 3.10. Let $(X, \tau, \mathcal{I}_1)$ and $(X, \tau, \mathcal{I}_2)$ be (L, M) -sits's and $\mathcal{I}_1 \leq \mathcal{I}_2$. Then

- (1) $\mathcal{A}_r^*(\mathcal{I}_1, \tau) \geq \mathcal{A}_r^*(\mathcal{I}_2, \tau)$.
- (2) $\tau_1^*(\mathcal{I}_1) \leq \tau_2^*(\mathcal{I}_2)$.

Proof. Obvious. $\square$

Theorem 3.11. Define the mapping $\beta : \Theta \rightarrow L$ on X by

$$\beta(\mathcal{A}) = \bigvee \{ \tau(\mathcal{B}) \odot \mathcal{I}(\mathcal{C}) \mid \mathcal{A} = \mathcal{B} \odot (\underline{1} - \mathcal{C}) \}.$$

The β is base for the (L, M) -smooth topology τ^* .

Proof. (1) Since $\mathcal{I}(\underline{0}) = 1$, $\beta(\underline{1}) = 1$.

(2) Suppose there exist $\mathcal{A}_1, \mathcal{A}_2 \in \Theta$ such that $\beta(\mathcal{A}_1 \odot \mathcal{A}_2) \not\geq \beta(\mathcal{A}_1) \odot \beta(\mathcal{A}_2)$. There exists $t \in M$ such that

$$\beta(\mathcal{A}_1 \odot \mathcal{A}_2) < t \leq \beta(\mathcal{A}_1) \odot \beta(\mathcal{A}_2).$$

Since $\beta(\mathcal{A}_1) \geq t$ and $\beta(\mathcal{A}_2) \geq t$, there exist $\mathcal{B}_1, \mathcal{B}_2, \mathcal{C}_1, \mathcal{C}_2 \in \Theta$ with $\mathcal{A}_1 = \mathcal{B}_1 \odot (\underline{1} - \mathcal{C}_1)$ and $\mathcal{A}_2 = \mathcal{B}_2 \odot (\underline{1} - \mathcal{C}_2)$ such that $\beta(\mathcal{A}_1) \geq \tau(\mathcal{B}_1) \odot \mathcal{I}(\mathcal{C}_1) \geq t$ and $\beta(\mathcal{A}_2) \geq \tau(\mathcal{B}_2) \odot \mathcal{I}(\mathcal{C}_2) \geq t$. Therefore,

$$\begin{aligned} \mathcal{A}_1 \odot \mathcal{A}_2 &= (\mathcal{B}_1 \odot (\underline{1} - \mathcal{C}_1)) \odot (\mathcal{B}_2 \odot (\underline{1} - \mathcal{C}_2)) \\ &= (\mathcal{B}_1 \odot \mathcal{B}_2) \odot ((\underline{1} - \mathcal{C}_1) \odot (\underline{1} - \mathcal{C}_2)) \\ &= (\mathcal{B}_1 \odot \mathcal{B}_2) \odot (\underline{1} - (\mathcal{C}_1 \vee \mathcal{C}_2)) \end{aligned}$$

Hence,

$$\begin{aligned} \beta(\mathcal{A}_1 \odot \mathcal{A}_2) &\geq \tau(\mathcal{B}_1 \odot \mathcal{B}_2) \odot \mathcal{I}(\mathcal{C}_1 \vee \mathcal{C}_2) \\ &\geq \tau(\mathcal{B}_1) \odot \tau(\mathcal{B}_2) \odot \mathcal{I}(\mathcal{C}_1) \odot \mathcal{I}(\mathcal{C}_2) \\ &= (\tau(\mathcal{B}_1) \odot \mathcal{I}(\mathcal{C}_1)) \odot (\tau(\mathcal{B}_2) \odot \mathcal{I}(\mathcal{C}_2)) \geq t. \end{aligned}$$

It is a contradiction. Thus, $\beta(\mathcal{A}_1 \odot \mathcal{A}_2) \geq \beta(\mathcal{A}_1) \odot \beta(\mathcal{A}_2)$. $\square$

Theorem 3.12. Let (X, τ) be (L, M) -smooth topological space and $\mathcal{I}_1, \mathcal{I}_2$ be two (L, M) -smooth ideals on X . Then, for any $\mathcal{A} \in L^X$ and $r \in M$,

- (1) $\mathcal{A}_r^*(\mathcal{I}_1 \odot \mathcal{I}_2, \tau) = \mathcal{A}_r^*(\mathcal{I}_1, \tau) \vee \mathcal{A}_r^*(\mathcal{I}_2, \tau)$.

$$(2) \mathcal{A}_r^*(\mathcal{I}_1 \vee \mathcal{I}_2, \tau) = \mathcal{A}_r^*(\mathcal{I}_1, \tau^*(\mathcal{I}_2,)) \odot \mathcal{A}^*(\mathcal{I}_2, \tau^*(\mathcal{I}_1)).$$

Proof. (1) Suppose that $\mathcal{A}_r^*(\mathcal{I}_1 \odot \mathcal{I}_2, \tau) \not\leq \mathcal{A}_r^*(\mathcal{I}_1, \tau) \vee \mathcal{A}_r^*(\mathcal{I}_2, \tau)$, there exist $x \in X$ and $t \in M$ such that

$$\mathcal{A}_r^*(\mathcal{I}_1 \odot \mathcal{I}_2, \tau)(x) \geq t > \mathcal{A}_r^*(\mathcal{I}_1, \tau) \vee \mathcal{A}_r^*(\mathcal{I}_2, \tau)(x).$$

Since $\mathcal{A}_r^*(\mathcal{I}_1, \tau) \vee \mathcal{A}_r^*(\mathcal{I}_2, \tau)(x) < t$, $\mathcal{A}_r^*(\mathcal{I}_1, \tau)(x) < t$ and $\mathcal{A}_r^*(\mathcal{I}_2, \tau)(x) < t$. Now, $\mathcal{A}_r^*(\mathcal{I}_1, \tau)(x) < t$, implies there exist $\mathcal{D}_1 \in Q_\tau(x_t, r)$ and for some $\mathcal{I}_1(\mathcal{C}_1) \geq r$ such that for every $y \in X$, $\mathcal{D}_1(y) + \mathcal{A}(y) - 1 \leq \mathcal{C}_1(y)$. **Again**, $\mathcal{A}_r^*(\mathcal{I}_2, \tau)(x) < t$, implies there exists $\mathcal{D}_2 \in Q_\tau(x_t, r)$ and for some $\mathcal{I}_2(\mathcal{C}_2) \geq r$ such that for each $y \in X$, $\mathcal{D}_2(y) + \mathcal{A}(y) - 1 \leq \mathcal{C}_2(y)$. Therefore, $(\mathcal{D}_1 \odot \mathcal{D}_2)(y) + \mathcal{A}(y) - 1 \leq (\mathcal{C}_1 \odot \mathcal{C}_2)(y)$, for every $y \in X$. Since $(\mathcal{D}_1 \odot \mathcal{D}_2) \in Q_\tau(x_t, r)$ and $(\mathcal{I}_1 \odot \mathcal{I}_2)(\mathcal{C}_1 \odot \mathcal{C}_2) \geq r$, $\mathcal{A}_r^*(\mathcal{I}_1 \odot \mathcal{I}_2, \tau) < t$, and this is a contradiction. So that $\mathcal{A}_r^*(\mathcal{I}_1 \odot \mathcal{I}_2, \tau) \leq \mathcal{A}_r^*(\mathcal{I}_1, \tau) \vee \mathcal{A}_r^*(\mathcal{I}_2, \tau)$.

Also, $\mathcal{I}_1, \mathcal{I}_2 \geq \mathcal{I}_1 \odot \mathcal{I}_2$, so by Theorem 3.4(2), $\mathcal{A}_r^*(\mathcal{I}_1 \odot \mathcal{I}_2) \geq \mathcal{A}_r^*(\mathcal{I}_1) \vee \mathcal{A}_r^*(\mathcal{I}_2)$. Then, $\mathcal{A}_r^*(\mathcal{I}_1 \odot \mathcal{I}_2, \tau) = \mathcal{A}_r^*(\mathcal{I}_1, \tau) \vee \mathcal{A}_r^*(\mathcal{I}_2, \tau)$.

(2) Suppose that $\mathcal{A}_r^*(\mathcal{I}_1 \vee \mathcal{I}_2, \tau) \not\leq \mathcal{A}_r^*(\mathcal{I}_1, \tau^*(\mathcal{I}_2,)) \odot \mathcal{A}^*(\mathcal{I}_2, \tau^*(\mathcal{I}_1))$, then there exist $x \in X$ and $t \in M$ such that

$$\mathcal{A}_r^*(\mathcal{I}_1 \vee \mathcal{I}_2, \tau)(x) < t \leq \mathcal{A}_r^*(\mathcal{I}_1, \tau^*(\mathcal{I}_2,))(x) \odot \mathcal{A}^*(\mathcal{I}_2, \tau^*(\mathcal{I}_1))(x)$$

Since $\mathcal{A}_r^*(\mathcal{I}_1 \vee \mathcal{I}_2, \tau)(x) < t$, there exists $\mathcal{D} \in Q_\tau(x_t, r)$, such that for every $y \in X$, and for some $(\mathcal{I}_1 \vee \mathcal{I}_2)(\mathcal{C}) \geq r$, $\mathcal{D}(y) + \mathcal{A}(y) - 1 \leq \mathcal{C}(y)$. Therefore, by heredity of L –smooth ideals and $\tau \leq \tau^*$ we can find $\mathcal{D}_1 \in Q_{\tau^*(\mathcal{I}_1)}(x_t, r)$ or $\mathcal{D}_2 \in Q_{\tau^*(\mathcal{I}_2)}(x_t, r)$ such that for every $y \in X$, $\mathcal{D}_1(y) + \mathcal{A}(y) - 1 \leq \mathcal{C}_1(y)$, or $\mathcal{D}_2(y) + \mathcal{A}(y) - 1 \leq \mathcal{C}_2(y)$, for some $\mathcal{I}_2(\mathcal{C}_2) \geq r$ or $\mathcal{I}_1(\mathcal{C}_1) \geq r$. This implies $\mathcal{A}^*(\mathcal{I}_2, \tau^*(\mathcal{I}_1))(x) < t$ or $\mathcal{A}_r^*(\mathcal{I}_1, \tau^*(\mathcal{I}_2))(x) < t$. It is a contradiction. Thus, $\mathcal{A}_r^*(\mathcal{I}_1 \vee \mathcal{I}_2, \tau) \geq \mathcal{A}_r^*(\mathcal{I}_1, \tau^*(\mathcal{I}_2,)) \odot \mathcal{A}^*(\mathcal{I}_2, \tau^*(\mathcal{I}_1))$.

Conversely, similarly $\mathcal{A}_r^*(\mathcal{I}_1 \vee \mathcal{I}_2, \tau) \leq \mathcal{A}_r^*(\mathcal{I}_1, \tau^*(\mathcal{I}_2,)) \odot \mathcal{A}^*(\mathcal{I}_2, \tau^*(\mathcal{I}_1))$.

An important result follows from the above theorem that $\tau^*(\mathcal{I})$ and $[\tau^*(\mathcal{I})]^*(\mathcal{I})$ (in short τ^{**}) are equal for any (L, M) –smooth ideal on X . $\square$

Corollary 3.13. Let $(X, \tau, \mathcal{I})$ be (L, M) –sits. For any $\mathcal{A} \in L^X$ and $r \in M$. Then $\mathcal{A}_r^*(\mathcal{I}) = \mathcal{A}_r^*(\mathcal{I}, \tau^*)$ and $\tau^*(\mathcal{I}) = \tau^{**}$.

Proof. Putting $\mathcal{I}_1 = \mathcal{I}_2$ in Theorem 3.12(2), we have required result. $\square$

Corollary 3.14. Let (X, τ) be (L, M) –smooth topological space and $\mathcal{I}_1, \mathcal{I}_2$ be two (L, M) –smooth ideals on X . Then,

$$(1) \tau^*(\mathcal{I}_1 \vee \mathcal{I}_2) = [\tau^*(\mathcal{I}_2)]^*(\mathcal{I}_1) = [\tau^*(\mathcal{I}_1)]^*(\mathcal{I}_2).$$

$$(2) \tau^*(\mathcal{I}_1 \odot \mathcal{I}_2) = \tau^*(\mathcal{I}_1) \odot \tau^*(\mathcal{I}_2).$$

Proof. proof is easily by using Theorem 3.12(2). $\square$

Definition 3.15. For (L, M) –smooth topological space (X, τ) with (L, M) –smooth ideal $\mathcal{I}$, τ is said to be smooth open compatible with $\mathcal{I}$, denoted by $\tau \sim \mathcal{I}$, if for each $\mathcal{A} \in L^X$, $x_t \in \mathcal{A}$, and $\mathcal{C} \in L^X$ with $\mathcal{I}(\mathcal{C}) \geq r$ there exists $\mathcal{D} \in Q_\tau(x_t, r)$ such that $\mathcal{D}(y) + \mathcal{A}(y) - 1 \leq \mathcal{C}(y)$ holds for every $y \in X$, then $\mathcal{I}(\mathcal{A}) \geq r$.

Definition 3.16. Let $\{\mathcal{B}_j : j \in J\}$ be a indexed family of smooth set of X such that $\mathcal{B}_j q \mathcal{A}$ for each $j \in J$ where $\mathcal{A} \in L^X$. Then $\{\mathcal{B}_j : j \in J\}$ is said to be a r –smooth quasi-cover of $\mathcal{A}$ iff $\mathcal{A}(y) + \bigvee_{j \in J} (\mathcal{B}_j)(y) \geq 1$ for every $y \in X$.

Further, let (X, τ) be (L, M) –smooth topological space, for each $\tau(\mathcal{B}_j) \geq r$. Then this r –smooth quasi-cover will be called smooth quasi open-cover of $\mathcal{A}$.

Theorem 3.17. Let (X, τ) be (L, M) –smooth topological space with (L, M) –smooth ideal $\mathcal{I}$ on X . Then the following conditions are equivalent.

- (1) $\tau \sim \mathcal{I}$.
- (2) If for every $\mathcal{A} \in L^X$ has r –smooth quasi open-cover of $\{\mathcal{B}_j : j \in J\}$ such that for each j , $\mathcal{A}(y) + \mathcal{B}_j(y) - 1 \leq \mathcal{C}(y)$, for every $y \in X$ and for some $\mathcal{I}(\mathcal{C}) \geq r$, then $\mathcal{I}(\mathcal{A}) \geq r$.
- (3) For every $\mathcal{A} \in L^X$, $\mathcal{A} \odot \mathcal{A}_r^* = \underline{0}$ implies $\mathcal{I}(\mathcal{A}) \geq r$.
- (4) For every $\mathcal{A} \in L^X$, $\mathcal{I}(\tilde{\mathcal{A}}) \geq r$, where $\tilde{\mathcal{A}} = \bigvee x_t$ such that $x_t \in \mathcal{A}$ but $x_t \notin \mathcal{A}_r^*$.
- (5) For every $\tau^*(\underline{1} - \mathcal{A}) \geq r$, $\mathcal{I}(\tilde{\mathcal{A}}) \geq r$.
- (6) For every $\mathcal{A} \in L^X$, if $\mathcal{A}$ contains no $\mathcal{B} \neq \underline{0}$ with $\mathcal{B} \leq \mathcal{B}_r^*$, then $\mathcal{I}(\mathcal{A}) \geq r$.

Proof. We prove most of the equivalent conditions which ultimately prove all the equivalence.

(1) $\Rightarrow$ (2): Let $\{\mathcal{B}_j : j \in J\}$ be a smooth quasi open-cover of $\mathcal{A} \in L^X$ such that for $j \in J$, $\mathcal{A}(y) + \mathcal{B}_j(y) - 1 \leq \mathcal{C}(y)$, for every $y \in X$ and for some $\mathcal{I}(\mathcal{C}) \geq r$. Therefore, as $\{\mathcal{B}_j : j \in J\}$ is r –smooth quasi open-cover of $\mathcal{A}$, for each $x_t \in \mathcal{A}$, there exist at least one $\mathcal{B}_{j_0}$ such that $x_t q \mathcal{B}_{j_0}$ and for every $y \in X$, $\mathcal{A}(y) + \mathcal{B}_{j_0}(y) - 1 \leq \mathcal{C}(y)$, for some $\mathcal{I}(\mathcal{C}) \geq r$. Obviously, $\mathcal{B}_{j_0} \in Q_\tau(x_t, r)$. By (1), we have $\mathcal{I}(\mathcal{A}) \geq r$.

(2) $\Rightarrow$ (1): Clear from the fact that a collection of $\{\mathcal{B}_j : j \in J\}$ which contains at least one $\mathcal{B}_{j_0} \in Q_\tau(x_t, r)$, of each fuzzy point of $\mathcal{A}$, constitutes a smooth quasi-open cover of $\mathcal{A}$.

(1) $\Rightarrow$ (3): Let $\mathcal{A} \odot \mathcal{A}_r^* = \underline{0}$, for every $y \in X$, $x_t \in \mathcal{A}$ implies $x_t \notin \mathcal{A}_r^*$. Then there exists $\mathcal{D} \in Q(x_t, r)$ and $\mathcal{I}(\mathcal{C}) \geq r$ such that for every $y \in X$, $\mathcal{D}(y) + \mathcal{A}(y) - 1 \leq \mathcal{C}(y)$. Since $\mathcal{D} \in Q_\tau(x_t, r)$. By (1), we have $\mathcal{I}(\mathcal{A}) \geq r$.

(3) $\Rightarrow$ (1): For every $x_t \in \mathcal{A}$, there exist an $\mathcal{D} \in Q_\tau(x_t, r)$ such that for every $y \in X$, $\mathcal{D}(y) + \mathcal{A}(y) - 1 \leq \mathcal{C}(y)$, for some $\mathcal{I}(\mathcal{C}) \geq r$. This implies $x_t \notin \mathcal{A}_r^*$. Now, there are two cases: either $\mathcal{A}_r^* = \underline{0}$ or $\mathcal{A}_r^* \neq \underline{0}$ but $t > \mathcal{A}_r^* \neq \underline{0}$. Let, if possible, $x_t \in \mathcal{A}$ such that $t > \mathcal{A}_r^* \neq \underline{0}$. Let $t' = \mathcal{A}_r^*(x)$. Then $x_{t'} \in \mathcal{A}_r^*(x)$. Also, $x_{t'} \in \mathcal{A}$. Thus, for every $\mathcal{V} \in Q_\tau(x_t, r)$ for every $\mathcal{I}(\mathcal{C}) \geq r$, there is at least one $y \in X$ such that $\mathcal{V}(y) + \mathcal{A}(y) - 1 > \mathcal{C}(y)$. Since $x_{t'} \in \mathcal{A}$, this contradicts the assumption for every fuzzy point of $\mathcal{A}$. So, $\mathcal{A}_r^* = \underline{0}$. That means, $x_t \in \mathcal{A}$, implies $x_t \notin \mathcal{A}_r^*$. Now this is true for every $\mathcal{A} \in L^X$. So, for every $\mathcal{A} \in L^X$, $\mathcal{A} \odot \mathcal{A}_r^* = \underline{0}$. Hence, by (3), we have $\mathcal{I}(\mathcal{A}) \geq r$, which implies $\tau \sim \mathcal{I}$.

(3) $\Rightarrow$ (4): Let $x_t \in \tilde{\mathcal{A}}$. Then, $x_t \in \mathcal{A}$ but $x_t \notin \mathcal{A}_r^*$. So, there exist an $\mathcal{D} \in Q_\tau(x_t, r)$ such that for every $y \in X$, $\mathcal{D}(y) + \mathcal{A}(y) - 1 \leq \mathcal{C}(y)$, for some $\mathcal{I}(\mathcal{C}) \geq r$. Since $\tilde{\mathcal{A}} \leq \mathcal{A}$, So for every $y \in X$, $\mathcal{D}(y) + \tilde{\mathcal{A}}(y) - 1 \leq \mathcal{C}(y)$ for some $\mathcal{I}(\mathcal{C}) \geq r$. Therefore, $x_t \notin \tilde{\mathcal{A}}_r^*$ implies that $\tilde{\mathcal{A}}_r^* = \underline{0}$ or $\tilde{\mathcal{A}}_r^* \neq \underline{0}$ but $t > \tilde{\mathcal{A}}_r^*$. Let $x_{t'} \in P_t(X)$ such that $t' \leq \tilde{\mathcal{A}}_r^*(x) < t$, i.e., $x_{t'} \in \tilde{\mathcal{A}}_r^*$. Then, for each $\mathcal{V} \in Q_\tau(x_{t'}, r)$ and for each $\mathcal{I}(\mathcal{C}) \geq r$ there is at least one $y \in X$ such that $\mathcal{V}(y) + \tilde{\mathcal{A}}(y) - 1 > \mathcal{C}(y)$. Since $\tilde{\mathcal{A}} \leq \mathcal{A}$, then so for each $\mathcal{V} \in Q_\tau(x_{t'}, r)$ and for each $\mathcal{I}(\mathcal{C}) \geq r$ there is at least one $y \in X$ such that $\mathcal{V}(y) + \mathcal{A}(y) - 1 > \mathcal{C}$. This implies $x_{t'} \in \mathcal{A}_r^*$. But as $t' < t$, $x_t \in \tilde{\mathcal{A}}$ implies $x_{t'} \in \tilde{\mathcal{A}}$, and therefore, $x_{t'} \notin \mathcal{A}_r^*$. This is a contradiction. Hence, $\mathcal{A}_r^* = \underline{0}$, so that $x_t \in \tilde{\mathcal{A}}$ implies $x_t \notin \tilde{\mathcal{A}}_r^*$ with $\tilde{\mathcal{A}}_r^* = \underline{0}$. Thus, $\tilde{\mathcal{A}} \odot \tilde{\mathcal{A}}_r^* = \underline{0}$, for every $\mathcal{A} \in I^X$. Hence, by (3), $\mathcal{I}(\tilde{\mathcal{A}}) \geq r$.

(4) $\Rightarrow$ (5): Straightforward.

(4) $\Rightarrow$ (6): Let $\mathcal{A} \in L^X$, $\mathcal{A}$ contains $\mathcal{B} \neq \underline{0}$ with $\mathcal{B} \leq \mathcal{B}_r^*$. Then, for every $\mathcal{A} \in L^X$, $\mathcal{A} = \tilde{\mathcal{A}} \vee (\mathcal{A} \odot \mathcal{A}_r^*)$. Therefore, $\mathcal{A}_r^* = (\tilde{\mathcal{A}} \vee (\mathcal{A} \odot \mathcal{A}_r^*))_r^* = \tilde{\mathcal{A}}_r^* \vee (\mathcal{A} \odot \mathcal{A}_r^*)_r^*$. by Theorem 3.4(5).

Now by (4), we have $\mathcal{I}(\tilde{\mathcal{A}}) \geq r$, then $\tilde{\mathcal{A}}_r^* = \underline{0}$. Hence, $(\mathcal{A} \odot \mathcal{A}_r^*)_r^* = \mathcal{A}_r^*$ but $\mathcal{A} \odot \mathcal{A}_r^* \leq \mathcal{A}_r^*$, then $\mathcal{A} \odot \mathcal{A}_r^* \leq (\mathcal{A} \odot \mathcal{A}_r^*)_r^*$. This contradicts the hypothesis about every fuzzy $\mathcal{A} \in L^X$, if $\underline{0} \neq \mathcal{B} \leq \mathcal{A}$ with $\mathcal{B} \leq \mathcal{B}_r^*$. Therefore, $\mathcal{A} \odot \mathcal{A}_r^* = \underline{0}$, so that $\mathcal{A} = \tilde{\mathcal{A}}$ by (4), we have $\mathcal{I}(\mathcal{A}) \geq r$.

(6) $\Rightarrow$ (4): Since, for every $\mathcal{A} \in L^X$, $\mathcal{A} \odot \mathcal{A}_r^* = \underline{0}$ Therefore, by (6), as $\mathcal{A}$ contains no non-empty fuzzy subset $\mathcal{B}$ with $\mathcal{B} \leq \mathcal{B}_r^*$, $\mathcal{I}(\mathcal{A}) \geq r$.

(5) $\Rightarrow$ (1): For every $\mathcal{A} \in L^X$, $x_t \in \mathcal{A}$, there exist an $\mathcal{D} \in Q_\tau(x_t, r)$ such that $\mathcal{D}(y) + \mathcal{A}(y) - 1 \leq \mathcal{C}(y)$ holds for every $y \in X$ and for some $\mathcal{I}(\mathcal{C}) \geq r$. This

implies $x_t \notin \mathcal{A}_r^*$. Let $\mathcal{B} = \mathcal{A} \vee \mathcal{A}_r^*$. Then, $\mathcal{B}_r^* = (\mathcal{A} \vee \mathcal{A}_r^*)_r^* = \mathcal{A}_r^* \vee (\mathcal{A}_r^*)_r^* = \mathcal{A}_r^*$ by Theorem 3.4(4). So, $Cl^*(\mathcal{B}, r) = \mathcal{B} \vee \mathcal{B}_r^* = \mathcal{B}$. That means $\tau^*(\underline{1} - \mathcal{B}) \geq r$. Therefore, by (5), we have $\mathcal{I}(\mathcal{B}) \geq r$.

Again, For any $x_t \in P_t(X)$, $x_t \notin \tilde{\mathcal{B}}_r^*$ implies $x_t \in \mathcal{B}$ but $x_t \notin \mathcal{B}_r^* = \mathcal{A}_r^*$. So, as $\mathcal{B} = \mathcal{A} \vee \mathcal{A}_r^*$, $x_t \in \mathcal{A}$. Now, by hypothesis about $\mathcal{A}$, we have for every $x_t \in \mathcal{A}_r^*$. So, $\tilde{\mathcal{B}} = \mathcal{A}$. Hence, $\mathcal{I}(\mathcal{A}) \geq r$, i.e., $\tau \sim \mathcal{I}$. $\square$

Theorem 3.18. Let (X, τ) be (L, M) –smooth topological space with (L, M) –smooth ideal $\mathcal{I}$, on X . Then the following are equivalent and implied by $\tau \sim \mathcal{I}$.

- (1) For every $\mathcal{A} \in L^X$, $\mathcal{A} \odot \mathcal{A}_r^* = \underline{0}$ implies $\mathcal{A}_r^* = \underline{0}$.
- (2) For every $\mathcal{A} \in L^X$, $\tilde{\mathcal{A}}_r^* = \underline{0}$.
- (3) For every $\mathcal{A} \in L^X$, $\mathcal{A} \odot \mathcal{A}_r^* = \mathcal{A}_r^*$.

Proof. Clear from Theorem 3.17. $\square$

An important consequence of Theorem 3.18 is the following corollary.

Corollary 3.19. Let $\tau \sim \mathcal{I}$. Then $\beta(\tau, \mathcal{I})$, a base for τ^* , and also $\beta(\tau, \mathcal{I}) = \tau^*$.

Proof. Clear.

4 Conclusion

A smoothing by using fuzzy logic gives rather good results. In particular smoothing of ideals, r –smooth open local map. (L, M) –smooth ideal topological spaces seem to be a good examples and corresponding concepts trace back to the (classic) fuzzy ideal structures. We feeling that we can be build a new mathematical object ((L, M) –smooth structures) where $L = (L, \leq, \vee, \odot, ', 0, 1)$ denotes a completely distributive lattice with order-reversing involution $'$ which has the least and greatest elements, say 0 and 1, respectively. This approach could be a subject of further studies.

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