

Generalization of Rodrigues' Formula in Weyl Space

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Abstract

In this paper, a generalization of Rodrigues's Formula in Weyl space is expressed.

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1 Introduction

A manifold with a conformal metric g_{ij} and a symmetric connection ∇_k satisfying the compatibility condition

$$\nabla_k g_{ij} - 2T_k g_{ij} = 0 \quad (1)$$

is called a Weyl space that will be denoted by $W_n(g_{ij}, T_k)$. The vector field T_k is named the complementary vector field.

The prolonged derivative and prolonged covariant derivative of A are, respectively defined by ([1, 5])

$$\dot{\partial}_k A = \partial_k A - pT_k A \quad (2)$$

and

$$\dot{\nabla}_k A = \nabla_k A - pT_k A \quad (3)$$

where A is a satellite of g_{ij} with weight $\{p\}$.

2 Generalization of Rodrigues' Formula

Let us take a point on the line v . Let us denote its coordinates by $x^a + tv^a$ where $v^a = t^i x_i^a + rn^a$ and $g_{ab}v^a v^b = 1$. Let $x^a + tv^a$ be describe a curve which is tangent to the line v . Then the prolonged covariant derivative of $x^a + tv^a$ in the direction of v^k , which is tangent vector field of a curve C at a point on W_2 , satisfies the following condition:

$$v_1^a + v_1^k (\dot{\nabla}_k t) v^a + t v_1^k \dot{\nabla}_k v^a = m v^a \quad (a = 1, 2, 3; k = 1, 2) \quad (4)$$

where m is to be determined.

Multiplying (4) by $g_{ab}v^b$, we get

$$g_{ab}v_1^a v^b + v_1^k \dot{\nabla}_k t + t g_{ab}(v_1^k \dot{\nabla}_k v^a) v^b = m \quad (b = 1, 2, 3) \quad (5)$$

or

$$g_{ab}v_1^a v^b + v_1^k \dot{\nabla}_k t = m \quad (6)$$

where $g_{ab}v^a v^b = 1$ and $(v_1^k \dot{\nabla}_k v^a) v^b = 0$.

Using (6) in (4), we have

$$v_1^a + v_1^k (\dot{\nabla}_k t) v^a + t v_1^k \dot{\nabla}_k v^a = (g_{cb}v_1^c v^b + v_1^k \dot{\nabla}_k t) v^a \quad (c = 1, 2, 3) \quad (7)$$

or

$$v_1^k (x_k^a + t \dot{\nabla}_k v^a - g_{cb}x_k^c v^b v^a) = 0 \quad (8)$$

where $v_1^c = v_1^k x_k^c$ [7].

We know that:

1)

$$g_{ab}v^a x_i^b = g_{ab}(t^j x_j^a + rn^a) x_i^b = g_{ij}t^j = t_i \quad (i, j = 1, 2). \quad (9)$$

2)

$$\begin{aligned} g_{ab}(\dot{\nabla}_k v^a)(\dot{\nabla}_l v^b) &= g_{ab}(D_k^i x_i^a + D_k n^a)(D_l^j x_j^b + D_l n^b) \\ &= g_{ij}D_k^i D_l^j + D_k D_l \\ &= D_k^i D_l^j (g_{ij} + h_i h_l) \\ &= G_{kl} \quad (l = 1, 2) \end{aligned} \quad (10)$$

where $D_k = -h_i D_k^i$ [7].

3)

$$\begin{aligned} g_{ab}(\dot{\nabla}_k v^a) x_j^b &= g_{ab}(D_k^i x_i^a + D_k n^a) x_j^b \\ &= g_{ij}D_k^i \\ &= D_{jk} \quad [4]. \end{aligned} \quad (11)$$

Multiplying (8) by $g_{ad}(\dot{\nabla}_l v^d)$ ($d = 1, 2, 3$) and using (9), (10) and (11), we obtain

$$v_1^k(D_{kl} + tG_{kl}) = 0. \quad (12)$$

Eliminating the parameter t in (12), we have

$$\begin{aligned} & (D_{11}G_{12} - D_{12}G_{11})v_1^1v_1^1 + \\ & + (D_{11}G_{22} - D_{22}G_{11})v_1^1v_1^2 + \\ & + (D_{21}G_{22} - D_{22}G_{21})v_1^2v_1^2 = 0 \end{aligned} \quad (13)$$

or implicitly

$$\varepsilon^{jl}D_{ij}G_{kl}v_1^iv_1^k = 0 \quad (14)$$

or

$$e^{jl}D_{ij}G_{kl}v_1^iv_1^k = 0 \quad (15)$$

where $\varepsilon^{jl} = e^{jl}/\sqrt{g}$, $e^{12} = 1$, $e^{21} = -1$, and $e^{11} = e^{22} = 0$.

The curves satisfying the equation (15) on W_2 constitute the net of curves. This net is named as the intersector net.

Using (10) and (11), we get from (15)

$$e^{jl}g_{hi}D_j^hD_k^mD_l^s(g_{ms} + h_mh_s)v_1^iv_1^k = 0 \quad (m, s = 1, 2) \quad (16)$$

or

$$(De^{hs}g_{hi}g_{ms}D_k^m - De^{hs}g_{hi}D_kg_{sq}h^q)v_1^iv_1^k = 0 \quad (q = 1, 2) \quad (17)$$

where $e^{jl}D_s^hD_l^s = De^{hs}$, $D = |D_j^h|$ and $-D_k = D_k^mh_m$ or

$$(Dge_{im}D_k^m - Dge_{iq}D_kh^q)v_1^iv_1^k = 0 \quad (18)$$

where $e^{hs}g_{hi}g_{ms} = ge_{im}$ [7], $g = |g_{ij}|$.

Taking m instead of q in the second term of (18), we get

$$e_{im}(D_k^m - D_kh^m)v_1^iv_1^k = 0 \quad (19)$$

where D and g are nonvanishing.

(19) is equivalent to (15).

On the other hand, the prolonged covariant derivative of Y : $v^a = t^ix_i^a + rn^a$ in the direction of v_1^k is

$$v_1^k\dot{\nabla}_kv^a = v_1^k(\dot{\nabla}_kt^i - r\omega_{ki}g^{il})x_i^a + v_1^k(t^i\omega_{ik} + \dot{\nabla}_kr)n^a \quad (20)$$

or

$$v_1^k \dot{\nabla}_k v^a = v_1^k (\dot{\nabla}_k t^i - r \omega_{kl} g^{il} - t^j \omega_{jk} \frac{t^i}{r} - \frac{1}{r} t^i \dot{\nabla}_k r) x_i^a + v_1^k (\frac{t^i}{r} \omega_{ik} + \frac{1}{r} \dot{\nabla}_k r) v^a \quad (21)$$

where $n^a = \frac{1}{r}(v^a - t^i x_i^a)$.

Let us denote the tangential component of (21) by $-DY$:

$$DY = v_1^k (-\dot{\nabla}_k t^i + r \omega_{kl} g^{il} + t^j \omega_{jk} \frac{t^i}{r} + \frac{1}{r} t^i \dot{\nabla}_k r) x_i^a. \quad (22)$$

DY is tangent to C if and only if the following equation is satisfied for some scalar q :

$$v_1^k (\dot{\nabla}_k t^i - r \omega_{kl} g^{il} - t^j \omega_{jk} \frac{t^i}{r} - \frac{1}{r} t^i \dot{\nabla}_k r) x_i^a = q x_k^a v_1^k. \quad (23)$$

Multiplying (23) by $g_{ab} x_m^b$, we have

$$v_1^k (\dot{\nabla}_k t_m - r \omega_{km} - t^j \omega_{jk} \frac{t_m}{r} - \frac{1}{r} t_m \dot{\nabla}_k r) = q g_{km} v_1^k \quad (24)$$

where $g_{ab} x_i^a x_m^b = g_{im}$, $g_{im} g^{il} = \delta_m^l$ and $g_{im} t^i = t_m$.

Multiplying (24) by g^{ms} , we get

$$g^{ms} v_1^k (\dot{\nabla}_k t_m - r \omega_{km} - t^j \omega_{jk} \frac{t_m}{r} - \frac{1}{r} t_m \dot{\nabla}_k r) = q v_1^s \quad (25)$$

where $g_{km} g^{ms} = \delta_k^s$.

Multiplying (25) by $\varepsilon_{sh} v_1^h$, we obtain

$$\varepsilon_{sh} g^{ms} v_1^k (\dot{\nabla}_k t_m - r \omega_{km} - t^j \omega_{jk} \frac{t_m}{r} - \frac{1}{r} t_m \dot{\nabla}_k r) v_1^h = 0 \quad (26)$$

where $\varepsilon_{sh} v_1^s v_1^h = 0$ (the directions coincide), or

$$\varepsilon_{sh} v_1^k (\dot{\nabla}_k t^s - r \omega_{km} g^{ms} - t^j \omega_{jk} \frac{t^s}{r} - \frac{1}{r} t^s \dot{\nabla}_k r) v_1^h = 0 \quad (27)$$

or

$$\varepsilon_{sh} v_1^k (D_k^s - h^s D_k) v_1^h = 0 \quad (28)$$

where $D_k^s = \dot{\nabla}_k t^s - r \omega_{km} g^{ms}$, $D_k = t^j \omega_{jk} + \dot{\nabla}_k r$ [2] and $h^s = t^s/r$.

(26) is equivalent to (28). From here, we have seen that C is a curve of the intersector net.

Let κ denote the magnitude (signed magnitude) of DY in the direction of v which is the tangent vector field of the curve C of the intersector net. Then, we have

$$\kappa v_1^i = v_1^k (-\dot{\nabla}_k t^i + r \omega_{kl} g^{il} + t^j \omega_{jk} \frac{t^i}{r} + \frac{1}{r} t^i \dot{\nabla}_k r). \quad (29)$$

Using (29) in (22), we have

$$DY + \kappa v^i_1 x^a_i = DY + \kappa v^a_1 = 0 \quad (30)$$

(30) is a generalization of Rodrigues's formula.

Remark: Generalization of Rodrigues' formula in E^3 was obtained by Pan [6].

If $Z : v^a = n^a$, then $v^k_1 \dot{\nabla}_k v^a = v^k_1 \dot{\nabla}_k n^a$. Using (20) and (23), we have

$DZ = v^k_1 \dot{\nabla}_k n^a = -v^k_1 \omega_{kl} g^{il} x^a_i$ and $-v^k_1 \omega_{kl} g^{il} x^a_i = q v^i_1 x^a_i$. From here, we get $v^k_1 (w_{kl} - \kappa_{11} g_{kl}) = 0$ where $-\kappa_{11} = q$, $\kappa_{11} = \omega_{ij} v^i_1 v^j_1$ and κ_{11} is the normal curvature of W_2 . This is the equation of lines of curvature [3] i.e. The net of lines of curvature is the intersector net of the normal congruence. Let κ denote the magnitude of DZ along a curve of the intersector net of Z . Since $v^k_1 \omega_{kl} g^{il} = \kappa v^i_1$, we have $DZ = \kappa v^a_1$ or $DZ + \kappa v^a_1 = 0$ or $v^k_1 \dot{\nabla}_k n^a + \kappa v^a_1 = 0$. This is a special case of (30).

Theorem 2.1 *If the tangential component of the prolonged covariant derivative of a congruence along a curve C is tangent to the curve C then C is a curve of the intersector net of the congruence.*

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