

Improved Homotopy Perturbation Method

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Abstract

In this paper a new treatment for homotopy perturbation method (**HPM**) is introduced. The new treatment is called improved homotopy perturbation method (**IHPM**) which improves the results obtained from **HPM**. At first, the principle of the **HPM** is described. Then **IHPM** is proposed, which yields the analytic approximate solution. To illustrate the methods some experiments are provided. In some experiments different approximate solutions are obtained by using **HPM**. By applying **IHPM**, we obtain exact solutions. The results show the efficiency, accuracy, and superiority of the new method. Furthermore, the convergency of the method is also considered.

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1 Introduction

Recently a great deal of interest has been focused on the application of **HPM** for the solution of many different problems. The **HPM** has been applied with great success to obtain the approximate solution of large variety of linear and nonlinear problems in ordinary differential equations (**ODEs**),

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partial differential equations (**PDEs**), and integral equations [1-15]. In some **PDEs** different approximate solutions can be obtained by using **HPM**. In this paper we improve **HPM** to obtain exact solutions for these **PDEs**.

The present study consists of the following sections. In section 2, we introduce **HPM** and **IHPM**. In section 3, to illustrate the method, some experiments are provided. In section 4, the convergency of the method is considered and finally in section 5 a short conclusion is given.

2 HPM and its improvement (IHPM)

He presented a homotopy perturbation technique based on the introduction of a homotopy and an artificial parameter for the solution of algebraic equations and **ODEs** [1]. To describe **HPM**, we consider the following nonlinear differential equation:

$$A(v) - f(r) = 0, r \in \Omega, \quad (1)$$

with the boundary conditions:

$$B(v, \frac{\partial v}{\partial n}) = 0, r \in \Gamma, \quad (2)$$

where A is a differential operator, B is a boundary operator, $f(r)$ is a known analytic function and Γ is the boundary of the domain Ω . The operator A can be divided into two parts L and N , where L is a linear operator and N is a nonlinear operator. Therefore, equation (1) can be rewritten as:

$$L(v) + N(v) - f(r) = 0. \quad (3)$$

Now we construct a homotopy $v(r, p) : \Omega \times [0, 1] \longrightarrow R$ which satisfies:

$$\begin{aligned} H(v, p) &= (1 - p)[L(v) - L(u_0)] + p[A(v) - f(r)] = \\ L(v) - (1 - p)L(u_0) + p[N(v) - f(r)] &= 0, p \in [0, 1], r \in \Omega, \end{aligned} \quad (4)$$

where $p \in [0, 1]$ is an embedding parameter, u_0 is an initial approximation which satisfies the boundary conditions. Therefore, obviously we have:

$$H(v, 0) = L(v) - L(u_0) = 0,$$

$$H(v, 1) = A(v) - f(r) = 0.$$

Changing the process of p from zero to unity is just that of $v(r, p)$ from $u_0(r)$ to $v(r)$. We assume that the solution of equation (4) can be written as a

power series in p ; i.e. $v = v_0 + pv_1 + p^2v_2 + p^3v_3 + \dots$. By setting $p = 1$, the approximation solution of (1) is obtained.

In some **PDEs** we can select the operator L in different ways. According to the definition of $H(v, p)$, the approximate solution that is obtained from $H(v, p)$ depends on operator L and initial conditions. Therefore, in some problems different approximate solutions are obtained. To show the subject consider the following problem

$$u_t + [f(u)]_x = [g(u)]_{xx} + h(u), \quad (5)$$

with the following conditions:

$$u(x, 0) = \varphi(x), 0 \leq x \leq 1, \quad (6)$$

$$u(0, t) = p(t), 0 \leq t \leq 1, \quad (7)$$

$$u(1, t) = q(t), 0 \leq t \leq T, \quad (8)$$

where $0 \leq u(x, t) \leq C$; C and T are given constant numbers. Besides, $[f(u)]_x$, $[g(u)]_{xx}$, and $h(u)$ represent nonlinear advection, nonlinear diffusion, and nonlinear reaction terms respectively. This problem is widely used to describe many important phenomena and dynamics, mechanics, chemistry, biology, and ect. By defining the $L = L_t$, we can seek the solution of problem based on **HPM** as:

$$u(\widehat{x}, t) = \sum_{n=0}^{\infty} u_n(\widehat{x}, t). \quad (9)$$

Likewise, by defining the $L = L_{xx}$, we can seek another approximate solution of the problem based on **HPM** as:

$$u(\widetilde{x}, t) = \sum_{n=0}^{\infty} u_n(\widetilde{x}, t). \quad (10)$$

Let us define $u_n(\widehat{x}, t) = \sum_{n=0}^{n-1} u_n(\widehat{x}, t)$ and $u_n(\widetilde{x}, t) = \sum_{n=0}^{n-1} u_n(\widetilde{x}, t)$. By combining these two approximate solutions, the better approximation solution can be obtained. For this purpose, let:

$$u_n(x, t) = \alpha_n \widehat{u}_n + \beta_n \widetilde{u}_n. \quad (11)$$

Some authors used $\alpha_n = \beta_n = \frac{1}{2}$ in their works to combine two approximate solutions that are obtained by Adomian decomposition method [16]. The optimum values of α_n and β_n are discussed in [17] for the approximate solutions that are obtained by Adomian decomposition method. The best values for α_n

and β_n in (11) can be obtained for each n . For instance, consider problem (5)-(8). The residual function for this problem is defined as:

$$J_n = \|u_n(0, t) - p(t)\|^2 + \|u_n(1, t) - q(t)\|^2 + \|u_n(x, 0) - \varphi(x)\|^2. \quad (12)$$

The values of α_n and β_n are chosen such that this residual is minimized. The initial approximation for this problem (i.e. (5)-(8)), can be obtained by using $u_0 = (1 - x)p(t) + xq(t)$.

3 Numerical experiments

To show the efficiency of the methods that is described in section 2 (i.e. **HPM** and **IHPM**), we test with the following experiments. The convergency of the method is also considered.

Experiment 1. Consider linear **PDE** $u_{tt} + u_{xx} + u_{xt} = 2(x + t)$, with the following conditions: $u(x, 0) = ax$, $u_t(x, 0) = x^2$, $u(0, t) = 0$, and $u_x(0, t) = a$. First we set $L = L_{tt} = \frac{\partial^2}{\partial t^2}$. According to the **HPM** that is defined in section 2, we have:

$$\begin{aligned} H(v, p) &= \frac{\partial^2}{\partial t^2}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots) - (1 - p)\frac{\partial^2 u_0}{\partial t^2} \\ &+ p\left[\frac{\partial^2}{\partial x^2}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots) + \frac{\partial^2}{\partial x \partial t}(v_0 + pv_1 + p^2v_2 \right. \\ &\quad \left. + p^3v_3 + p^4v_4 + p^5v_5 + \dots) - 2(x + t)\right] = 0. \end{aligned}$$

The initial approximation (i.e. u_0) can be obtained from initial and boundary conditions ($u_0 = tu_t(x, 0) + xu_x(0, t)$). By equating the coefficients of p to zero, we obtain:

$$\begin{aligned} \text{coefficient of } p^0 &: \frac{\partial^2 v_0}{\partial t^2} - \frac{\partial^2 u_0}{\partial t^2} = 0, \Rightarrow v_0 = u_0 = ax + x^2t, \\ \text{coefficient of } p^1 &: \frac{\partial^2 v_1}{\partial t^2} + \frac{\partial^2 u_0}{\partial t^2} + \frac{\partial^2 v_0}{\partial x^2} + \frac{\partial^2 v_0}{\partial x \partial t} - 2(x + t) = 0, \Rightarrow v_1 = 0, \\ \text{coefficient of } p^2 &: \frac{\partial^2 v_2}{\partial t^2} + \frac{\partial^2 v_1}{\partial x^2} + \frac{\partial^2 v_1}{\partial x \partial t} = 0, \Rightarrow v_2 = 0, \\ &\vdots \\ \text{coefficient of } p^n &: \frac{\partial^2 v_n}{\partial t^2} + \frac{\partial^2 v_{n-1}}{\partial x^2} + \frac{\partial^2 v_{n-1}}{\partial x \partial t} = 0, \Rightarrow v_n = 0. \end{aligned}$$

Therefore, we obtain $u(x, t) = ax + x^2t$, which is the exact solution of the problem.

Now we set $L = L_{xx} = \frac{\partial^2}{\partial x^2}$. According to the **HPM** that is defined in section 2, we have:

$$H(v, p) = \frac{\partial^2}{\partial x^2}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots) - (1 - p)\frac{\partial^2 u_0}{\partial x^2}$$

$$+p\left[\frac{\partial^2}{\partial t^2}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots) + \frac{\partial^2}{\partial x\partial t}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots) - 2(x + t)\right] = 0.$$

By equating the coefficients of p to zero, we obtain:

coefficient of $p^0 : \frac{\partial^2 v_0}{\partial x^2} - \frac{\partial^2 u_0}{\partial x^2} = 0, \Rightarrow v_0 = u_0 = ax + x^2t,$

coefficient of $p^1 : \frac{\partial^2 v_1}{\partial x^2} + \frac{\partial^2 v_0}{\partial x^2} + \frac{\partial^2 v_0}{\partial t^2} + \frac{\partial^2 v_0}{\partial x\partial t} - 2(x + t) = 0, \Rightarrow v_1 = 0,$

coefficient of $p^2 : \frac{\partial^2 v_2}{\partial x^2} + \frac{\partial^2 v_1}{\partial t^2} + \frac{\partial^2 v_1}{\partial x\partial t} = 0, \Rightarrow v_2 = 0,$

⋮

coefficient of $p^n : \frac{\partial^2 v_n}{\partial x^2} + \frac{\partial^2 v_{n-1}}{\partial t^2} + \frac{\partial^2 v_{n-1}}{\partial x\partial t} = 0, \Rightarrow v_n = 0.$

Therefore, we obtain $u(x, t) = ax + x^2t$, which is the exact solution of the problem. Since finite numbers of v_i are not zero, the convergency of the solution is trivial and **HPM** is equivalent to **IHPM**. Each number in $[0, 1]$, can be the optimum value for α_n . In this case we set $\beta_n = 1 - \alpha_n$.

In this experiment, by using $u_0 = x^2t$ (initial condition), and $L = L_{tt} = \frac{\partial^2}{\partial t^2}$, we obtain:

$$v_0 = x^2t,$$

$$v_1 = 0,$$

$$v_2 = 0,$$

$$v_3 = 0,$$

⋮

$$v_n = 0.$$

Therefore, we obtain $u(\widehat{x}, t) = x^2t$. In the same way, by using $u_0 = ax$ (initial condition), and $L = L_{xx} = \frac{\partial^2}{\partial x^2}$, we obtain:

$$v_0 = ax,$$

$$v_1 = \frac{1}{3}x^3 + x^2t,$$

$$v_2 = -\frac{1}{3}x^3,$$

$$v_3 = 0,$$

⋮

$$v_n = 0.$$

Therefore, we obtain $u(\widetilde{x}, t) = ax + x^2t$. The optimum values of α_n and β_n are $\alpha_n = 0$ and $\beta_n = 1$. So, the exact solution is obtained. This experiment shows that **IHPM** with these initial conditions (i.e. $u_0 = x^2t$ and $u_0 = ax$) can obtain exact solution but **HPM** with $u_0 = x^2t$ can not obtain the exact

solution.

Experiment 2. Consider linear **PDE** $u_t = u_{xx} - u_x$, with the following conditions: $u(x, 0) = e^x - x$, $u(0, t) = 1 + t$, and $u_x(1, t) = e - 1$. First we set $L = L_t = \frac{\partial}{\partial t}$. According to the **HPM**, we have:

$$\begin{aligned} H(v, p) = & \frac{\partial}{\partial t}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots) - (1-p)\frac{\partial u_0}{\partial t} \\ & + p\left[\frac{\partial}{\partial x}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots) - \frac{\partial^2}{\partial x^2}(v_0 + pv_1 \right. \\ & \left. + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots)\right] = 0. \end{aligned}$$

By equating the coefficients of p to zero, we obtain:

$$\begin{aligned} \text{coefficient of } p^0 : & \frac{\partial v_0}{\partial t} - \frac{\partial u_0}{\partial t} = 0, \Rightarrow v_0 = u_0 = e^x - x, \\ \text{coefficient of } p^1 : & \frac{\partial v_1}{\partial t} + \frac{\partial u_0}{\partial t} + \frac{\partial v_0}{\partial x} - \frac{\partial^2 v_0}{\partial x^2} = 0, \Rightarrow \frac{\partial v_1}{\partial t} = 1, \Rightarrow v_1 = t, \\ \text{coefficient of } p^2 : & \frac{\partial v_2}{\partial t} + \frac{\partial v_1}{\partial x} - \frac{\partial^2 v_1}{\partial x^2} = 0, \Rightarrow \frac{\partial v_2}{\partial t} = 0, \Rightarrow v_2 = 0, \\ \text{coefficient of } p^3 : & \frac{\partial v_3}{\partial t} + \frac{\partial v_2}{\partial x} - \frac{\partial^2 v_2}{\partial x^2} = 0, \Rightarrow \frac{\partial v_3}{\partial t} = 0, \Rightarrow v_3 = 0, \\ & \vdots \\ \text{coefficient of } p^n : & \frac{\partial v_n}{\partial t} + \frac{\partial v_{n-1}}{\partial x} - \frac{\partial^2 v_{n-1}}{\partial x^2} = 0, \Rightarrow \frac{\partial v_n}{\partial t} = 0, \Rightarrow v_n = 0. \end{aligned}$$

Therefore, we obtain $u(x, t) = e^x - x + t$, which is the exact solution of the problem.

Now we set $L = L_x = \frac{\partial}{\partial x}$. According to the **HPM**, we have:

$$\begin{aligned} H(v, p) = & \frac{\partial}{\partial x}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots) - (1-p)\frac{\partial u_0}{\partial x} \\ & + p\left[\frac{\partial}{\partial t}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots) - \frac{\partial^2}{\partial x^2}(v_0 + pv_1 \right. \\ & \left. + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots)\right] = 0. \end{aligned}$$

By equating the coefficients of p to zero, we obtain:

$$\begin{aligned} \text{coefficient of } p^0 : & \frac{\partial v_0}{\partial x} - \frac{\partial u_0}{\partial x} = 0, \Rightarrow v_0 = u_0 = 1 + t, \\ \text{coefficient of } p^1 : & \frac{\partial v_1}{\partial x} + \frac{\partial u_0}{\partial x} + \frac{\partial v_0}{\partial t} - \frac{\partial^2 v_0}{\partial x^2} = 0, \Rightarrow \frac{\partial v_1}{\partial x} = -1 \Rightarrow v_1 = -x, \\ \text{coefficient of } p^2 : & \frac{\partial v_2}{\partial x} + \frac{\partial v_1}{\partial t} - \frac{\partial^2 v_1}{\partial x^2} = 0, \Rightarrow v_2 = 0, \\ \text{coefficient of } p^3 : & \frac{\partial v_3}{\partial x} + \frac{\partial v_2}{\partial t} - \frac{\partial^2 v_2}{\partial x^2} = 0, \Rightarrow v_3 = 0, \\ & \vdots \\ \text{coefficient of } p^n : & \frac{\partial v_n}{\partial x} + \frac{\partial v_{n-1}}{\partial t} - \frac{\partial^2 v_{n-1}}{\partial x^2} = 0, \Rightarrow v_n = 0. \end{aligned}$$

Therefore, we obtain $u(x, t) = 1 + t - x$. Consequently **HPM** by using $u_0 = 1 + t$ can not obtain the exact solution of the problem. The optimum values of α_n and β_n for this problem, according to the (12), are $\alpha_n = 1$ and

$\beta_n = 0$. So, the exact solution is obtained.

Experiment 3. Consider linear **PDE** (*Klein-Gordon equation*) $u_{tt} - u_{xx} + u = 0$, with the following conditions: $u(x, 0) = x + e^{-x}$, $u_t(x, 0) = 0$. First we set $L = L_{tt} = \frac{\partial^2}{\partial x^2}$. According to the **HPM**, we have:

$$H(v, p) = \frac{\partial^2}{\partial t^2}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots) - (1 - p)\frac{\partial^2 u_0}{\partial t^2} - p\left[\frac{\partial^2}{\partial x^2}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots) - (v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots)\right] = 0.$$

By equating the coefficients of p to zero, we obtain:

$$\begin{aligned} \text{coefficient of } p^0 &: \frac{\partial^2 v_0}{\partial t^2} - \frac{\partial^2 u_0}{\partial t^2} = 0, \Rightarrow v_0 = u_0 = e^{-x} + x, \\ \text{coefficient of } p^1 &: \frac{\partial^2 v_1}{\partial t^2} + \frac{\partial^2 u_0}{\partial t^2} - \frac{\partial^2 v_0}{\partial x^2} + v_0 = 0, \Rightarrow v_1 = -\frac{t^2}{2!}x, \\ \text{coefficient of } p^2 &: \frac{\partial^2 v_2}{\partial t^2} - \frac{\partial^2 v_1}{\partial x^2} + v_1 = 0, \Rightarrow v_2 = \frac{t^4}{4!}x, \\ &\vdots \\ \text{coefficient of } p^n &: \frac{\partial^2 v_n}{\partial t^2} - \frac{\partial^2 v_{n-1}}{\partial x^2} + v_{n-1} = 0, \Rightarrow v_n = \frac{(-1)^n t^{2n}}{(2n)!}x. \end{aligned}$$

Therefore, by using Maclaurin’s formula, we obtain $\widehat{u(x, t)} = e^{-x} + x(1 - \frac{t^2}{2!} + \frac{t^4}{4!} - + \dots + \frac{(-1)^n t^{2n}}{(2n)!} + \dots) = e^{-x} + x \cos(t)$, which is the exact solution of the problem. In this experiment, there is a unique way to choose L .

Experiment 4. Consider nonlinear **PDE** $u_{tt} + u_{xx} + u_x^2 = 2x + t^4$, with the following conditions: $u(x, 0) = 0$, $u_t(x, 0) = a$, $u(0, t) = at$, and $u_x(0, t) = t^2$. First, we set $L = L_{tt} = \frac{\partial^2}{\partial t^2}$. According to the **HPM**, we have:

$$H(v, p) = \frac{\partial^2}{\partial t^2}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots) - (1 - p)\frac{\partial^2 u_0}{\partial t^2} + p\left[\frac{\partial^2}{\partial x^2}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots) + \left(\frac{\partial}{\partial x}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots)\right)^2 - 2x - t^4\right] = 0.$$

The initial approximation can be obtained from initial and boundary conditions (i.e. $u_0 = tu_t(x, 0) + xu_x(0, t) = at + xt^2$). By equating the coefficients of p to zero, we obtain:

$$\begin{aligned} \text{coefficient of } p^0 &: \frac{\partial^2 v_0}{\partial t^2} - \frac{\partial^2 u_0}{\partial t^2} = 0, \Rightarrow v_0 = u_0 = at + xt^2, \\ \text{coefficient of } p^1 &: \frac{\partial^2 v_1}{\partial t^2} + 2x + t^4 - 2x - t^4 = 0, \Rightarrow v_1 = 0, \\ \text{coefficient of } p^2 &: \frac{\partial^2 v_2}{\partial t^2} + \frac{\partial^2 v_1}{\partial x^2} + \left(\frac{\partial}{\partial x} 2v_0v_1\right)^2 = 0, \Rightarrow v_2 = 0, \\ &\vdots \end{aligned}$$

Therefore, we obtain $\widehat{u(x, t)} = at + xt^2$, which is the exact solution of the problem.

Now we set $L = L_{xx} = \frac{\partial^2}{\partial x^2}$. According to the **HPM**, we have:

$$H(v, p) = \frac{\partial^2}{\partial x^2}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots) - (1-p)\frac{\partial^2 u_0}{\partial x^2} \\ + p\left[\frac{\partial^2}{\partial t^2}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots) + \left(\frac{\partial}{\partial x}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots)\right)^2 - 2x - t^4\right] = 0.$$

By equating the coefficients of p to zero, we obtain:

$$\text{coefficient of } p^0 : \frac{\partial^2 v_0}{\partial x^2} - \frac{\partial^2 u_0}{\partial x^2} = 0, \Rightarrow v_0 = u_0 = at + xt^2,$$

$$\text{coefficient of } p^1 : \frac{\partial^2 v_1}{\partial x^2} + \frac{\partial^2 u_0}{\partial x^2} + \frac{\partial^2 v_0}{\partial t^2} + \left(\frac{\partial v_0}{\partial x}\right)^2 - 2x - t^4 = 0, \Rightarrow v_1 = 0,$$

$$\text{coefficient of } p^2 : \frac{\partial^2 v_2}{\partial x^2} + \frac{\partial^2 v_1}{\partial x^2} + \left(\frac{\partial}{\partial x} 2v_0v_1\right)^2 = 0, \Rightarrow v_2 = 0,$$

⋮

Therefore, we obtain $\widetilde{u(x, t)} = at + xt^2$, which is the exact solution of the problem. Since finite numbers of v_i are not zero, the convergency of the solution is trivial and **HPM** is equivalent to **IHPM** in this case. Each number in $[0, 1]$, can be the optimum value of α_n . In this case, we set $\beta_n = 1 - \alpha_n$.

In this experiment, by using $u_0 = at$, $L = L_{tt} = \frac{\partial^2}{\partial t^2}$, and **HPM**, we obtain:

$$v_0 = at,$$

$$v_1 = xt^2 + \frac{1}{30}t^6,$$

$$v_2 = 0,$$

$$v_3 = -\frac{1}{30}t^6,$$

$$v_4 = 0,$$

⋮

$$v_n = 0.$$

Therefore, we obtain $\widehat{u(x, t)} = at + xt^2$. In the same way, by using $u_0 = xt^2$, and **HPM**, we obtain:

$$v_0 = xt^2,$$

$$v_1 = 0,$$

$$v_2 = 0,$$

⋮

$$v_n = 0.$$

Therefore, we obtain $\widetilde{u(x, t)} = xt^2$. The optimum values of α_n and β_n are $\alpha_n = 1$ and $\beta_n = 0$. So, the exact solution of the problem is obtained. By

using $L = L_{tt}$, and $u_0 = xt^2$ **HPM** can not obtain exact solution but **IHPM** can obtain the exact solution.

Experiment 5. Consider nonlinear **PDE** (*Burger equation*) $u_t = u_{xx} + uu_x$, with the following conditions: $u(x, 0) = 1 - x$, $u(0, t) = \frac{1}{1+t}$, $u(1, t) = 0$. First we set $L = L_t = \frac{\partial}{\partial t}$. According to the **HPM**, we have:

$$\begin{aligned}
 H(v, p) &= \frac{\partial}{\partial t}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots) - (1 - p)\frac{\partial u_0}{\partial t} \\
 &+ p\left[-\frac{\partial^2}{\partial x^2}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots) - (v_0 + pv_1 + p^2v_2 \right. \\
 &\left. + p^3v_3 + p^4v_4 + p^5v_5 + \dots)\left(\frac{\partial}{\partial x}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots)\right)\right] = 0.
 \end{aligned}$$

By equating the coefficients of p to zero, we obtain:

$$\begin{aligned}
 \text{coefficient of } p^0 &: \frac{\partial v_0}{\partial t} - \frac{\partial u_0}{\partial t} = 0, \Rightarrow v_0 = u_0 = 1 - x, \\
 \text{coefficient of } p^1 &: \frac{\partial v_1}{\partial t} + \frac{\partial u_0}{\partial x} - \frac{\partial^2 v_0}{\partial x^2} - v_0 \frac{\partial v_0}{\partial x} = 0, \Rightarrow v_1 = -t(1 - x), \\
 \text{coefficient of } p^2 &: \frac{\partial v_2}{\partial t} - \frac{\partial^2 v_1}{\partial x^2} - v_0 \frac{\partial v_1}{\partial x} - v_1 \frac{\partial v_0}{\partial x} = 0, \Rightarrow v_2 = t^2(1 - x), \\
 \text{coefficient of } p^3 &: \frac{\partial v_3}{\partial t} - \frac{\partial^2 v_2}{\partial x^2} - v_0 \frac{\partial v_2}{\partial x} - v_1 \frac{\partial v_1}{\partial x} - v_2 \frac{\partial v_0}{\partial x} = 0, \Rightarrow v_3 = -t^3(1 - x), \\
 &\vdots
 \end{aligned}$$

Therefore, we obtain $\widehat{u(x, t)} = (1 - t + t^2 - t^3 + \dots)(1 - x) = \frac{1-x}{1+t}$, which is the exact solution of the problem.

Now, we set $L = L_{xx} = \frac{\partial^2}{\partial x^2}$. According to the **HPM**, we have:

$$\begin{aligned}
 H(v, p) &= \frac{\partial^2}{\partial x^2}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots) - (1 - p)\frac{\partial^2 u_0}{\partial x^2} \\
 &+ p\left[-\frac{\partial}{\partial t}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots) + (v_0 + pv_1 + p^2v_2 + p^3v_3 \right. \\
 &\left. + p^4v_4 + p^5v_5 + \dots)\left(\frac{\partial}{\partial x}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots)\right)\right] = 0.
 \end{aligned}$$

By equating the coefficients of p to zero, we obtain:

$$\begin{aligned}
 \text{coefficient of } p^0 &: \frac{\partial^2 v_0}{\partial x^2} - \frac{\partial^2 u_0}{\partial x^2} = 0, \Rightarrow v_0 = u_0 = \frac{1-x}{1+t}, \\
 \text{coefficient of } p^1 &: \frac{\partial^2 v_1}{\partial x^2} + \frac{\partial^2 u_0}{\partial x^2} - \frac{\partial v_0}{\partial t} + v_0 \frac{\partial v_0}{\partial x} = 0, \Rightarrow v_1 = 0, \\
 \text{coefficient of } p^2 &: \frac{\partial^2 v_2}{\partial x^2} - \frac{\partial v_1}{\partial t} + v_0 \frac{\partial v_1}{\partial x} + v_1 \frac{\partial v_0}{\partial x} = 0, \Rightarrow v_2 = 0, \\
 &\vdots
 \end{aligned}$$

Therefore, we obtain $\widetilde{u(x, t)} = \frac{1-x}{1+t}$, which is the exact solution of the problem. Since finite numbers of v_i are not zero, the convergency of the solution is trivial and **HPM** is equivalent to **IHPM**. Each number in $[0, 1]$, can be the optimum value of α_n . In this case, we set $\beta_n = 1 - \alpha_n$.

Experiment 6. Consider nonlinear **PDE** $u_t = uu_{xx} + u_x^2 + u$, with the following conditions: $u(x, 0) = \sqrt{x}$, $u(0, t) = 0$, $u(1, t) = e^t$. First we set $L = L_t = \frac{\partial}{\partial t}$. According to the **HPM**, we have:

$$H(v, p) = \frac{\partial}{\partial t}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots) - (1 - p)\frac{\partial u_0}{\partial t} - p[(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots)(\frac{\partial^2}{\partial x^2}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots)) + (\frac{\partial}{\partial x}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots))^2 + (v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots)] = 0.$$

By equating the coefficients of p to zero, we obtain:

$$\text{coefficient of } p^0 : \frac{\partial v_0}{\partial t} - \frac{\partial u_0}{\partial t} = 0, \Rightarrow v_0 = u_0 = \sqrt{x},$$

$$\text{coefficient of } p^1 : \frac{\partial v_1}{\partial t} + \frac{\partial u_0}{\partial t} - v_0 \frac{\partial^2 v_0}{\partial x^2} - (\frac{\partial v_0}{\partial x})^2 + v_0 = 0, \Rightarrow v_1 = t\sqrt{x},$$

$$\text{coefficient of } p^2 : \frac{\partial v_2}{\partial t} - [v_0 \frac{\partial^2 v_1}{\partial x^2} + v_1 \frac{\partial^2 v_0}{\partial x^2} + 2\frac{\partial v_0}{\partial x} \frac{\partial v_1}{\partial x} + v_1] = 0, \Rightarrow v_2 = \frac{t^2}{2}\sqrt{x},$$

\vdots

Therefore, by using Maclaurin's formula, we obtain $u(\widehat{x}, t) = \sqrt{x}(1 + t + \frac{t^2}{2} + \dots) = \sqrt{x}e^t$, which is the exact solution of the problem. In this experiment, there is a unique way to choose L .

Experiment 7. Consider nonlinear **PDE** $u_t + u^2u_x = 0$, with the following condition: $u(x, 0) = 3x$. We set $L = L_t = \frac{\partial}{\partial t}$. According to the **HPM**, we have:

$$H(v, p) = \frac{\partial}{\partial t}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots) - (1 - p)\frac{\partial u_0}{\partial t} + p[(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots)^2(\frac{\partial}{\partial x}(v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + p^5v_5 + \dots))] = 0.$$

By equating the coefficients of p to zero, we obtain:

$$\text{coefficient of } p^0 : \frac{\partial v_0}{\partial t} - \frac{\partial u_0}{\partial t} = 0, \Rightarrow v_0 = u_0 = 3x,$$

$$\text{coefficient of } p^1 : \frac{\partial v_1}{\partial t} + \frac{\partial u_0}{\partial t} + v_0^2 \frac{\partial v_0}{\partial x} = 0, \Rightarrow v_1 = -27x^2t,$$

$$\text{coefficient of } p^2 : \frac{\partial v_2}{\partial t} + v_0^2 \frac{\partial v_1}{\partial x} + 2v_0v_1 \frac{\partial v_0}{\partial x} = 0, \Rightarrow v_2 = 486x^3t^2,$$

$$\text{coefficient of } p^3 : \frac{\partial v_3}{\partial t} + v_0^2 \frac{\partial v_2}{\partial x} + 2v_0v_1 \frac{\partial v_1}{\partial x} + v_1^2 \frac{\partial v_0}{\partial x} + 2v_0v_2 \frac{\partial v_0}{\partial x} = 0, \Rightarrow$$

$$v_3 = -10935x^4t^3,$$

\vdots

Therefore, by using Maclaurin's formula, we obtain:

$$u(\widehat{x}, t) = (3x - 27x^2t + 486x^3t^2 - 10935x^4t^3 + \dots)$$

$$= \begin{cases} 3x, & \text{for } (t = 0), \\ \frac{1}{6t}(\sqrt{1 + 36xt} - 1), & \text{for } (t > 0), \end{cases}$$

which is the exact solution of the problem. In this experiment, there is a unique way to choose L .

4 Convergency of the method

An approximate solution of problem (1) is expressed as:

$$v = \sum_{i=0}^{\infty} v_i. \quad (13)$$

To consider the convergency of this series, we can apply classical test such as the root and the ratio tests [18].

Theorem .1 (Root Test) Given (13), put $\alpha = \limsup_{n \rightarrow \infty} \sqrt[n]{|v_n|}$. Then:

- (a) if $\alpha < 1$, then (13) converges;
- (b) if $\alpha > 1$, then (13) diverges;
- (a) if $\alpha = 1$, the test gives no information.

Proof. See [18].

Theorem .2 (Ratio Test) The series (13),

- (a) converges if $\limsup_{n \rightarrow \infty} \left| \frac{v_{n+1}}{v_n} \right| < 1$,
- (b) diverges if $\left| \frac{v_{n+1}}{v_n} \right| \geq 1$ for all $n \geq n_0$, where n_0 is some fixed integer.

Proof. See [18].

For expressed experiments in section 3, with infinite non-zero v_i , the convergency of the approximate solutions can be obtained easily by ratio or root tests.

5 Conclusions

According to the approximate solutions that we have obtained, we infer that **IHPM** is a powerful tool for solving the linear, and nonlinear equations. Expressed experiments show that **IHPM** is superior to **HPM**. This method is easy to implement and the convergency shows that the method can give good approximate solution for different types of evolution equations.

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