

# On the Basis Property of Eigenfunction of the Frankl Problem with Nonlocal Parity Conditions of the Third Kind

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## Abstract

In the present paper, we obtain the eigenvalues and eigenfunctions of the Frankl problem with a nonlocal parity condition of the third kind. we prove the minimalist, the completeness and Riesz basis of the eigenfunctions corresponding to the eigenvalues of the problem in the space  $L_2(D_+)$ .

## 1. INTRODUCTION

The primary Frankl problem was inquired in [1]. The problem with a nonlocal boundary condition of the second kind was studied in [2]. In the present paper, we assume boundary conditions of the third kind that when  $y$  is limited to zero and also in  $x = 0$  the function values are linearly dependent in the elliptic and Hyperbolic regions. In the proof of principal theorem we investigate the minimalist, the completeness and Riesz basis of a specified system of cosines.

**Definition 1.** System  $\{x_n\}_{n \in N} \subset X$  is called complete in  $X$  if  $\overline{L[\{x_n\}_{n \in N}]} = X$ .

**Definition 2.** System  $\{x_n\}_{n \in N} \subset X$  is called minimal in  $X$  if  $x_k \notin \overline{L[\{x_n\}_{n \neq k}]}$ ,  $\forall k \in N$ .

**Remark.** If the system  $\{x_n\}_{n \in \mathbb{N}}$  is minimal in  $L_p(I)$ , then it is also minimal in  $L_p(J)$  for  $J \supset I$ ; and if it is complete in  $L_p(I)$ , then it is also complete in  $L_p(J)$ ; for  $J \subset I$ .

## 2. THE FRANKL PROBLEM WITH NONLOCAL CONDITION OF THE THIRD KIND

The Frankl problem is to seek a solution for equation

$$u_{xx} + \operatorname{sgn}(y)u_{yy} + \mu^2 \operatorname{sgn}(x+y)u = 0 \quad (1)$$

in  $D_+ \cup D_{-1} \cup D_{-2}$  with the boundary conditions

$$u(1, \theta) = 0, \quad \theta \in [0, \frac{\pi}{2}] \quad (2)$$

$$\frac{\partial u}{\partial x}(0, y) = 0, \quad y \in (-1, 1) \quad (3)$$

$$\frac{\partial u}{\partial y}(x, +0) = \frac{\partial u}{\partial y}(x, -0) \quad (4)$$

$$\kappa u(0, y) = u(0, -y), \quad y \in [0, 1] \quad (5)$$

$$\kappa u(x, +0) = u(x, -0) \quad (6)$$

The function  $u(x, y) \in C^0(D_+ \cup D_{-1} \cup D_{-2}) \cap C^2(D_+) \cap C^2(D_-)$ . which areas  $D_+, D_{-1}$  and  $D_{-2}$  are defined as follows:

$$\begin{aligned} D_+ &= \left\{ (r, \theta) : \quad 0 < r < 1, \quad 0 < \theta < \frac{\pi}{2} \right\} \\ D_{-1} &= \left\{ (x, y) : \quad -y < x < y+1, \quad \frac{-1}{2} < y < 0 \right\} \\ D_{-2} &= \left\{ (x, y) : \quad x-1 < y < -x, \quad 0 < x < \frac{1}{2} \right\} \end{aligned}$$

**Theorem 1.** The eigenvalues and eigenfunctions of problem (1)-(6) show by two series. In the first series, the eigenvalues  $\lambda_{nk} = \mu_{nk}^2$  are found from the equation

$$J_{4n}(\mu_{nk}) = 0$$

such that  $n = 0, 1, 2, \dots, k = 1, 2, \dots$  and the  $J_\alpha(z)$  are the Bessel functions [3, p. 12], and the eigenfunctions are provided by the regulations

$$u_{nk}(r, \theta) = A_{nk} J_{4n}(\mu_{nk} r) \cos 4n\left(\frac{\pi}{2} - \theta\right) \quad \text{in } D_+$$

$$\begin{aligned} u_{nk}(\rho, \psi) &= \kappa A_{nk} J_{4n}(\mu_{nk} \rho) \cosh 4n\psi & \text{in } D_{-1} \\ u_{nk}(R, \varphi) &= \kappa A_{nk} J_{4n}(\mu_{nk} R) \cosh 4n\varphi & \text{in } D_{-2} \end{aligned}$$

that we use of polar coordinate system

$$r^2 = x^2 + y^2 \quad x = r \cos \theta \quad y = r \sin \theta$$

for  $0 \leq \theta \leq \frac{\pi}{2}$  and  $0 \leq r \leq 1$  in  $D_+$ ,

of cartesian coordinate system

$$\rho^2 = x^2 - y^2 \quad x = \rho \cosh \psi \quad y = \rho \sinh \psi$$

for  $-\infty < \psi < 0$  and  $0 < \rho < 1$  in  $D_{-1}$ , and

$$R^2 = y^2 - x^2 \quad x = R \sinh \varphi \quad y = -R \cosh \varphi$$

for  $0 < \varphi < \infty$  and  $0 < R < 1$  in  $D_{-2}$ . In the second series, the eigenvalues  $\tilde{\lambda}_{nk} = \tilde{\mu}_{nk}^2$  are resulted from the equation

$$J_{4(n+\Delta)}(\tilde{\mu}_{nk}) = 0 \quad n = 0, 1, \dots \quad k = 1, 2, \dots$$

and the eigenfunctions are determined by the relations

$$\tilde{u}_{nk}(r, \theta) = \tilde{A}_{nk} J_{\tilde{\alpha}_n}(\tilde{\mu}_{nk} r) \cos \tilde{\alpha}_n \left( \frac{\pi}{2} - \theta \right) \text{ in } D_+$$

$$\tilde{u}_{nk}(\rho, \psi) = \tilde{A}_{nk} J_{\tilde{\alpha}_n}(\tilde{\mu}_{nk} \rho) \left( \kappa \frac{\kappa^2 - 1}{\kappa^2 + 1} \cosh \tilde{\alpha}_n \psi - \frac{2\kappa}{\kappa^2 + 1} \sinh \tilde{\alpha}_n \psi \right) \text{ in } D_{-1}$$

$$\tilde{u}_{nk}(R, \varphi) = \kappa \tilde{A}_{nk} J_{\tilde{\alpha}_n}(\tilde{\mu}_{nk} R) \cosh \tilde{\alpha}_n \varphi \text{ in } D_{-2}$$

where;

$$\tilde{\alpha}_n = 4(n + \Delta) \quad , \quad \Delta = \frac{1}{\pi} \arcsin \frac{\kappa}{\sqrt{1 + \kappa^2}} \quad , \quad \Delta \in \left( \frac{-1}{2}, \frac{1}{2} \right)$$

**Theorem 2.** The system of functions

$$\left\{ \cos 4n \left( \frac{\pi}{2} - \theta \right) \right\}_{n=0}^{\infty} \quad , \quad \left\{ \cos 4(n + \Delta) \left( \frac{\pi}{2} - \theta \right) \right\}_{n=1}^{\infty}$$

is complete and a Riesz basis in the space  $L_2(0, \frac{\pi}{2})$  for  $\Delta \in (\frac{-1}{4}, \frac{1}{2})$ .

for  $\Delta < \frac{-1}{4}$  the system is not complete but is minimal, for  $\Delta > \frac{3}{4}$  is complete but is not minimal, and if  $\Delta = \frac{-1}{4}$  is complete and minimal.

**Proof.** The proof of this theorem we use the convergence function

$$f(\theta) = \sum_{n=0}^{\infty} A_n \cos 4n \left( \frac{\pi}{2} - \theta \right) + \sum_{n=1}^{\infty} B_n \cos 4(n + \Delta) \left( \frac{\pi}{2} - \theta \right)$$

in  $L_2(0, \frac{\pi}{2})$ , Riesz basis the system  $\{\sin(n + \Delta)(\pi - 4\theta)\}_{n=0}^{\infty}$  for  $\Delta \in (\frac{-1}{4}, \frac{3}{4})$  and [3].

**Theorem 3.** The system eigenfunction

$$u_{nk}(r, \theta) = A_{nk} J_{4n}(\mu_{nk} r) \cos 4n(\frac{\pi}{2} - \theta)$$

$$\tilde{u}_{nk}(r, \theta) = \tilde{A}_{nk} J_{\tilde{\alpha}_n}(\tilde{\mu}_{nk} r) \cos \tilde{\alpha}_n(\frac{\pi}{2} - \theta)$$

is complete and basis in the space  $L^2(D_+)$ , therefore

$$\int_{D_+} f(r, \theta) u_{nk}(r, \theta) r d\theta dr = 0,$$

$$\int_{D_+} f(r, \theta) \tilde{u}_{nk}(r, \theta) r d\theta dr = 0$$

and  $f \in L^2(D_+)$  then  $f = 0$  in  $D_+$ .

**Proof.** Using Fobini theorem and Lebesgue's integral for any  $n, k = 1, 2, \dots$  we have

$$\begin{aligned} 0 &= \int_{D_+} f(r, \theta) u_{nk}(r, \theta) r d\theta dr \\ &= \int_0^1 \left( r J_{4n}(\mu_{nk} r) \int_0^{\frac{\pi}{2}} f(r, \theta) \cos(4n)(\frac{\pi}{2} - \theta) d\theta \right) dr \end{aligned}$$

again since  $f \in L^2(D_+)$  so;

$$\int_0^1 \int_0^{\frac{\pi}{2}} r |f(r, \theta)|^2 d\theta dr < \infty$$

Insomuch system  $\{\sqrt{r} J_{4n}(\mu_{nk} r)\}_{k=1}^{\infty}$  in  $L^2(0, 1)$  is orthogonal and complete, it is enough to prove;

$$\sqrt{r} \int_0^{\frac{\pi}{2}} f(r, \theta) \cos(4n)(\frac{\pi}{2} - \theta) d\theta \in L^2(0, 1)$$

Using the Holder inequality

$$\left| \sqrt{r} \int_0^{\frac{\pi}{2}} f(r, \theta) \cos(4n)(\frac{\pi}{2} - \theta) d\theta \right|^2$$

$$\begin{aligned}
& < \left| \sqrt{r} \left\{ \int_0^{\frac{\pi}{2}} f^2(r, \theta) d\theta \right\}^{\frac{1}{2}} \left\{ \int_0^{\frac{\pi}{2}} \cos^2 4n \left( \frac{\pi}{2} - \theta \right) d\theta \right\}^{\frac{1}{2}} \right|^2 \\
& = |r| \left| \left\{ \int_0^{\frac{\pi}{2}} f^2(r, \theta) d\theta \right\}^{\frac{1}{2}} \right|^2 \left| \left\{ \int_0^{\frac{\pi}{2}} \cos^2 4n \theta d\theta \right\}^{\frac{1}{2}} \right|^2 \\
& < r \int_0^{\frac{\pi}{2}} |f^2(r, \theta)| d\theta \int_0^{\frac{\pi}{2}} \frac{1 + \cos 8n\theta}{2} d\theta \\
& < \frac{1}{2} r \int_0^{\frac{\pi}{2}} |f^2(r, \theta)| d\theta \int_0^{\frac{\pi}{2}} d\theta \\
& = \frac{\pi}{4} r \int_0^{\frac{\pi}{2}} |f^2(r, \theta)| d\theta = \frac{\pi}{4} r \int_0^{\frac{\pi}{2}} |f(r, \theta)|^2 d\theta
\end{aligned}$$

with the integration interval  $(0, 1)$ ,

$$\int_0^1 \left| \sqrt{r} \int_0^{\frac{\pi}{2}} f(r, \theta) \cos(4n) \left( \frac{\pi}{2} - \theta \right) d\theta \right|^2 dr < \frac{\pi}{4} \int_0^1 r \int_0^{\frac{\pi}{2}} |f(r, \theta)|^2 d\theta dr$$

Thus

$$\int_0^1 \left| \sqrt{r} \int_0^{\frac{\pi}{2}} f(r, \theta) \cos(4n) \left( \frac{\pi}{2} - \theta \right) d\theta \right|^2 dr \leq \frac{\pi}{4} \int_0^1 r \int_0^{\frac{\pi}{2}} |f(r, \theta)|^2 d\theta dr < \infty$$

This inequality is equivalent to

$$\left\{ \int_0^1 \left| \sqrt{r} \int_0^{\frac{\pi}{2}} f(r, \theta) \cos(4n) \left( \frac{\pi}{2} - \theta \right) d\theta \right|^2 dr \right\}^{\frac{1}{2}} < \infty$$

Also system  $\{\sqrt{r} J_{4n}(\mu_{nk} r)\}$  is orthogonl and complete for  $k = 1, 2, \dots$  in  $L^2(0, 1)$  of relation

$$\int_0^1 \left( \sqrt{r} J_{4n}(\mu_{nk} r) \sqrt{r} \int_0^{\frac{\pi}{2}} f(r, \theta) \cos 4n \left( \frac{\pi}{2} - \theta \right) d\theta \right) dr = 0$$

imply that

$$\sqrt{r} \int_0^{\frac{\pi}{2}} f(r, \theta) \cos 4n(\frac{\pi}{2} - \theta) d\theta = 0$$

According to theorem 2, we conclude that  $f(r, \theta) = 0$  in  $L^2(0, 1)$ . Similarly, if we consider the above calculations for sequence  $\{\cos[4(n + \Delta)](\frac{\pi}{2} - \theta)\}$  for  $n = 1, 2, \dots$  we have;

$$\sqrt{r} \int_0^{\frac{\pi}{2}} f(r, \theta) \cos[4(n + \Delta)](\frac{\pi}{2} - \theta) d\theta = 0$$

Because completeness  $[4(n + \Delta)](2 - \theta)_{n=0}^{\infty}$ ,  $f(r, \theta) = 0$  in  $L^2(0, 1)$ . The proof of the theorem is complete.

**Theorem 3.** The system of eigenfunctions  $u_{nk}$  and  $\tilde{u}_{nk}$  of the problem (1)-(6) is a Riesz basis in the space  $L_2(D_+)$  where,

$$A_{nk}^2 = \left( \int_0^1 J_{4n}^2(\mu_{nk} r) r dr \right)^{-1} \quad \tilde{A}_{nk} = \left( \int_0^1 J_{4(n+\Delta)}^2(\tilde{\mu}_{nk} r) r dr \right)^{-1}$$

**Proof.** Theorem 3 results from Theorem 2 and the completeness and orthogonality of the system  $\{A_{nk} \sqrt{r} J_{4n}(\mu_{nk} r)\}_{k=1}^{\infty}$  for  $n=0$  and  $\{\tilde{A}_{nk} \sqrt{r} J_{4(n+\Delta)}(\tilde{\mu}_{nk} r)\}_{k=1}^{\infty}$  for  $n=1$  in  $L_2(0, 1)$ .

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