

A Coincidence Point Theorem for Four Mappings in Dislocated Metric Spaces

K. P. R. Rao

Department of Applied Mathematics
Acharya Nagarjuna University-Dr.M.R.Appa Row Campus
Nuzvid-521201,Krishna Dt.,A.P., India
kprrao2004@yahoo.com

P. Ranga Swamy

Department of Mathematics
St. Ann's College of Engineering & Technology
Chirala, Prakasam Dt.,A.P., India
puligeti@yahoo.co.in

Abstract

In this paper, we prove a common coincidence point theorem for four mappings in dislocated metric spaces.

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1 Introduction

In 2005 F.M. Zeyada, G.H. Hassan, M.A. Ahmed [3] established various definitions of dislocated quasi-metric space. C.T. Aage, J.N. Salunke [2] and A.Isufati [1] proved fixed point theorems for a single map and a pair of mappings in dislocated metric spaces. In this paper we prove a common coincidence point theorem for four maps in dislocated metric spaces.

Now we give some known definitions in dq-metric spaces.

Definition 1.1 ([3]).*Let X be a nonempty set and let $d : X \times X \longrightarrow [0, \infty)$ be a function satisfying following conditions : (i) $d(x, y) = d(y, x) = 0$ implies $x = y$, (ii) $d(x, y) \leq d(x, z) + d(z, y)$, for all $x, y, z \in X$. Then d is called a dislocated quasi-metric on X .*

If d satisfies $d(x, x) = 0, \forall x \in X$ then the dislocated quasi-metric is called a quasi-metric on X .

If d satisfies $d(x, y) = d(y, x), \forall x, y \in X$ then the dislocated quasi-metric is called a dislocated metric on X .

Definition 1.2 ([3]). A sequence $\{x_n\}$ in dq -metric space (dislocated quasi-metric space) (X, d) is called a Cauchy sequence if for given $\epsilon > 0$, there exists $n_0 \in \mathbb{N}$ such that for all $m, n \geq n_0$ implies $d(x_m, x_n) < \epsilon$ or $d(x_n, x_m) < \epsilon$.

Definition 1.3 ([3]). A sequence $\{x_n\}$ is said to be dislocated quasi-converges to x if $\lim_{n \rightarrow \infty} d(x_n, x) = \lim_{n \rightarrow \infty} d(x, x_n) = 0$. In this case x is called a dq -limit of $\{x_n\}$ and we write $x_n \rightarrow x$.

Lemma 1.4 ([3]). dq -limit in a dq -metric space is unique.

Definition 1.5 ([3]). A dq -metric space (X, d) is called complete if every Cauchy sequence in it is dq -convergent.

Definition 1.6 ([3]). Let (X, d_1) and (Y, d_2) be dq -metric spaces and let $f : X \rightarrow Y$ be a function. Then f is said to be continuous at $x_0 \in X$, if the sequence $\{f(x_n)\}$ is d_2q -convergent to $f(x_0) \in Y$ whenever the sequence $\{x_n\}$ in X is d_1q -convergent to x_0 .

Definition 1.7 ([3]). Let (X, d) be a dq -metric space. A map $T : X \rightarrow X$ is called contraction if there exists $0 \leq \lambda < 1$ such that $d(Tx, Ty) \leq \lambda d(x, y)$ for all $x, y \in X$.

Theorem 1.8 ([3]). Let (X, d) be a dq -metric space and let $T : X \rightarrow X$ be a continuous contraction mapping. Then T has unique fixed point.

2 Main Results

Theorem 2.1 Let (X, d) be a complete dislocated metric space. Let F, G, S and $T : X \rightarrow X$ be continuous mappings satisfying

$$(2.1.1) \quad S(X) \subseteq G(X) \text{ and } T(X) \subseteq F(X),$$

$$(2.1.2) \quad SF = FS \text{ and } TG = GT \text{ and}$$

$$(2.1.3) \quad d(Sx, Ty) \leq \phi(\max\{d(Fx, Gy), d(Fx, Sx), d(Gy, Ty), \frac{d(Fx, Sx)d(Gy, Ty)}{d(Fx, Gy)}\})$$

for all $x, y \in X$, where $\phi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ is monotonically non-decreasing and $\sum_{n=1}^{\infty} \phi^n(t) < \infty$ for all $t > 0$.

Then (i) F and S (or) G and T have coincidence point or

(ii) the pairs (F, S) and (G, T) have a common coincidence point.

Proof. It is clear that $\phi^n(t) \rightarrow 0$ as $n \rightarrow \infty$ and $\phi(t) < t$ for all $t > 0$. Suppose x_0 is an arbitrary point of X and define the sequences $\{x_n\}$ and $\{y_n\}$ in X such that

$$y_{2n} = Sx_{2n} = Gx_{2n+1},$$

$$y_{2n+1} = Tx_{2n+1} = Fx_{2n+2}, n = 0, 1, 2, 3, \dots$$

If $y_{2n} = y_{2n+1}$ for some n , then $Gx_{2n+1} = Tx_{2n+1}$. Hence x_{2n+1} is a coincidence point of G and T . If $y_{2n+1} = y_{2n+2}$ for some n , then $Fx_{2n+2} = Sx_{2n+2}$. Hence x_{2n+2} is a coincidence point of F and S .

Assume that $y_n \neq y_{n+1}$ for all n .

$$d(y_{2n}, y_{2n+1}) = d(Sx_{2n}, Tx_{2n+1})$$

$$\leq \phi \left(\max \left\{ d(y_{2n-1}, y_{2n}), d(y_{2n-1}, y_{2n}), \right. \right.$$

$$\left. \left. d(y_{2n}, y_{2n+1}), \frac{d(y_{2n-1}, y_{2n})d(y_{2n}, y_{2n+1})}{d(y_{2n-1}, y_{2n})} \right\} \right)$$

$$= \phi (\max \{d(y_{2n-1}, y_{2n}), d(y_{2n}, y_{2n+1})\})$$

If $\max\{d(y_{2n-1}, y_{2n}), d(y_{2n}, y_{2n+1})\} = d(y_{2n}, y_{2n+1})$, then $d(y_{2n}, y_{2n+1}) \leq \phi(d(y_{2n}, y_{2n+1})) < d(y_{2n}, y_{2n+1})$. It is a contradiction. Hence $d(y_{2n}, y_{2n+1}) \leq \phi(d(y_{2n-1}, y_{2n})) \dots (1)$

$$d(y_{2n-1}, y_{2n}) = d(Sx_{2n}, Tx_{2n-1})$$

$$\leq \phi \left(\max \left\{ d(y_{2n-1}, y_{2n-2}), d(y_{2n-1}, y_{2n}), \right. \right.$$

$$\left. \left. d(y_{2n-2}, y_{2n-1}), \frac{d(y_{2n-1}, y_{2n})d(y_{2n-2}, y_{2n-1})}{d(y_{2n-1}, y_{2n-2})} \right\} \right)$$

$$= \phi (\max \{d(y_{2n-1}, y_{2n-2}), d(y_{2n-1}, y_{2n})\})$$

Thus $d(y_{2n-1}, y_{2n}) \leq \phi(d(y_{2n-2}, y_{2n-1})) \dots (2)$

From (1) and (2) we have

$$d(y_n, y_{n+1}) \leq \phi(d(y_{n-1}, y_n))$$

$$\leq \phi^2(d(y_{n-2}, y_{n-1}))$$

$$\vdots$$

$$\leq \phi^n(d(y_0, y_1)) \dots (3)$$

Now for $n, m \in N$ with $n < m$, we have

$$d(y_n, y_m) \leq d(y_n, y_{n+1}) + d(y_{n+1}, y_{n+2}) + \dots + d(y_{m-1}, y_m)$$

$$\leq \phi^n(d(y_0, y_1)) + \phi^{n+1}(d(y_0, y_1)) + \dots + \phi^{m-1}(d(y_0, y_1)) \text{ from (3)}$$

$$\leq \sum_{i=n}^{\infty} \phi^i(d(y_0, y_1))$$

$$\rightarrow 0 \text{ as } n, m \rightarrow \infty.$$

Hence $\{y_n\}$ is a Cauchy sequence in the complete dislocated metric space X . Hence there exists $u \in X$ such that $\{y_n\}$ converges to u .

Since $SF = FS$ and S and F are continuous, we have

$$Su = \lim_{n \rightarrow \infty} SFx_{2n} = \lim_{n \rightarrow \infty} FSx_{2n} = Fu.$$

Since $TG = GT$ and T and G are continuous, we have

$$Tu = \lim_{n \rightarrow \infty} TGx_{2n+1} = \lim_{n \rightarrow \infty} GTx_{2n+1} = Gu.$$

Thus the pairs (F, S) and (G, T) have a common coincidence point.

The following Example illustrates Theorem 2.1.

Example 2.2 Let $X = [0, 1]$ and $d(x, y) = \max\{x, y\}$. Then (X, d) is a dislocated metric space. Define

$$Sx = 0, Tx = \frac{x}{6}, Fx = x \text{ and } Gx = \frac{x}{3}.$$

Clearly S, T, F, G are continuous and (2.1.1) and (2.1.2) are satisfied. Also $d(Sx, Ty) \leq \phi(d(Fx, Gy))$ for all $x, y \in X$, where $\phi(t) = \frac{t}{2}$.

Clearly 0 is a common coincidence point of the pairs (F, S) and (G, T) .

Recently, Isufati[1] proved the following

Theorem 2.3 (Theorem 3.3, [1]). Let S, T be continuous self mappings on a complete dislocated metric space (X, d) satisfying

$$d(Sx, Ty) \leq h \max\{d(x, y), d(x, Sx), d(y, Ty), \frac{1}{2}[d(x, Ty) + d(y, Sx)]\}$$

for all $x, y \in X$ and $0 < h < 1$.

Then S and T have a common fixed point in X .

We observed that Theorem 2.3 is not valid in view of the following example.

Example 2.4 Let $X = \{1, 2, 3\}$ and $d(x, y) = \begin{cases} 2, & \text{if } x + y \text{ is even} \\ 1, & \text{if } x + y \text{ is odd} \end{cases}$.

Define $S, T : X \rightarrow X$ as $S1 = S2 = S3 = 1$ and $T1 = T2 = T3 = 2$.

Clearly $d(Sx, Ty) = \frac{1}{2} \max\{d(x, y), d(x, Sx), d(y, Ty), \frac{1}{2}[d(x, Ty) + d(y, Sx)]\}$ for all $x, y \in X$. Clearly 1 is a fixed point of S and 2 is a fixed point of T . Also S and T have no common fixed points.

Now, we give a corollary which is a probable modification of Theorem 2.3.

Corollary 2.5 Let (X, d) be a complete dislocated metric space and $S, T : X \rightarrow X$ be continuous mappings satisfying

$$(2.5.1) \quad d(Sx, Ty) \leq \phi(\max\{d(x, y), d(x, Sx), d(y, Ty), \frac{d(x, Sx)d(y, Ty)}{d(x, y)}\})$$

for all $x, y \in X$, where ϕ is as in Theorem 2.1.

Then either S or T has a fixed point or S and T have a unique common fixed point.

Proof. Putting $F = G = I$ (Identity map) in Theorem 2.1, we have either S or T has a fixed point or S and T have a common fixed point in X .

Suppose u and v are two common fixed points of S and T . Then

$$d(u, v) = d(Su, Tv) \leq \phi(\max\{d(u, v), d(u, u), d(v, v), \frac{d(u, u)d(v, v)}{d(u, v)}\}) \dots (1)$$

Replacing v by u in (1), we get

$d(u, u) \leq \phi(d(u, u))$ which implies that $d(u, u) = 0$.

Similarly, replacing u by v in (1), we get

$d(v, v) \leq \phi(d(v, v))$ which implies that $d(v, v) = 0$.

Now from (1),

$d(u, v) \leq \phi(d(u, v)) < d(u, v)$ if $d(u, v) > 0$. Hence $d(u, v) = 0$.

Since (X, d) is a dislocated metric space, we have $u = v$.

Hence S and T have a unique common fixed point.

Theorem 2.6 *Let (X, d) be a complete dq - metric space. Let $T : X \rightarrow X$ be a continuous mapping satisfying*

$$(2.6.1) \quad d(Tx, Ty) \leq \phi(\max\{d(x, y), d(x, Tx)d(y, Ty), \frac{d(x, Tx)d(y, Ty)}{d(x, y)}\})$$

for all $x, y \in X$, where ϕ is as in Theorem 2.1.

Then T has a unique common fixed point in X .

Proof. It is clear that $\phi(t) < t$ for all $t > 0$. Suppose x_0 is an arbitrary point of X .

Define $x_{n+1} = Tx_n, n = 0, 1, 2, \dots$

If $x_{n+1} = x_n$ for some n , then $Tx_n = x_n$. Hence x_n is a fixed point of T .

Assume that $x_{n+1} \neq x_n, \forall n$.

$$\begin{aligned} d(x_n, x_{n+1}) &= d(Tx_{n-1}, Tx_n) \\ &\leq \phi \left(\max \left\{ d(x_{n-1}, x_n), d(x_{n-1}, x_n), \right. \right. \\ &\quad \left. \left. d(x_n, x_{n+1}), \frac{d(x_{n-1}, x_n)d(x_n, x_{n+1})}{d(x_{n-1}, x_n)} \right\} \right) \\ &= \phi(\max\{d(x_{n-1}, x_n), d(x_n, x_{n+1})\}) \end{aligned}$$

If $\max\{d(x_{n-1}, x_n), d(x_n, x_{n+1})\} = d(x_n, x_{n+1})$ then

$d(x_n, x_{n+1}) \leq \phi(d(x_n, x_{n+1})) < d(x_n, x_{n+1})$.

It is a contradiction. Hence

$$\begin{aligned} d(x_n, x_{n+1}) &\leq \phi(d(x_{n-1}, x_n)) \\ &\leq \phi^2(d(x_{n-2}, x_{n-1})) \\ &\vdots \\ &\leq \phi^n(d(x_0, x_1)) \end{aligned}$$

As in Theorem 2.1, it follows that $\{x_n\}$ is a Cauchy sequence in complete dq - metric space X . Hence there exists $u \in X$ such that $\{x_n\}$ converges to u .

Since T is continuous, we have $u = \lim_{n \rightarrow \infty} Tx_n = T(\lim_{n \rightarrow \infty} x_n) = Tu$.

Suppose v is another fixed point of T . Now

$$\begin{aligned} d(u, v) &= d(Tu, Tv) \\ &\leq \phi \left(\max \left\{ d(u, v), d(u, u), d(v, v), \frac{d(u, u)d(v, v)}{d(u, v)} \right\} \right) \dots (1) \end{aligned}$$

Replacing v by u in (1), we get

$$d(u, u) \leq \phi(d(u, u)) < d(u, u) \text{ if } d(u, u) > 0.$$

Hence $d(u, u) = 0$ (2)

Similarly we can show that $d(v, v) = 0$ (3)

Now from(1), $d(u, v) \leq \phi(d(u, v))$ which implies that $d(u, v) = 0$(4)

$$\begin{aligned} d(v, u) &= d(Tv, Tu) \\ &\leq \phi \left(\max \left\{ d(v, u), d(v, v), d(u, u), \frac{d(v, v)d(u, u)}{d(v, u)} \right\} \right) \end{aligned}$$

Using(2) and (3),we have

$$d(v, u) \leq \phi(d(v, u)) \text{ which implies that } d(v, u) = 0$$
.....(5)

From (4) and (5), we have $u = v$.

Thus u is the unique fixed point of T .

Remark 2.7 *Theorem 3.3 of C.T. Aage, and J.N. Salunke [2] is a corollary to Theorem 2.6. Theorem 3.1 of A. Isufati [1] is a corollary to Theorem 2.6.*

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