

New Best Proximity Point Theorems for a Pair of Nonlinear Non-self Mappings in Metric Spaces

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Abstract

In this paper, we establish new convergence theorems and best proximity point theorems for a pair of nonlinear non-self mappings in metric spaces.

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1. Introduction and preliminaries

From a mathematical point of view, it is well known that several problems arising from diverse areas of natural science involve the existence of solutions of nonlinear equations with the form $Tx = x$, where T is a selfmapping or non-self mapping defined on metric spaces or topological vector spaces. Fixed point theory plays an important role in solving such nonlinear equations. However, in our experience, if T is not a selfmapping, there is a high possibility that the equations of the form $Tx = x$ does not necessarily admit a solution. In this status, one would try to find an approximate solution x in the domain of T such that the error $d(x, Tx)$ is minimum, where d is the distance function.

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Let A and B be nonempty subsets of a metric space (X, d) and $T : A \cup B \rightarrow A \cup B$ be a self-mapping. A point $x \in A \cup B$ is called a *best proximity point* for T if

$$d(x, Tx) = \text{dist}(A, B) := \inf\{d(x, y) : x \in A, y \in B\}.$$

In this paper, we denote by \mathbb{N} and \mathbb{R} , the sets of positive integers and real numbers, respectively.

In 2003, Kirk, Srinivasan and Veeramani [18] introduced cyclic mappings and best proximity points for generalizing the Banach contraction principle. Let A and B be nonempty subsets of a metric space (X, d) . A mapping $T : A \cup B \rightarrow A \cup B$ is called *cyclic* if

$$T(A) \subset B \text{ and } T(B) \subset A.$$

In the last decades, a number of existence and uniqueness theorems for best proximity point were investigated by several authors; see, e.g., [1-5, 8, 15-20] and references therein.

Let f be a real-valued function defined on \mathbb{R} . For $c \in \mathbb{R}$, we recall that

$$\limsup_{x \rightarrow c^+} f(x) = \inf_{\varepsilon > 0} \sup_{c < x < c + \varepsilon} f(x).$$

The concept of $\mathcal{MT}(\lambda)$ -function [8] was introduced by Du in 2016.

Definition 1.1. Let $\lambda > 0$. A function $\mu : [0, \infty) \rightarrow [0, \lambda)$ is said to be an $\mathcal{MT}(\lambda)$ -function [8, 10-15] if $\limsup_{s \rightarrow t^+} \mu(s) < \lambda$ for all $t \in [0, \infty)$. In particular, if $\lambda = 1$, then $\mu : [0, \infty) \rightarrow [0, 1)$ is called an \mathcal{MT} -function (or \mathcal{R} -function) [6-16].

Du established the following important and useful characterizations of $\mathcal{MT}(\lambda)$ -functions; see [8, 10-15].

Theorem 1.1 (see [8, Theorem 2.4]). Let $\lambda > 0$ and let $\mu : [0, \infty) \rightarrow [0, \lambda)$ be a function. Then the following statements are equivalent.

- (1) μ is an $\mathcal{MT}(\lambda)$ -function.
- (2) $\lambda^{-1}\mu$ is an \mathcal{MT} -function.
- (3) For each $t \in [0, \infty)$, there exist $\xi_t^{(1)} \in [0, \lambda)$ and $\epsilon_t^{(1)} > 0$ such that $\mu(s) \leq \xi_t^{(1)}$ for all $s \in (t, t + \epsilon_t^{(1)})$.
- (4) For each $t \in [0, \infty)$, there exist $\xi_t^{(2)} \in [0, \lambda)$ and $\epsilon_t^{(2)} > 0$ such that $\mu(s) \leq \xi_t^{(2)}$ for all $s \in [t, t + \epsilon_t^{(2)})$.

- (5) For each $t \in [0, \infty)$, there exist $\xi_t^{(3)} \in [0, \lambda)$ and $\epsilon_t^{(3)} > 0$ such that $\mu(s) \leq \xi_t^{(3)}$ for all $s \in (t, t + \epsilon_t^{(3)}]$.
- (6) For each $t \in [0, \infty)$, there exist $\xi_t^{(4)} \in [0, \lambda)$ and $\epsilon_t^{(4)} > 0$ such that $\mu(s) \leq \xi_t^{(4)}$ for all $s \in [t, t + \epsilon_t^{(4)})$.
- (7) For any nonincreasing sequence $\{x_n\}_{n \in \mathbb{N}}$ in $[0, \infty)$, we have $0 \leq \sup_{n \in \mathbb{N}} \mu(x_n) < \lambda$.
- (8) For any strictly decreasing sequence $\{x_n\}_{n \in \mathbb{N}}$ in $[0, \infty)$, we have $0 \leq \sup_{n \in \mathbb{N}} \mu(x_n) < \lambda$.
- (9) For any eventually nonincreasing sequence $\{x_n\}_{n \in \mathbb{N}}$ (i.e. there exists $\ell \in \mathbb{N}$ such that $x_{n+1} \leq x_n$ for all $n \in \mathbb{N}$ with $n \geq \ell$) in $[0, \infty)$, we have $0 \leq \sup_{n \in \mathbb{N}} \mu(x_n) < \lambda$.
- (10) For any eventually strictly decreasing sequence $\{x_n\}_{n \in \mathbb{N}}$ (i.e. there exists $\ell \in \mathbb{N}$ such that $x_{n+1} < x_n$ for all $n \in \mathbb{N}$ with $n \geq \ell$) in $[0, \infty)$, we have $0 \leq \sup_{n \in \mathbb{N}} \mu(x_n) < \lambda$.

In this paper, we establish new convergence theorems and best proximity point theorems for a pair of nonlinear non-self mappings in metric spaces.

2. Main results

Recently, Du introduced the concept of approximate sequence [15] as follows.

Definition 2.1 [15]. Let A and B be nonempty subsets of a metric space (X, d) and $\tau : [0, \infty) \rightarrow [0, 1)$ be a function. A sequence $\{x_n\}_{n \in \mathbb{N}}$ in $A \cup B$ is said to be *approximate with respect to τ* , if the following conditions are satisfied:

- (a) one of the following conditions holds:
- (i) $\{x_{2n-1}\}_{n \in \mathbb{N}} \subset A$ and $\{x_{2n}\}_{n \in \mathbb{N}} \subset B$;
 - (ii) $\{x_{2n}\}_{n \in \mathbb{N}} \subset A$ and $\{x_{2n-1}\}_{n \in \mathbb{N}} \subset B$,
- (b) $d(x_{n+1}, x_{n+2}) \leq \tau(d(x_n, x_{n+1}))d(x_n, x_{n+1}) + (1 - \tau(d(x_n, x_{n+1})))\text{dist}(A, B)$ for all $n \in \mathbb{N}$.

By applying Theorem 1.1, Du established the following convergence theorem for approximate sequences in [15].

Theorem 2.1 [15]. *Let A and B be nonempty subsets of a metric space (X, d) and $\varphi : [0, \infty) \rightarrow [0, 1)$ be an \mathcal{MT} -function. If $\{x_n\}_{n \in \mathbb{N}} \subset A \cup B$ is an approximate sequence with respect to φ , then $\lim_{n \rightarrow \infty} d(x_n, x_{n+1}) = \inf_{n \in \mathbb{N}} d(x_n, x_{n+1}) = \text{dist}(A, B)$.*

In this section, we first establish an existence theorems of approximate sequences for a pair of nonlinear non-self mappings.

Theorem 2.2. *Let A and B be nonempty subsets of a metric space (X, d) and $F : A \rightarrow B$ and $G : B \rightarrow A$ be two mappings. Suppose that*

(DY) *there exists a function $\varphi : [0, \infty) \rightarrow [0, 1)$ such that*

$$d(Fx, Gy) \leq \frac{1}{3}\varphi(d(x, y)) \max\{d(x, y) + d(Fx, y), d(x, Fx) + d(y, Gy) + d(Fx, Gy)\} + (1 - \varphi(d(x, y))) \text{dist}(A, B)$$

for all $x \in A$ and $y \in B$.

Then there exists an approximate sequence in $A \cup B$ with respect to φ .

Proof. Let $x_1 \in A$ be given. Define $x_{2n} = Fx_{2n-1}$ and $x_{2n+1} = Gx_{2n}$ for each $n \in \mathbb{N}$. Then $\{x_{2n-1}\}_{n \in \mathbb{N}} \subset A$ and $\{x_{2n}\}_{n \in \mathbb{N}} \subset B$. We want to show that the sequence $\{x_n\}_{n \in \mathbb{N}}$ in $A \cup B$ satisfies the following:

$$d(x_{n+1}, x_{n+2}) \leq \varphi(d(x_n, x_{n+1}))d(x_n, x_{n+1}) + (1 - \varphi(d(x_n, x_{n+1})))\text{dist}(A, B) \quad (2.1)$$

for all $n \in \mathbb{N}$. If $\varphi(d(x_1, x_2)) = 0$, then, by (DY), we have

$$d(x_2, x_3) \leq \text{dist}(A, B) \leq d(x_1, x_2),$$

and hence

$$\begin{aligned} d(x_2, x_3) &\leq \text{dist}(A, B) \\ &= \varphi(d(x_1, x_2))d(x_1, x_2) + (1 - \varphi(d(x_1, x_2)))\text{dist}(A, B). \end{aligned}$$

Suppose that $\varphi(d(x_1, x_2)) > 0$. From (DY), we get

$$\begin{aligned} d(x_2, x_3) &\leq \frac{1}{3}\varphi(d(x_1, x_2)) \max\{d(x_1, x_2), d(x_1, x_2) + 2d(x_2, x_3)\} \\ &\quad + (1 - \varphi(d(x_1, x_2)))\text{dist}(A, B) \quad (2.2) \\ &= \frac{1}{3}\varphi(d(x_1, x_2)) [d(x_1, x_2) + 2d(x_2, x_3)] + (1 - \varphi(d(x_1, x_2)))\text{dist}(A, B). \end{aligned}$$

We assume that

$$d(x_2, x_3) > d(x_1, x_2). \quad (2.3)$$

Then inequalities (2.2) and (2.3) deduce

$$d(x_2, x_3) < \varphi(d(x_1, x_2))d(x_2, x_3) + (1 - \varphi(d(x_1, x_2)))d(x_2, x_3) = d(x_2, x_3)$$

which leads to a contradiction. So it must be

$$d(x_2, x_3) \leq d(x_1, x_2) \quad (2.4)$$

So, by (2.2) and (2.4), we obtain

$$\begin{aligned} d(x_2, x_3) &\leq \frac{1}{3}\varphi(d(x_1, x_2))\{d(x_1, x_2) + 2d(x_2, x_3)\} + (1 - \varphi(d(x_1, x_2)))dist(A, B) \\ &\leq \varphi(d(x_1, x_2))d(x_1, x_2) + (1 - \varphi(d(x_1, x_2)))dist(A, B). \end{aligned}$$

Hence (2.1) holds for $n = 1$. Next, we claim that (2.1) holds for $n = 2$. If $\varphi(d(x_2, x_3)) = 0$, then, by (2.1) again, we obtain

$$d(x_4, x_3) \leq dist(A, B) \leq d(x_3, x_2),$$

and

$$d(x_4, x_3) \leq \varphi(d(x_3, x_2))d(x_3, x_2) + (1 - \varphi(d(x_3, x_2)))dist(A, B).$$

Assume that $\varphi(d(x_2, x_3)) > 0$. By (DY), we get

$$\begin{aligned} d(x_4, x_3) &\leq \frac{1}{3}\varphi(d(x_3, x_2))\max\{d(x_4, x_3) + 2d(x_3, x_2), d(x_2, x_3) + 2d(x_4, x_3)\} \\ &\quad + (1 - \varphi(d(x_3, x_2)))dist(A, B). \end{aligned} \quad (2.5)$$

Suppose that

$$d(x_2, x_3) + 2d(x_4, x_3) > d(x_4, x_3) + 2d(x_3, x_2).$$

Then we obtain

$$d(x_4, x_3) > d(x_3, x_2). \quad (2.6)$$

Thus inequalities (2.5) and (2.6) imply

$$d(x_3, x_2) < \varphi(d(x_2, x_1))d(x_3, x_2) + (1 - \varphi(d(x_2, x_1)))d(x_3, x_2) = d(x_3, x_2)$$

which is a contradiction. Hence it must be

$$d(x_4, x_3) \leq d(x_3, x_2). \quad (2.7)$$

Using (2.5) and (2.7), we obtain

$$\begin{aligned} d(x_4, x_3) &\leq \frac{1}{3}\varphi(d(x_3, x_2)) \max\{d(x_4, x_3) + 2d(x_3, x_2), d(x_2, x_3) + 2d(x_4, x_3)\} \\ &\quad + (1 - \varphi(d(x_3, x_2)))\text{dist}(A, B). \\ &\leq \varphi(d(x_3, x_2))d(x_3, x_2) + (1 - \varphi(d(x_3, x_2)))\text{dist}(A, B). \end{aligned}$$

So (2.1) is true for $n = 2$. By induction, we prove that our claim (2.1) holds for $n \in \mathbb{N}$. Hence, we show that $\{x_n\}_{n \in \mathbb{N}}$ is an approximate sequence in $A \cup B$ with respect to φ . \square

Theorem 2.3. *Let A and B be nonempty subsets of a metric space (X, d) and $T : A \cup B \rightarrow A \cup B$ be a cyclic mapping. Suppose that*

(H) *there exists a function $\varphi : [0, \infty] \rightarrow [0, 1)$ such that*

$$\begin{aligned} d(Tx, Ty) &\leq \frac{1}{3}\varphi(d(x, y)) \max\{d(x, y) + d(Tx, y), d(x, Tx) + d(y, Ty) \\ &\quad + d(Tx, Ty)\} + (1 - \varphi(d(x, y)))\text{dist}(A, B) \end{aligned}$$

for all $x \in A$ and $y \in B$.

Then there exists an approximate sequence in $A \cup B$ with respect to φ .

Proof. Since T is cyclic, we have $T(A) \subset B$ and $T(B) \subset A$. So we can define two mapping $F : A \rightarrow B$ and $G : B \rightarrow A$ by $F := T|_A$ and $G := T|_B$. It is easy to see that the condition (H) implies the condition (DY). Hence, the conclusion is immediate from Theorem 2.2. \square

Applying Theorems 2.1 and 2.2, we establish immediately the following new convergence theorem.

Theorem 2.4. *Let A and B be nonempty subsets of a metric space (X, d) and $F : A \rightarrow B$ and $G : B \rightarrow A$ be two mappings. Suppose that there exists an \mathcal{MT} -function $\varphi : [0, \infty] \rightarrow [0, 1)$ such that*

$$\begin{aligned} d(Fx, Gy) &\leq \frac{1}{3}\varphi(d(x, y)) \max\{d(x, y) + d(Fx, y), d(x, Fx) + d(y, Gy) \\ &\quad + d(Fx, Gy)\} + (1 - \varphi(d(x, y)))\text{dist}(A, B) \end{aligned}$$

for all $x \in A$ and $y \in B$. Then there exists a sequence $\{x_n\}_{n \in \mathbb{N}} \subset A \cup B$ such that

$$(a) \quad d(x_{n+1}, x_{n+2}) \leq \varphi(d(x_n, x_{n+1}))d(x_n, x_{n+1}) + [1 - \varphi(d(x_n, x_{n+1}))]\text{dist}(A, B)$$

for all $n \in \mathbb{N}$;

$$(b) \lim_{n \rightarrow \infty} d(x_n, x_{n+1}) = \inf_{n \in \mathbb{N}} d(x_n, x_{n+1}) = \text{dist}(A, B).$$

Corollary 2.1. *Let A and B be nonempty subsets of a metric space (X, d) and $T : A \cup B \rightarrow A \cup B$ be a cyclic mapping. Suppose that there exists an \mathcal{MT} -funtion $\varphi : [0, \infty] \rightarrow [0, 1)$ such that*

$$d(Fx, Gy) \leq \frac{1}{3} \varphi(d(x, y)) [d(x, y) + d(Fx, y)] + (1 - \varphi(d(x, y))) \text{dist}(A, B)$$

for all $x \in A$ and $y \in B$. Then there exists a sequence $\{x_n\}_{n \in \mathbb{N}} \subset A \cup B$ such that

$$(a) d(x_{n+1}, x_{n+2}) \leq \varphi(d(x_n, x_{n+1}))d(x_n, x_{n+1}) + [1 - \varphi(d(x_n, x_{n+1}))] \text{dist}(A, B) \text{ for all } n \in \mathbb{N};$$

$$(b) \lim_{n \rightarrow \infty} d(x_n, x_{n+1}) = \inf_{n \in \mathbb{N}} d(x_n, x_{n+1}) = \text{dist}(A, B).$$

Corollary 2.2. *Let A and B be nonempty subsets of a metric space (X, d) and $T : A \cup B \rightarrow A \cup B$ be a cyclic mapping. Suppose that there exists an \mathcal{MT} -funtion $\varphi : [0, \infty] \rightarrow [0, 1)$ such that*

$$d(Fx, Gy) \leq \frac{1}{3} \varphi(d(x, y)) [d(x, Fx) + d(y, Gy) + d(Fx, Gy)] + (1 - \varphi(d(x, y))) \text{dist}(A, B)$$

for all $x \in A$ and $y \in B$. Then there exists a sequence $\{x_n\}_{n \in \mathbb{N}} \subset A \cup B$ such that

$$(a) d(x_{n+1}, x_{n+2}) \leq \varphi(d(x_n, x_{n+1}))d(x_n, x_{n+1}) + [1 - \varphi(d(x_n, x_{n+1}))] \text{dist}(A, B) \text{ for all } n \in \mathbb{N};$$

$$(b) \lim_{n \rightarrow \infty} d(x_n, x_{n+1}) = \inf_{n \in \mathbb{N}} d(x_n, x_{n+1}) = \text{dist}(A, B).$$

Some new existence theorems for best proximity points can be established by applying Theorem 2.4.

Theorem 2.5. *In Theorem 2.4, if we further assume*

$$(C) d(Fx, Gy) \leq d(x, y) \text{ for any } x \in A \text{ and } y \in B.$$

Then the following statements hold.

- (a) If $\{x_{2n-1}\}_{n \in \mathbb{N}}$ has a convergent subsequence in A , then there exists $u \in A$ such that $d(u, Fu) = \text{dist}(A, B)$.
- (b) If $\{x_{2n}\}_{n \in \mathbb{N}}$ has a convergent subsequence in B , then there exists $v \in B$ such that $d(v, Gv) = \text{dist}(A, B)$.

Proof. Applying Theorem 2.4 and following a similar argument as the proof of [15, Theorem 2.5], we can prove the conclusion. \square

Remark 2.1. As a direct application of Theorem 2.5, we can obtain easily some new (common) fixed point theorems.

Corollary 2.3. Let A and B be nonempty subsets of a metric space (X, d) and $T : A \cup B \rightarrow A \cup B$ be a cyclic mapping. Suppose that

- (i) $d(Tx, Ty) \leq d(x, y)$ for any $x \in A$ and $y \in B$.
- (ii) there exists an \mathcal{MT} -funtion $\varphi : [0, \infty] \rightarrow [0, 1)$ such that

$$d(Tx, Ty) \leq \frac{1}{3} \varphi(d(x, y)) \max\{d(x, y) + d(Tx, y), d(x, Tx) + d(y, Ty) + d(Tx, Ty)\} + (1 - \varphi(d(x, y))) \text{dist}(A, B)$$

for all $x \in A$ and $y \in B$.

Then the following statements hold.

- (a) If $\{x_{2n-1}\}_{n \in \mathbb{N}}$ has a convergent subsequence in A , then there exists $u \in A$ such that $d(u, Tu) = \text{dist}(A, B)$.
- (b) If $\{x_{2n}\}_{n \in \mathbb{N}}$ has a convergent subsequence in B , then there exists $v \in B$ such that $d(v, Tv) = \text{dist}(A, B)$.

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