

## Lie Group Structure on the Set $BP(\mathbb{R}^2)$

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### Abstract

A ball with one dimension is a circle. Let  $BP(\mathbb{R}^2)$  be the set of circles with the same center and  $r$ -radius. In this article, we prove that the set of  $S$  has a group structure, manifold structure and Lie group structure. If  $\{A_i\}_{i \in \mathbb{N}} = A$  is a partition of a non-empty set  $A$  and there is a relation among all on  $A_i$ , then some geometric properties workable on  $A$  using this partition. In this study, using  $S_{r_k}^1$  partition of  $\mathbb{R}^2$  we establish Lie group structure on this  $S_{r_k}^1$  partition.

**Mathematics Subject Classification:** 22E15, 22E20

**Keywords:** Circle, Lie group, manifold

## 1 Introduction

We know that  $\mathbb{R}^2$  is a set of  $(x, y)$  points, where  $x, y \in \mathbb{R}$ . Nevertheless we can introduce  $\mathbb{R}^2$  as a collection of subsets of  $\mathbb{R}^2$  which union of these subsets is  $\mathbb{R}^2$ . For example, we can treat  $\mathbb{R}^2$  as a collection of the parallel straight lines. Similarly,  $\mathbb{R}^2$  is a collection of vectors, or  $P, X$  tangent vectors, etc.  $\mathbb{R}^2$  allows

us to build different structures on each different handling  $\mathbb{R}^2$ . A new structure can be created by treating  $\mathbb{R}^2$  as circles with center  $(0, 0)$  and radius  $r$ ,  $r \in \mathbb{R}^+$ . In this paper, a new structure on  $\mathbb{R}^2$  using the ball partition  $BP$  of  $\mathbb{R}^2$  will be tried to construct. Firstly, we give the definitions and some properties of group, manifold and Lie groups.

**Definition 1.1** *A group  $(G, *)$  is a monoid, with identity  $e$ , which has the additional property that for every element  $a \in G$ , there exists an element  $a' \in G$  such that*

*$a * a' = a' * a = e$ . Thus a group is a set  $G$  together with a binary operation  $*$  on  $G$  such that*

- 1)  *$(a * b) * c = a * (b * c)$  for any elements  $a, b$  and  $c$  in  $G$ .*
- 2) *There is a unique element  $e$  in  $G$  such that*

$$a * e = e * a \quad (1)$$

for any  $a \in G$ .

3) *For every  $a \in G$  there is an element  $a' \in G$ , called an inverse of  $a$ , such that*

$$a * a' = a' * a = e \quad (2)$$

[4].

**Definition 1.2** *A differentiable or  $C^\infty$  (or smooth) structure on a topological manifold  $M$  is a family  $U = \{U_\alpha, \varphi_\alpha\}$  of coordinate neighborhoods such that:*

- 1) *the  $U_\alpha$  cover  $M$ ,*
- 2) *for any  $\alpha, \beta$  the neighborhoods  $U_\alpha, \varphi_\alpha$  and  $U_\beta, \varphi_\beta$  are  $C^\infty$ -compatible,*
- 3) *any coordinate neighborhood  $V, \psi$  compatible with every  $U_\alpha, \varphi_\alpha \in U$  is itself in  $U$ .*

*A  $C^\infty$  manifold is a topological manifold together with a  $C^\infty$ -differentiable structure [1, 2, 3].*

Let  $M$  be a manifold and  $N$  be a set. If there is a 1:1 correspondence between  $M$  and  $N$ , then we can establish a manifold structure on  $N$ . For example,  $\mathbb{R}^{m \cdot n}$  is a manifold and  $M(n \times m, \mathbb{R})$  is a set of  $n \times m$  real matrices. And there is a 1:1 correspondence between  $\mathbb{R}^{m \cdot n}$  and  $M(n \times m, \mathbb{R})$ . Finally,  $M(n \times m, \mathbb{R})$  is a differentiable manifold.

**Definition 1.3** *A Lie group is a group which is at same time a differentiable manifold such that the group operation  $(a, b) \in G \times G \rightarrow ab^{-1} \in G$  is a manifold mapping of  $G \times G$  into  $G$  [3].*

Let  $M$  be a non-empty set. The set

$$M = \{U_i \mid U_i \subset M, i = 1, \dots, n, n \in \mathbb{N}\} \tag{3}$$

is called a covering of the set  $M$ . A covering  $M$  is called a partition of the set  $M$ . If  $U_i \cap U_j = \emptyset$  for every  $i, j, i, j = 1, \dots, n, i \neq j$ .

In this study, we will study on  $\mathbb{R}^2$ , but what we say is true for  $\mathbb{R}^n$ .

Another partition of  $\mathbb{R}^2$  can be given as follows.

$$L(\mathbb{R}^2) = \{A_i \mid A_i = \{(x, y) \mid y = mx + n, m : \text{fixed}, n \in \mathbb{R}\}\}. \tag{4}$$

In the partition  $P(\mathbb{R}^2)$ , subsets are points  $(x, y)$ . Using the properties of points, we can define some structures on  $\mathbb{R}^2$  as affine structure, manifold structure, etc.

In the partition  $L(\mathbb{R}^2)$ , subsets are parallel straight lines. Using the properties of parallel lines, we can define some structures on  $\mathbb{R}^2$ .

## 2 $B^1(\mathbb{R}^2)$ Partition of $\mathbb{R}^2$

In this section we define a special partition of  $\mathbb{R}^2$  using circles with center  $(0, 0)$ .

**Definition 2.1** *The partition*

$$BP(\mathbb{R}^2) = \{C_r(0, 0) \mid r \in \mathbb{R}^+\} \tag{5}$$

is called ball partition of  $\mathbb{R}^2$ , where  $C_r(0, 0) = \{x, y\} \in \mathbb{R}^2 \mid x^2 + y^2 = r^2\}$ .

It is sufficient to know what is radius  $r$  to  $C_r(0, 0)$ . When  $r \in \mathbb{R}^+$  is given we can define  $C_r(0, 0)$  and  $\{re^{i\theta} \mid 0 \leq r \leq \theta\}$ . So the following diagram is commutative (Figure 2).

Now we define a product  $\otimes$  on  $BP(\mathbb{R}^2)$  as follows.

$$\begin{aligned} BP(\mathbb{R}^2) \times BP(\mathbb{R}^2) &\rightarrow BP(\mathbb{R}^2) \\ (C_{r_1}, C_{r_2}) &\rightarrow C_{r_1} \otimes C_{r_2} = C_{(r_1.r_2)} \end{aligned} \tag{6}$$

where the product  $r_1.r_2$  is product on  $\mathbb{R}$ .

**Theorem 2.2**  $(BP(\mathbb{R}^2), \otimes)$  is an abel group.

1. Associativity:  $\forall C_{r_1}, C_{r_2}$  and  $C_{r_3}$ ,

$$(C_{r_1} \otimes C_{r_2}) \otimes C_{r_3} = C_{r_1} \otimes (C_{r_2} \otimes C_{r_3}) \tag{7}$$

2. Existance of unit element: For  $r = 1, C_r$  is an unit element.
3. Existance of inverse element: For every  $C_r, C_{\frac{1}{r}}$  is the inverse element.
4. Commutative or abelian property: For every  $C_{r_1}$  and  $C_{r_2}$ ,

$$C_{r_1} \otimes C_{r_2} = C_{r_1.r_2} = C_{r_2.r_1} = C_{r_2} \otimes C_{r_1}. \tag{8}$$

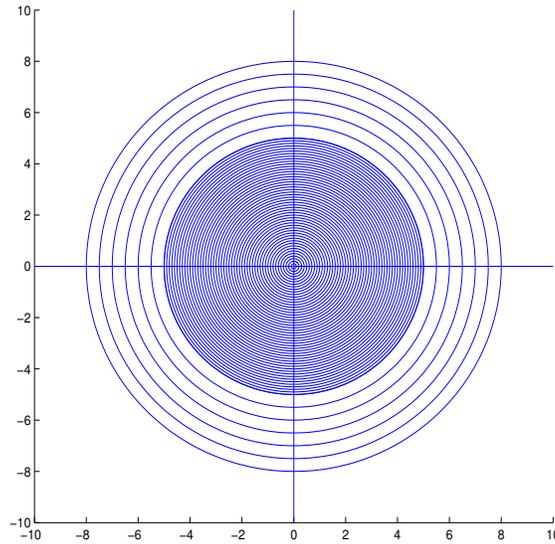


Figure 1:  $BP(\mathbb{R}^2)$  Ball Partition of  $\mathbb{R}^2$

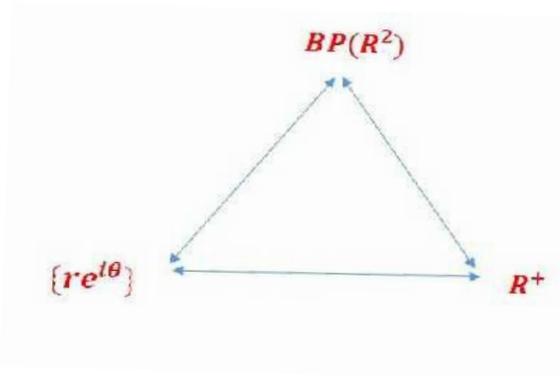


Figure 2: Commutative diagram

**Theorem 2.3**  $BP(\mathbb{R}^2)$  is a differentiable manifold with dimension 1.

**Proof 2.4** There is a 1:1 correspondence between  $BP(\mathbb{R}^2)$  and  $\mathbb{R}^+$ .  $\mathbb{R}^+$  is an open subset of  $\mathbb{R}$  and  $\mathbb{R}$  is a differentiable manifold [1].

We know that every open subset of a manifold is a differentiable manifold with same dimension [1]. So  $BP(\mathbb{R}^2)$  is a manifold with dimension 1.

Any open subset of  $BP(\mathbb{R}^2)$  is

$$\{C_r \mid r_0 < r < r_2, r_0, r, r_1 \in \mathbb{R}\} \tag{9}$$

Now we can give a Lie group structure on  $BP(\mathbb{R}^2)$ .

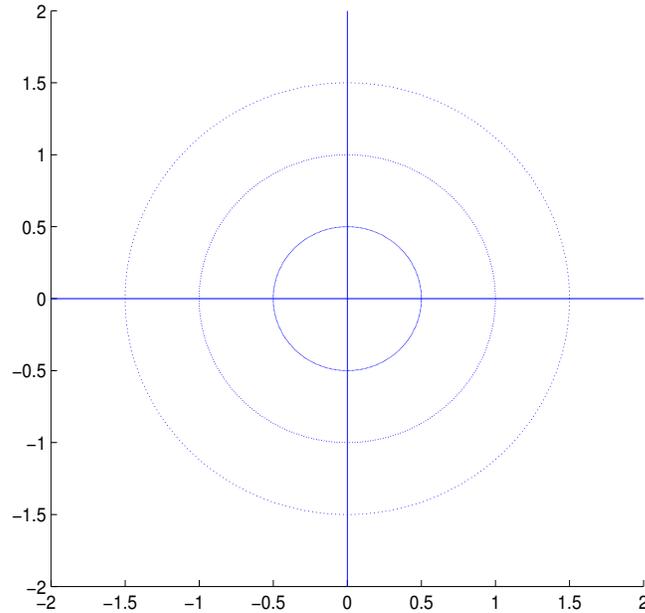


Figure 3: Unit element and inverse element

**Theorem 2.5**  $BP(\mathbb{R}^2)$  is a Lie group.

**Proof 2.6** We showed that  $BP(\mathbb{R}^2)$  is a differentiable manifold with dimension 1. Also, the group operation

$$C_{r_1} \otimes C_{r_2} = C_{r_1.r_2} \quad (10)$$

is differentiable such that  $r_1 e^{i\theta_1} . r_2 e^{i\theta_2} = r_1 r_2 e^{i\theta}$  is differentiable.

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