

On Decomposable Almost Pseudo Projectively Symmetric Manifolds

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Abstract

In this paper we study the almost pseudo projectively symmetric Riemannian manifold of dim n & decomposable almost pseudo projectively symmetric Riemannian manifold of dim n ($n \geq 3$).

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1. Introduction

Let (M^n, g) be a Riemannian manifold of dim- n ($n \geq 3$). A non-flat Riemannian manifold (M^n, g) , ($n \geq 2$) is called an almost pseudo symmetric manifold whose curvature tensor R of type (0,4) satisfies condition [18].

$$\begin{aligned}(\nabla_X R)(Y, Z, U, V) = [A(X) + B(X)]R(Y, Z, U, V) \\ + A(Y)R(X, Z, U, V) + A(Z)R(Y, X, U) \\ + A(U)R(Y, Z, X, V) + A(V)R(Y, Z, U, X)\end{aligned}\quad (1.1)$$

where A and B are nowhere vanishing 1-forms such that

$$A(X) = g(X, \rho) \text{ \& } B(X) = g(X, Q) \quad \text{for all } X, \quad (1.2)$$

ρ and Q are the vector fields associated with the 1-forms A and B , respectively. An n -dimensional almost pseudo symmetric manifold has been denoted by $A(PS)_n$. If $A = B$ in (1.1), then the manifold reduces to a pseudo symmetric manifold $(PS)_n$ introduced by Chaki[12], whose notion is different from that of introduced by Deszcz [14]. Pseudo symmetric spaces, generalized symmetric spaces, were also studied by Mikes[6,7]. Also almost pseudo symmetric manifold is not a particular case of a weakly symmetric manifold $(WS)_n$ introduced by Tamassy and Binh[11].

The notion of locally symmetric manifolds has been weakened by many authors in several ways to a different extent such as conformally symmetric manifolds by Chaki and Gupta[12], recurrent manifolds introduced by Walker[2], conformally recurrent manifolds by Adati and Miyazawa[17], projective symmetric manifolds by Soos[5], projective-symmetric and projectively recurrent affinely connected spaces by Mikes[6], pseudo-conformally symmetric spaces by De and Biswas[19], almost pseudo conformally symmetric manifolds by De and Gazi [20], weakly conharmonically symmetric manifolds by Shaikh and Hui[1].

The projective curvature W of type (0,4) of a Riemannian manifold (M^n, g) ($n > 3$) is given by

$$\begin{aligned} W(Y, Z, U, V) &= R(Y, Z, U, V) - \frac{1}{(n-1)} [S(Z, U)g(Y, V) - S(Y, U)g(Z, V)] \end{aligned} \quad (1.3)$$

where S is the Ricci tensor of the manifold of type (0,2). The present paper is concerned with a non-projective flat Riemannian manifold (M^n, g) ($n > 3$) whose projective curvature tensor W satisfies the condition

$$\begin{aligned} (\nabla_X W)(Y, Z, U, V) &= [A(X) + B(X)]W(Y, Z, U, V) \\ &\quad + A(Y)W(X, Z, U, V) + A(Z)W(Y, X, U, V) \\ &\quad + A(U)W(Y, Z, X, V) + A(V)W(Y, Z, U, X) \end{aligned} \quad (1.4)$$

where A & B are same as defined in (1.2). A manifold of this type will be known as almost pseudo projectively symmetric manifold denoted by $A(PPS)_n$. As the conformal curvature tensor vanishes identically for $n = 3$, we assume the condition $n > 3$ throughout the paper. The paper is organized as follows

In Section 2, it deals with an $A(PPS)_n$. In Section 3, it is concerned with a decomposable $A(PPS)_n$ and exactly defined each decomposition of an $A(PPS)_n$. In Section 4, it is shown that the integral curves of the unit torse-forming vector field ρ in an Einstein $A(PPS)_n$ are geodesics. Hence it is also found that the vector field Q is the torse-forming vector field and its integral curves are geodesics.

2. $A(PPS)_n$

L denotes the symmetric endomorphism of the tangent space at each point of the manifold corresponding to the Ricci tensor S of type $(0,2)$, that is

$$g(LX, Y) = S(X, Y) \tag{2.1}$$

Let $e_i, (1 \leq i \leq n)$ be an orthonormal basis of the tangent space at any point of the manifold. From (1.3), we have

$$\begin{aligned} F(Z, U) &= \sum_{i=1}^n W(Z, e_i, e_i, U) = \sum_{i=1}^n W(e_i, Z, U, e_i) \\ &= -\frac{r}{n-1} g(Z, U) \end{aligned}$$

$$\sum_{i=1}^n K(e_i, e_i, Y, Z) = \sum_{i=1}^n K(Y, Z, e_i, e_i) = 0$$

(2.2)

where r is the scalar curvature of the manifold.

From (1.4) and (2.2), we have

$$\begin{aligned} (\nabla_X F)(Z, U) &= -\frac{r}{n-1} \{[A(X) + B(X)]\}g(Z, U) \\ &\quad + A(R(X, Z)U) - \frac{1}{n-1} \{S(Z, U)A(X) - S(X, U)A(Z)\} \\ &\quad + A(R(X, U)Z) - \frac{1}{n-1} \{S(U, Z)A(X) - S(X, Z)A(U)\} \end{aligned} \tag{2.3}$$

Putting $Z = U = e_i$ in (2.3) and taking summation over $i, (1 \leq i \leq n)$, it follows from (2.2) that

$$\nabla_X r = r \left\{ \left(\frac{n+2}{n} \right) A(X) + B(X) \right\} \tag{2.4}$$

Thus we can state it as a theorem as follows

Theorem—1 The scalar curvature tensor r of an $A(PPS)_n$ satisfies the following relation

$$\nabla_X r = r \left\{ \left(\frac{n+2}{n} \right) A(X) + B(X) \right\} \quad \text{for all } X. \tag{2.5}$$

Let us consider $A(PPS)_n$ of constant scalar curvature. Thus from (2.5) and r not equal to 0, we get

$$\left(\frac{n+2}{n} \right) A(X) + B(X) = 0 \quad \text{for all } X \tag{2.6}$$

this implies the following theorem

Theorem—2 The two associated 1 –forms in an $A(PPS)_n$ of non-zero constant scalar curvature are linearly dependent.

3. Decomposable $A(PPS)_n$

If a Riemannian manifold (M^n, g) can be expressed as the product, $M_1^p \times M_2^{n-p}$ for $(2 \leq p \leq n - 2)$, namely, if coordinates can be found so that its metric takes the form [16]

$$dS^2 = g_{ij} dx^i dx^j = \bar{g}_{ab} dx^a dx^b + g^*_{\alpha\beta} dx^\alpha dx^\beta \quad (3.1)$$

then it is called decomposable.

where \bar{g}_{ab} are functions of x^1, x^2, \dots, x^p & $g^*_{\alpha\beta}$ are functions of $x^{p+1}, x^{p+2}, \dots, x^n$ only. a, b, c, \dots are taken to have range from 1 to p & $\alpha, \beta, \gamma, \dots$ are taken to have range from $p + 1$ to n . The two parts of (3.1) are the metrics of $M_1^p (p \geq 2)$ and $M_2^{n-p} (n - p \geq 2)$ which are called the decomposable spaces of M^n [9].

From eq(3.1), we have

$$g_{ab} = \bar{g}_{ab}, g_{\alpha\beta} = g^*_{\alpha\beta}, g^{ab} = \bar{g}^{ab}, g^{\alpha\beta} = g^{*\alpha\beta}, g_{\alpha\beta} = g^{\alpha\beta} = 0 \quad (3.2)$$

Let $(M^n, g) = (M_1^p, \bar{g}) \times (M_2^{n-p}, g^*) (2 \leq p \leq n - 2)$ be a decomposable Riemannian manifold. Throughout this paper objects from M_1 are denoted by 'bar' and that from M_2 are denoted by 'star'.

Let $\bar{X}, \bar{Y}, \bar{Z}, \bar{U}, \bar{V} \in \chi(M_1)$ and $X^*, Y^*, Z^*, U^*, V^* \in \chi(M_2)$. In decomposable Riemannian manifold the following relations hold [9]

$$\begin{aligned} R(X^*, \bar{Y}, \bar{Z}, \bar{U}) &= 0 = R(\bar{X}, Y^*, \bar{Z}, U^*) = R(\bar{X}, Y^*, Z^*, U^*) \\ (\nabla_{X^*} R)(\bar{Y}, \bar{Z}, \bar{U}, \bar{V}) &= 0 = (\nabla_{\bar{X}} R)(\bar{Y}, Z^*, \bar{U}, V^*) = (\nabla_{X^*} R)(\bar{Y}, Z^*, \bar{U}, V^*) \\ R(\bar{X}, \bar{Y}, \bar{Z}, \bar{U}) &= \bar{R}(\bar{X}, \bar{Y}, \bar{Z}, \bar{U}); \\ R(X^*, Y^*, Z^*, U^*) &= R^*(X^*, Y^*, Z^*, U^*) \\ S(\bar{X}, \bar{Y}) &= \bar{S}(\bar{X}, \bar{Y}) \\ S(X^*, Y^*) &= S^*(X^*, Y^*) \\ (\nabla_{\bar{X}} S)(\bar{Y}, \bar{Z}) &= (\bar{\nabla}_{\bar{X}} S)(\bar{Y}, \bar{Z}); \\ (\nabla_{X^*} S)(Y^*, Z^*) &= (\nabla^*_{X^*} S)(Y^*, Z^*) \\ r &= \bar{r} + r^* \end{aligned} \quad (3.3)$$

we consider a decomposable $A(PPS)_n$, which is decomposable in M_1^p & $M_2^{n-p} (2 \leq p \leq n - 2)$.

Then using (3.3), we have from (1.3)

$$W(X^*, \bar{Y}, \bar{Z}, \bar{U}) = W(\bar{X}, Y^*, Z^*, U^*) = 0$$

$$W(X^*, \bar{Y}, \bar{Z}, U^*) = \frac{1}{n-1} [S(\bar{Y}, \bar{Z})g(X^*, U^*)] \tag{3.4}$$

From (1.4) on the manifold M_1 , we have

$$\begin{aligned} (\nabla_{\bar{X}}W)(\bar{Y}, \bar{Z}, \bar{U}, \bar{V}) &= [A(\bar{X}) + B(\bar{X})]W(\bar{Y}, \bar{Z}, \bar{U}, \bar{V}) \\ &\quad + A(\bar{Y})W(\bar{X}, \bar{Z}, \bar{U}, \bar{V}) + A(\bar{Z})W(\bar{Y}, \bar{X}, \bar{U}, \bar{V}) \\ &\quad + A(\bar{U})W(\bar{Y}, \bar{Z}, \bar{X}, \bar{V}) + A(\bar{V})W(\bar{Y}, \bar{Z}, \bar{U}, \bar{X}) \end{aligned} \tag{3.5}$$

Replacing \bar{X} by X^* in (3.5) and using (3.4) & (3.3), we get

$$[A(X^*) + B(X^*)]W(\bar{Y}, \bar{Z}, \bar{U}, \bar{V}) = 0 \tag{3.6}$$

Similarly, replacing \bar{Y} by Y^* , we have

$$A(Y^*)W(\bar{X}, \bar{Z}, \bar{U}, \bar{V}) = 0 \tag{3.7}$$

Put $\bar{X} = X^*$ & $\bar{U} = U^*$ in (3.5), we get

$$A(\bar{Y})W(X^*, \bar{Z}, U^*, \bar{V}) + A(\bar{Z})W(\bar{Y}, X^*, U^*, \bar{V}) + A(\bar{V})W(\bar{Y}, \bar{Z}, U^*, X^*) = 0 \tag{3.8}$$

Similarly putting $\bar{Y} = Y^*$ & $\bar{V} = V^*$ in (3.5), we get

$$\begin{aligned} [A(\bar{X}) + B(\bar{X})]W(Y^*, \bar{Z}, \bar{U}, V^*) + A(\bar{Z})W(Y^*, \bar{X}, \bar{U}, V^*) + \\ A(\bar{U})W(Y^*, \bar{Z}, \bar{X}, V^*) = 0 \end{aligned} \tag{3.9}$$

Setting $\bar{X} = X^*$, $\bar{Y} = Y^*$ & $\bar{V} = V^*$ in (3.5), we get

$$\begin{aligned} (\nabla_{X^*}W)(Y^*, \bar{Z}, \bar{U}, V^*) &= [A(X^*) + B(X^*)]W(Y^*, \bar{Z}, \bar{U}, V^*) \\ &\quad + A(Y^*)W(X^*, \bar{Z}, \bar{U}, V^*) + A(V^*)W(Y^*, \bar{Z}, \bar{U}, X^*) \end{aligned} \tag{3.10}$$

Similarly replacing $\bar{Z} = Z^*$, $\bar{U} = U^*$ & $\bar{V} = V^*$ in (3.5), we get

$$A(Z^*)W(\bar{Y}, \bar{X}, U^*, V^*) + A(U^*)W(\bar{Y}, Z^*, \bar{X}, V^*) + A(V^*)W(\bar{Y}, Z^*, U^*, \bar{X}) = 0 \tag{3.11}$$

Setting $\bar{X} = X^*$, $\bar{Z} = Z^*$, $\bar{U} = U^*$ & $\bar{V} = V^*$ in (3.5), we get

$$A(\bar{Y})W(X^*, Z^*, U^*, V^*) = 0 \tag{3.12}$$

Similarly putting $\bar{Y} = Y^*$, $\bar{Z} = Z^*$, $\bar{U} = U^*$ & $\bar{V} = V^*$ in (3.5), we get

$$[A(\bar{X}) + B(\bar{X})]W(Y^*, Z^*, U^*, V^*) = 0 \tag{3.13}$$

Now setting $\bar{X} = X^*$, $\bar{Y} = Y^*$, $\bar{Z} = Z^*$, $\bar{U} = U^*$ & $\bar{V} = V^*$ in (3.5), we get

$$\begin{aligned} (\nabla_{X^*}W)(Y^*, Z^*, U^*, V^*) &= [A(X^*) + B(X^*)]W(Y^*, Z^*, U^*, V^*) \\ &\quad + A(Y^*)W(X^*, Z^*, U^*, V^*) + A(Z^*)W(Y^*, X^*, U^*, V^*) \\ &\quad + A(U^*)W(Y^*, Z^*, X^*, V^*) + A(V^*)W(Y^*, Z^*, U^*, X^*) \end{aligned} \tag{3.14}$$

Thus from (3.6), (3.7), (3.12) & (3.13) we have following theorem

Theorem-3 Let an $A(PPS)n$ be a decomposable space such that $M^n = M_1^p \times M_2^{n-p}$ for $(2 \leq p \leq n - 2)$, then one of the decomposition is projectively flat and on the other $A = B = 0$.

Let us now deal with each decomposition individually. Let one of the decompositions be projectively flat. Then, we get

$$W(\bar{Y}, \bar{Z}, \bar{U}, \bar{V}) = 0 \text{ for } \bar{Y}, \bar{Z}, \bar{U}, \bar{V} \in \chi(M_1)$$

From (1.3), we have

$$R(\bar{Y}, \bar{Z}, \bar{U}, \bar{V}) = \frac{1}{n-1} [S(\bar{Z}, \bar{U})g(\bar{Y}, \bar{V}) - S(\bar{Y}, \bar{U})g(\bar{Z}, \bar{V})] \quad (3.15)$$

Contracting over \bar{Y} & \bar{V} , we get

$$S(\bar{Z}, \bar{U}) = 0 \quad (3.16)$$

Hence manifold M_1 is of vanishing curvature.

Let us consider the other decomposition, that is, $A = B = 0$ on M_2 . Then from (3.10), we get

$$(\nabla_{X^*} W)(Y^*, \bar{Z}, \bar{U}, V^*) = 0$$

Which implies that

$$(\nabla_{X^*} S)(Y^*, V^*) = 0 \quad (3.17)$$

Hence we see that the manifold M_1 is Ricci-symmetric.

By virtue of equation(3.14), we have

$$(\nabla_{X^*} W)(Y^*, Z^*, U^*, V^*) = 0 \quad (3.18)$$

Therefore we can state the following

Theorem—4 Let $A(PPS)n$ be decomposable Riemannian manifold $M^n = M_1^p \times M_2^{n-p}$ for $(2 \leq p \leq n-2)$. Then the following holds

(1) If one of the decompositions is projectively flat, then it is of vanishing curvature.

(2) If 1-forms A & B vanish on the other then this decomposition is Ricci-symmetric and is projectively symmetric.

Now contracting in (3.8) over X^* and U^* , we get

$$A(\bar{Y})\{(n-p)S(\bar{Z}, \bar{V}) + r^*g(\bar{Z}, \bar{V})\} - A(\bar{Z})\{(n-p)S(\bar{Y}, \bar{V}) + r^*g(\bar{Y}, \bar{V})\} = 0 \quad (3.19)$$

Again contracting over \bar{Z} and \bar{V} , we obtain

$$A(L\bar{Y}) = \left\{ \frac{(p-1)}{(n-p)} r^* + \bar{r} \right\} A(\bar{Y}) \quad (3.20)$$

Repeating similar operation for (3.9), we have

$$\begin{aligned} 0 = & [A(\bar{X}) + B(\bar{X})]\{(n-p)S(\bar{Z}, \bar{U}) + r^*g(\bar{Z}, \bar{U})\} \\ & + A(\bar{Z})\{(n-p)S(\bar{X}, \bar{U}) + r^*g(\bar{X}, \bar{U})\} \\ & + A(\bar{U})\{(n-p)S(\bar{Z}, \bar{X}) + r^*g(\bar{Z}, \bar{X})\} \end{aligned} \quad (3.21)$$

and

$$A(\bar{X})\{(n - p)\bar{r} + (p + 2)r^*\} + B(\bar{X})\{(n - p)\bar{r} + pr^*\} + 2(n - p)A(L\bar{X}) = 0 \tag{3.22}$$

Using (3.20), we have

$$3A(\bar{X}) + B(\bar{X}) = 0 \tag{3.23}$$

Thus we can state it as follows

Theorem–5 Let (M^n, g) be decomposable Riemannian manifold $M_1^p \times M_2^{n-p}$ for $(2 \leq p \leq n - 2)$ If M is an $A(PPS)n$, then the following relations are satisfied

$$A(L\bar{X}) = \left\{ \frac{(p - 1)}{(n - p)} r^* + \bar{r} \right\} A(\bar{X})$$

and

$$3A(\bar{X}) + B(\bar{X}) = 0$$

on M_1 .

Contracting in (3.12) over \bar{Y} , \bar{X} and Z^*, V^* , respectively, we obtain

$$A(LU^*) = \left\{ r^* + \frac{(p - 1)}{p} \bar{r} \right\} A(U^*)$$

on M_2 . Hence we can state the following

Theorem–6 Let (M^n, g) be decomposable Riemannian manifold $M_1^p \times M_2^{n-p}$ for $(2 \leq p \leq n - 2)$

If M is an $A(PPS)n$, then the following relations are satisfied

$$A(LU^*) = \left\{ r^* + \frac{(p-1)}{p} \bar{r} \right\} A(U^*)$$

on M_2 .

4. The torse-forming vector field ρ

We consider an $A(PPS)n$ defined by (1.4) which is an Einstein manifold. Then its Ricci tensor S satisfies

$$S(Z, U) = \frac{r}{n} g(Z, U) \tag{4.1}$$

It follows that

$$dr(Z) = 0 \text{ and } (\nabla_X S)(Z, U) = 0 \tag{4.2}$$

We suppose that ρ is a unit-torse forming vector [19] defined by

$$\nabla_X \rho = \lambda X + \omega(X)\rho \tag{4.3}$$

where λ is a non-zero scalar and ω is a non-zero 1 –form, called the scalar and 1 –form of the vector field ρ , respectively. Some properties of torse -forming vector fields in Riemannian spaces have been studied by Rachunek and Mikes [10] and various mathematicians.

Now by (4.2), we have

$$(\nabla_X S)(Z, \rho) = 0 \quad (4.4)$$

Since $(\nabla_X S)(Z, \rho) = \nabla_X S(Z, \rho) - S(\nabla_X Z, \rho) - S(Z, \nabla_X \rho)$ and using (1.2) and (4.1), we have

$$\frac{r}{n}(\nabla_X A)(Z) - S(Z, \nabla_X \rho) = 0 \quad (4.5)$$

Substituting (4.3) in (4.5) and using (4.1), we get

$$\frac{r}{n}(\nabla_X A)(Z) - \lambda S(Z, X) - \frac{r}{n}\omega(X)A(Z) = 0 \quad (4.6)$$

Putting $Z = \rho$ in (4.6) and remembering that ρ is a unit vector, thus equation(4.6) reduces to

$$(\nabla_X A)(\rho) = \lambda A(X) + \omega(X) \quad (4.7)$$

Since ρ is a unit vector, we get

$$(\nabla_X A)(\rho) = -A(\nabla_X \rho) \quad (4.8)$$

From (4.3) and (4.8), it follows that

$$(\nabla_X A)(\rho) = -\lambda A(X) - \omega(X) \quad (4.9)$$

From(4.7) and (4.9), we get

$$\omega(X) = -\lambda A(X)$$

It means that

$$\lambda = -\omega(\rho) \quad (4.10)$$

Using (4.10) in (4.3), we have

$$\nabla_X \rho = \omega(\rho)X + \omega(X)\rho \quad (4.11)$$

Hence it follows that $\nabla_\rho \rho = 0$.

Therefore we can state it as follows

Theorem-7 If in an Einstein $A(PPS)_n$ the vector field ρ is a unit torse-forming vector field, then the integral curves of the vector ρ are geodesics.

As we know that an Einstein manifold is of constant scalar curvature, so from Theorem-2, two associated 1-forms in an Einstein $A(PPS)_n$ whose scalar curvature is non-zero are linearly dependent. Also, it follows from (1.2) and (2.6) that

$$\rho = -\left(\frac{n}{n+2}\right)Q \quad (4.12)$$

From equations (4.11) and (4.12), we can say that the vector field Q is also a torse-forming vector field. Thus from Theorem–7, the integral curves of the vector field Q are also geodesics.

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