

On D -Recurrent Spaces with Semi-Symmetric Recurrent-Metric Connection

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Abstract

The properties of Riemannian spaces admitting a semi-symmetric metric connection and semi-symmetric recurrent-metric connection were studied in [1-9]. On the other hand, the notion of the recurrent Riemannian space was introduced and studied in [7]. Furthermore, D -recurrent spaces with semi-symmetric connection were investigated in [8].

In this work, we introduce D -recurrent spaces with semi-symmetric recurrent-metric connection denoted by (M_n, g, D) and obtain some properties of the curvature tensor L_{ijk}^m of (M_n, g, D) . For such a space, it is shown that $D_l L_{ijkh} = \rho_l L_{ijkh}$, ($\rho_l \neq 0$), where L_{ijkh} is the curvature tensor corresponding to the D connection and ρ_l is a non-zero covariant vector field. Also, an example of these spaces is given.

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1 Introduction

Let (M_n, g) ($n > 2$) be an n -dimensional differentiable manifold of class C^∞ with metric tensor g , the Riemannian connection ∇ and, a smooth linear connection D on M_n .

If, for any smooth vector fields X and Y on M_n , the torsion tensor T of D satisfies the relation

$$T(X, Y) = \pi(Y)X - \pi(X)Y, \quad (1.1)$$

where π is a smooth linear differential form, then the connection D is said to be semi-symmetric [9].

If, in addition, the connection D satisfies the following condition

$$D_X g = 2\mu(X)g, \quad (1.2)$$

where μ is a smooth linear differential form, then the connection D is said to be semi-symmetric recurrent-metric ([5],[9]).

Let $\left\{ \begin{smallmatrix} m \\ ji \end{smallmatrix} \right\}$ be the coefficients of the Riemannian connection ∇ and, D a semi-symmetric recurrent-metric connection on M_n with coefficients

$$\Gamma_{ji}^m = \left\{ \begin{smallmatrix} m \\ ji \end{smallmatrix} \right\} + \delta_j^m \lambda_i - \mu_j \delta_i^m - g_{ji} \lambda^m, \quad (1.3)$$

where we put $\pi_i = \lambda_i - \mu_i$ and $\lambda^m = \lambda_t g^{tm}$ [5].

The curvature tensor L_{kji}^m of the connection D and the curvature tensor of the Riemannian connection ∇ , respectively, are defined by [5]

$$L_{kji}^m = \partial_k \Gamma_{ji}^m - \partial_j \Gamma_{ki}^m + \Gamma_{kt}^m \Gamma_{ji}^t - \Gamma_{jt}^m \Gamma_{ki}^t, \quad \left(\partial_k = \frac{\partial}{\partial x^k} \right), \quad (1.4)$$

$$R_{kji}^m = \partial_k \left\{ \begin{smallmatrix} m \\ ji \end{smallmatrix} \right\} - \partial_j \left\{ \begin{smallmatrix} m \\ ki \end{smallmatrix} \right\} + \left\{ \begin{smallmatrix} m \\ kt \end{smallmatrix} \right\} \left\{ \begin{smallmatrix} t \\ ji \end{smallmatrix} \right\} - \left\{ \begin{smallmatrix} m \\ jt \end{smallmatrix} \right\} \left\{ \begin{smallmatrix} t \\ ki \end{smallmatrix} \right\}. \quad (1.5)$$

Let $L_{kjih} = L_{kji}^m g_{mh}$ and $R_{kjih} = R_{kji}^m g_{mh}$.

Substituting (1.3) in (1.4), we obtain the following equation for the curvature tensor L_{kji}^m of M_n with the semi-symmetric recurrent-metric connection, in short (M_n, g, D) .

$$L_{kjih} = R_{kjih} + g_{jh} \lambda_{ki} - g_{kh} \lambda_{ji} + \lambda_{jh} g_{ki} - \lambda_{kh} g_{ji} + g_{ih} (\mu_{jk} - \mu_{kj}), \quad (1.6)$$

where we put

$$\lambda_{ki} = \nabla_k \lambda_i - \lambda_k \lambda_i + \frac{1}{2} g_{ki} \lambda_t \lambda^t, \quad (1.7)$$

$$\mu_{jk} = \nabla_j \mu_k - \mu_j \mu_k + \frac{1}{2} g_{jk} \mu_t \mu^t. \quad (1.8)$$

Proposition. For the curvature tensor L_{kjih} of the semi-symmetric recurrent-metric connection, the following properties hold:

$$i) \quad L_{kjih} = -L_{jkih}, \tag{1.9}$$

$$ii) \quad L_{kkih} = 0. \tag{1.10}$$

Proof. i) Interchanging the indices k and j in (1.6), we get

$$L_{jkih} = R_{jkih} + g_{kh}\lambda_{ji} - g_{jh}\lambda_{ki} + \lambda_{kh}g_{ji} - \lambda_{jh}g_{ki} + g_{ih}(\mu_{kj} - \mu_{jk}) = -L_{kjih}.$$

ii) By taking $k = j$ in (1.6), we obtain

$$L_{kkih} = R_{kkih} + g_{kh}\lambda_{ki} - g_{kh}\lambda_{ki} + \lambda_{kh}g_{ki} - \lambda_{kh}g_{ki} + g_{ih}(\mu_{kk} - \mu_{kk}) = 0.$$

Definition. The space (M_n, g, D) is called D -recurrent if there exists a non-zero covariant vector field ρ_l such that

$$D_l L_{ijk}^m = (\rho_l - 2\mu_l) L_{ijk}^m, \tag{1.11}$$

where μ_l is the component of a covariant vector field satisfying the condition of recurrent metric connection (1.2).

Lemma. If the space (M_n, g, D) is D -recurrent, then

$$D_l L_{ijkh} = \rho_l L_{ijkh}. \tag{1.12}$$

Proof. Multiplying (1.11) by g_{mh} we obtain

$$\begin{aligned} (D_l L_{ijk}^m) g_{mh} &= (\rho_l - 2\mu_l) L_{ijk}^m g_{mh} \\ &= \rho_l L_{ijk}^m g_{mh} - L_{ijk}^m (2\mu_l g_{mh}). \end{aligned}$$

Using (1.2) we get

$$(D_l L_{ijk}^m) g_{mh} + L_{ijk}^m (D_l g_{mh}) = \rho_l L_{ijk}^m g_{mh},$$

from which $D_l L_{ijkh} = \rho_l L_{ijkh}$.

In the next section, we will present an example of a D -recurrent space with semi-symmetric recurrent-metric connection that we have introduced.

2 An Example of D-Recurrent Spaces

Let each Latin index run over $1, 2, \dots, n$ and each Greek index $2, 3, \dots, n-1$. We define the metric g in (M_n, g, D) , ($n \geq 4$) by the formula [2,3]

$$ds^2 = \varphi (dx^1)^2 + k_{\alpha\beta} dx^\alpha dx^\beta + 2dx^1 dx^n, \quad (2.1)$$

where $[k_{\alpha\beta}]$ is a symmetric non-singular matrix with constant entries, φ is a scalar function and independent of x^n .

In the metric (2.1), the only non-vanishing components of the Christoffel symbols, the Riemannian curvature tensor R_{hijk} and Ricci tensor R_{ij} , respectively, are the following, [6]

$$\left\{ \begin{matrix} \beta \\ 11 \end{matrix} \right\} = -\frac{1}{2}k^{\beta\alpha}\varphi_{,\alpha}, \quad \left\{ \begin{matrix} n \\ 11 \end{matrix} \right\} = \frac{1}{2}\varphi_{,1}, \quad \left\{ \begin{matrix} n \\ 1\alpha \end{matrix} \right\} = \frac{1}{2}\varphi_{,\alpha},$$

and

$$R_{1\alpha\beta 1} = \frac{1}{2}\varphi_{,\alpha\beta}, \quad R_{11} = \frac{1}{2}k^{\alpha\beta}\varphi_{,\alpha\beta}, \quad (2.2)$$

where $(.)$ denotes the partial differentiation with respect to coordinates and $[k^{\alpha\beta}]$ is the inverse matrix of $[k_{\alpha\beta}]$.

Let's define the vector components λ_h and μ_h , which are contained in the formula of coefficients of the connection D by

$$\lambda_h = \begin{cases} \psi(x^1), & \text{for } h = 1 \\ 0, & \text{otherwise} \end{cases}, \quad \mu_h = \begin{cases} \theta(x^1), & \text{for } h = 1 \\ 0, & \text{otherwise} \end{cases}, \quad (2.3)$$

where $\psi(x^1)$ and $\theta(x^1)$ are continuous functions of x^1 on the interval $I = [a, b]$.

By using the formula (1.3), (2.2) and (2.3), we obtain the following non-zero components of Γ_{ij}^h

$$\begin{aligned} \Gamma_{11}^1 &= \left\{ \begin{matrix} 1 \\ 11 \end{matrix} \right\} + \delta_1^1 \lambda_1 - \mu_1 \delta_1^1 - g_{11} \lambda^1 = \lambda_1 - \mu_1, \\ \Gamma_{11}^\beta &= \left\{ \begin{matrix} \beta \\ 11 \end{matrix} \right\} + \delta_1^\beta \lambda_1 - \mu_1 \delta_1^\beta - g_{11} \lambda^\beta = \left\{ \begin{matrix} \beta \\ 11 \end{matrix} \right\} = -\frac{1}{2}k^{\beta\alpha}\varphi_{,\alpha}, \\ \Gamma_{1\alpha}^\alpha &= \left\{ \begin{matrix} \alpha \\ 1\alpha \end{matrix} \right\} + \delta_1^\alpha \lambda_\alpha - \mu_1 \delta_\alpha^1 - g_{1\alpha} \lambda^\alpha = -\mu_1, \\ \Gamma_{\alpha 1}^\alpha &= \left\{ \begin{matrix} \alpha \\ \alpha 1 \end{matrix} \right\} + \delta_\alpha^\alpha \lambda_1 - \mu_\alpha \delta_\alpha^1 - g_{\alpha 1} \lambda^\alpha = \lambda_1, \\ \Gamma_{1\alpha}^\beta &= \left\{ \begin{matrix} \beta \\ 1\alpha \end{matrix} \right\} + \delta_1^\beta \lambda_\alpha - \mu_1 \delta_\alpha^\beta - g_{1\alpha} \lambda^\beta = \begin{cases} -\mu_1, & \text{for } \alpha = \beta \\ 0, & \alpha \neq \beta \end{cases}, \end{aligned}$$

$$\begin{aligned}
 \Gamma_{\alpha 1}^{\beta} &= \left\{ \begin{matrix} \beta \\ \alpha 1 \end{matrix} \right\} + \delta_{\alpha}^{\beta} \lambda_1 - \mu_{\alpha} \delta_1^{\beta} - g_{\alpha 1} \lambda^{\beta} = \begin{cases} \lambda_1, & \text{for } \alpha = \beta \\ 0, & \alpha \neq \beta \end{cases}, \\
 \Gamma_{11}^n &= \left\{ \begin{matrix} n \\ 11 \end{matrix} \right\} + \delta_1^n \lambda_1 - \mu_1 \delta_1^n - g_{11} \lambda^n = \left\{ \begin{matrix} n \\ 11 \end{matrix} \right\} = \frac{1}{2} \varphi_{.1} - \lambda_1 \varphi, \\
 \Gamma_{1\alpha}^n &= \left\{ \begin{matrix} n \\ 1\alpha \end{matrix} \right\} + \delta_1^n \lambda_{\alpha} - \mu_1 \delta_{\alpha}^n - g_{1\alpha} \lambda^n = \left\{ \begin{matrix} n \\ 1\alpha \end{matrix} \right\} = \frac{1}{2} \varphi_{.\alpha}, \\
 \Gamma_{\alpha 1}^n &= \left\{ \begin{matrix} n \\ \alpha 1 \end{matrix} \right\} + \delta_{\alpha}^n \lambda_1 - \mu_{\alpha} \delta_1^n - g_{\alpha 1} \lambda^n = \left\{ \begin{matrix} n \\ \alpha 1 \end{matrix} \right\} = \frac{1}{2} \varphi_{.\alpha}, \\
 \Gamma_{1n}^n &= \left\{ \begin{matrix} n \\ 1n \end{matrix} \right\} + \delta_1^n \lambda_n - \mu_1 \delta_n^n - g_{1n} \lambda^n = -\mu_1 - \lambda_1, \\
 \Gamma_{\alpha\alpha}^n &= \left\{ \begin{matrix} n \\ \alpha\alpha \end{matrix} \right\} + \delta_{\alpha}^n \lambda_{\alpha} - \mu_{\alpha} \delta_{\alpha}^n - g_{\alpha\alpha} \lambda^n = -\lambda_1.
 \end{aligned} \tag{2.4}$$

Substituting (2.3) in the formula of λ_{jk} and μ_{jk} and using (2.2) we see that the only non-zero components are

$$\lambda_{11} = \nabla_1 \lambda_1 - \lambda_1 \lambda_1 = \frac{\partial \lambda_1}{\partial x^1} - \lambda_{\alpha} \left\{ \begin{matrix} \alpha \\ 11 \end{matrix} \right\} - \lambda_1^2 = \psi'(x^1) - \psi^2(x^1), \tag{2.5}$$

$$\mu_{11} = \nabla_1 \mu_1 - \mu_1 \mu_1 = \frac{\partial \mu_1}{\partial x^1} - \mu_{\alpha} \left\{ \begin{matrix} \alpha \\ 11 \end{matrix} \right\} - \mu_1^2 = \theta'(x^1) - \theta^2(x^1). \tag{2.6}$$

Recall that the covariant derivatives of the tensors λ_{ij} and μ_{ij} with respect to the connection D are given

$$D_k \lambda_{ij} = \frac{\partial \lambda_{ij}}{\partial x^k} - \lambda_{aj} \Gamma_{ik}^a - \lambda_{ia} \Gamma_{jk}^a, \quad D_k \mu_{ij} = \frac{\partial \mu_{ij}}{\partial x^k} - \mu_{aj} \Gamma_{ik}^a - \mu_{ia} \Gamma_{jk}^a.$$

One can easily show that the only non-zero components $D_l \lambda_{11}$ and $D_l \mu_{11}$ are

$$\begin{aligned}
 D_1 \lambda_{11} &= (\psi'' - 2\psi \psi') - 2(\psi' - \psi^2)(\psi - \theta), \\
 D_1 \mu_{11} &= (\theta'' - 2\theta \theta') - 2(\theta' - \theta^2)(\psi - \theta).
 \end{aligned} \tag{2.7}$$

For the metric (2.1),

if we consider $k_{\alpha\beta}$ as $\delta_{\alpha\beta}$ and $\varphi = k_{\alpha\beta} x^{\alpha} x^{\beta} (x^1)^4 e^{\int_a^{x^1} (4\psi(t) - 2\theta(t)) dt}$, $x^1 \in I = [a, b]$,

then we obtain

$$\varphi = \sum_{\alpha=2}^{n-1} x^{\alpha} x^{\alpha} (x^1)^4 e^{\int_a^{x^1} (4\psi(t) - 2\theta(t)) dt}, \quad x^1 \in I. \tag{2.8}$$

Hence,

$$\varphi_{.\alpha\alpha} = 2(x^1)^4 e^{\int_a^{x^1} (4\psi(t)-2\theta(t))dt}, \quad \text{and } \varphi_{.\alpha\beta} = 0 \text{ for } \alpha \neq \beta. \quad (2.9)$$

It follows from (2.2) and (2.8) that the only non-zero components of R_{hijk} are

$$R_{1\alpha\alpha 1} = (x^1)^4 e^{\int_a^{x^1} (4\psi(t)-2\theta(t))dt}. \quad (2.10)$$

On the other hand, by using the covariant derivative of the curvature tensor with respect to the connection D , we find

$$D_l L_{hijk} = \frac{\partial L_{hijk}}{\partial x^l} - L_{aijk} \Gamma_{hl}^a - L_{hajk} \Gamma_{il}^a - L_{haij} \Gamma_{kl}^a - L_{hija} \Gamma_{kl}^a.$$

Also, by means of (2.4) and (2.9), it can be easily shown that the only non-zero components of $D_l R_{hijk}$ are

$$D_1 R_{1\alpha\alpha 1} = 4(x^1)^3 e^{\int_a^{x^1} (4\psi(t)-2\theta(t))dt}. \quad (2.11)$$

Substituting (2.5), (2.6), (2.9), and (2.10) in (1.11), we obtain the non-zero components of the curvature tensor L_{hijk} and their covariant derivatives with respect to the connection D as follows

$$\begin{aligned} L_{1\alpha 1\alpha} &= R_{1\alpha 1\alpha} + g_{\alpha\alpha} \lambda_{11}, \\ L_{\alpha 11\alpha} &= -L_{1\alpha 1\alpha} = R_{\alpha 11\alpha} - g_{\alpha\alpha} \lambda_{11}, \\ L_{1\alpha\alpha 1} &= R_{1\alpha\alpha 1} - g_{\alpha\alpha} \lambda_{11}, \\ L_{\alpha 1\alpha 1} &= -L_{1\alpha\alpha 1} = R_{\alpha 1\alpha 1} + g_{\alpha\alpha} \lambda_{11}, \\ L_{1n11} &= -\lambda_{11}, \\ L_{n111} &= -L_{1n11} = \lambda_{11}, \end{aligned} \quad (2.12)$$

$$\begin{aligned} D_k L_{1\alpha 1\alpha} &= D_k R_{1\alpha 1\alpha} + D_k(g_{\alpha\alpha} \lambda_{11}) = \begin{cases} D_1 R_{1\alpha 1\alpha} + D_1(g_{\alpha\alpha} \lambda_{11}), & k = 1 \\ 0, & k \neq 1 \end{cases}, \\ D_k L_{\alpha 11\alpha} &= D_k R_{\alpha 11\alpha} - D_k(g_{\alpha\alpha} \lambda_{11}) = \begin{cases} D_1 R_{\alpha 11\alpha} - D_1(g_{\alpha\alpha} \lambda_{11}), & k = 1 \\ 0, & k \neq 1 \end{cases}, \\ D_k L_{1\alpha\alpha 1} &= D_k R_{1\alpha\alpha 1} - D_k(g_{\alpha\alpha} \lambda_{11}) = \begin{cases} D_1 R_{\alpha\alpha 1} - D_1(g_{\alpha\alpha} \lambda_{11}), & k = 1 \\ 0, & k \neq 1 \end{cases}, \\ D_k L_{\alpha 1\alpha 1} &= D_k R_{\alpha 1\alpha 1} + D_k(g_{\alpha\alpha} \lambda_{11}) = \begin{cases} D_1 R_{\alpha 1\alpha 1} + D_1(g_{\alpha\alpha} \lambda_{11}), & k = 1 \\ 0, & k \neq 1 \end{cases}, \\ D_k L_{1n11} &= -D_k \lambda_{11} = \begin{cases} -D_1 \lambda_{11}, & k = 1 \\ 0, & k \neq 1 \end{cases}, \\ D_k L_{n111} &= D_k \lambda_{11} = \begin{cases} D_1 \lambda_{11}, & k = 1 \\ 0, & k \neq 1. \end{cases} \end{aligned} \quad (2.13)$$

Since $D_l R_{1\alpha\alpha 1} = 0$ and $D_l \lambda_{11} = 0$ for $l \neq 1$, we observe that $D_l L_{hijk} = 0$ for $l \neq 1$.

Moreover, using the metric recurrency condition we obtain

$$D_1 g_{11} = 2\mu_1 g_{11}, \tag{2.14}$$

$$D_1 g_{1n} = 2\mu_1 g_{1n}, \tag{2.15}$$

from which we get

$$\varphi_{.1} - 2\varphi\psi = 0, \tag{2.16}$$

$$\theta = -\psi. \tag{2.17}$$

If we suppose that $\rho = (-4/x^1, 0, 0, \dots, 0)$, ($x^1 \neq 0$) then D -recurrency condition (1.12) reduces to $D_1 L_{hijk} = \rho_1 L_{hijk}$ which gives the following equations

$$D_1 (g_{\alpha\alpha} \lambda_{11}) = \rho_1 g_{\alpha\alpha} \lambda_{11}, \tag{2.18}$$

$$D_1 R_{1\alpha\alpha 1} = \rho_1 R_{1\alpha\alpha 1}. \tag{2.19}$$

Substituting (2.5), (2.6) and (2.17) in (2.18) we obtain the following differential equation

$$\psi'' - 4\psi\psi' + 2\psi^3 = 0, \tag{2.20}$$

where $(')$ denotes the derivative with respect to x^1 .

Let us consider the transformations

$$\psi' = \phi \tag{2.21}$$

$$\psi'' = \dot{\phi} \phi \tag{2.22}$$

then the differential equation (2.20) takes the form

$$\dot{\phi} \phi - 4\psi \phi + 2\psi^3 = 0, \tag{2.23}$$

where $\dot{\phi} = d\phi/d\psi$.

When we compare (2.23) with Abel's equation of the 2nd kind it is seen that [10]

$$\begin{aligned} \phi \dot{\phi} &= P(\psi) \phi + Q(\psi), \\ P &= 4\psi, \quad Q = -2\psi^3. \end{aligned} \tag{2.24}$$

After transformations

$$\phi = \psi^2 \kappa(\psi), \quad \zeta = \ln \psi \tag{2.25}$$

and by using the derivative of κ with respect to ζ

$$\frac{d\kappa}{d\zeta} = \frac{\kappa_\psi}{\zeta_\psi} = \psi \left[\frac{\dot{\phi}}{\psi^2} - \frac{2\phi}{\psi^3} \right] \quad (2.26)$$

we have the separable differential equation

$$\frac{d\kappa}{d\zeta} = 4 - \frac{2}{\kappa} - 2\kappa = -\frac{2}{\kappa} (\kappa - 1)^2. \quad (2.27)$$

We can solve the above differential equation for ζ as

$$\zeta = \frac{1}{2} \left[\frac{1}{\kappa - 1} - \ln(\kappa - 1) \right] + C_1, \quad \kappa \neq 1 \quad (2.28)$$

and by replacing $\kappa = \phi/\psi^2$ and $\zeta = \ln \psi$ we find the following first order ODE

$$\ln \psi = \frac{1}{2} \left[\frac{1}{\psi'/\psi^2 - 1} - \ln\left(\frac{\psi'}{\psi^2} - 1\right) \right] + C_1 \quad (2.29)$$

with an arbitrary integration constant C_1 .

After arranging the above equation according to ψ and ψ' , the solution takes the form

$$\frac{\psi^2}{\psi' - \psi^2} = \ln[C_1(\psi' - \psi^2)] \quad (2.30)$$

and this equation needs to be integrated once more to find the general solution. However, it is not possible to solve it explicitly for ψ' . So, we take a particular solution for the choice, $\kappa = 1$ in (2.27) and this leads to the solution

$$\psi(x^1) = -\frac{1}{x^1 + c} = -\theta, \quad x^1 \neq -c, \quad (2.31)$$

where c is a constant.

Finally, we have determined the functions ψ and θ , therefore, the connection coefficients are determined such that the metric recurrency condition (1.2) and D -recurrency condition (1.12) are satisfied for the space (M_n, g, D) , having the metric (2.1).

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