

A Simple Note about Matrices Symmetric in Signs

Gregory L. Light

Providence College, Providence
Rhode Island 02918 U.S.A.
glight@providence.edu

Abstract

This paper proves that any real matrix symmetric in signs, $\{+, -, 0\}$, has no pure imaginary eigenvalues, so that if it is also of full rank, then it is hyperbolic – information useful in dynamical systems.

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1 Introduction

This short note is concerned with the eigenvalues of real matrices with symmetric sign patterns, which will henceforth be denoted by H . The study of general "sign pattern matrices" - - that is, matrices that are distinguished only by the signs of their entries, $\{+, -, 0\}$ - - has been in existence for decades (*cf.* [1, 3]), with a recently renewed interest due to the M-theory in quantum physics (see, e.g., [5]); major research interests on such "qualitative matrices" have been about the properties of positive matrices or the conditions of matrix invertibility (*see, e.g.*, [4, 6]). Our $\{H\}$ here actually contain positive matrices as a special case.

We will show that such matrices $\{H\}$ can not have eigenvalues that lie on the imaginary axis of the complex-plane, except possibly at the point of origin. Our motivation here is that, if of full rank, $\{H\}$ are then hyperbolic, which is a theme of interest in the study of dynamical systems (*cf., e.g.*, [2], 107).

Section 2 below will derive the proposition, and Section 3 will draw a summary.

2 The Proposition

Definition 1 A matrix $H_{n \times n}$ will be termed (here in this paper by the author) "quasi-hyperbolic" if each of its eigenvalues $\lambda_j, j = 1, \dots, n$, satisfies $\lambda_j^2 \notin (-\infty, 0)$; if in addition $\lambda_j \neq 0, \forall j = 1, \dots, n$, then H is (as defined in the textbook) hyperbolic.

Proposition 1 Assume that matrix $H_{n \times n}$ is symmetric in signs, i.e., $\text{sgn} h_{ij} = \text{sgn} h_{ji} \in \{1, -1, 0\} \forall i \forall j \in \{1, \dots, n\}$. Then $H_{n \times n}$ is quasi-hyperbolic.

Proof. Let $H \equiv (h_{ij})_{n \times n}$ be as assumed. Let $\epsilon > 0$, and $\hat{I} \equiv (\hat{\delta}_{ij})_{n \times n}$ with

$$\hat{\delta}_{ij} := 10^{-\kappa} \delta_{ij}, \quad \kappa \equiv \frac{\delta_{1j}}{\epsilon}. \text{ (Kronecker delta)} \tag{1}$$

Consider $\tilde{H} \equiv (\tilde{h}_{ij}) := \hat{I} H \hat{I}^{-1}$, which shares the same set of eigenvalues as H . Let $\mathbf{b} \equiv (b_i)_{n \times 1} \in \mathbb{R}^n$, and consider $\mathbf{e}_1 \tilde{H}^2 \mathbf{b}$, where $\mathbf{e}_1 \equiv (\delta_{1j})_{1 \times n}$. We have:

$$\begin{aligned} \mathbf{e}_1 \tilde{H}^2 \mathbf{b} &= \left(\sum_{j=1}^n h_{1j} h_{j1}, \quad \hat{\delta}_{11} \sum_{j=1}^n h_{1j} h_{j2}, \quad \dots, \quad \hat{\delta}_{11} \sum_{j=1}^n h_{1j} h_{jn} \right) \mathbf{b} \\ &= b_1 \sum_{j=1}^n h_{1j} h_{j1} + \hat{\delta}_{11} \left(\sum_{i=2}^n b_i \sum_{j=1}^n h_{1j} h_{ji} \right); \end{aligned} \tag{2}$$

choose ϵ and thus $\hat{\delta}_{11}$ small; since $\sum_{j=1}^n h_{1j} h_{j1} \geq 0$, we have $\text{sgn}(\mathbf{e}_1 \tilde{H}^2 \mathbf{b}) \cdot \text{sgn}(b_1) \geq 0$; thus, $\tilde{H}^2 \equiv \hat{I} H^2 \hat{I}^{-1}$ has no negative eigenvalues, and hence H has no eigenvalues $\pm ri \forall r > 0$; i.e., H is quasi-hyperbolic. ■

Example 1 As a simple illustration, consider the matrix

$$\begin{pmatrix} 1 & a \\ b & -1 \end{pmatrix}, \tag{3}$$

which has eigenvalues

$$\lambda = \pm \sqrt{1 + ab}; \tag{4}$$

thus, $\lambda^2 < 0$ implies that $ab < 0$.

Remark 1 Since H has no pure imaginary eigenvalues, any continuous sign-preserving rank-preserving transformation of H must leave all the eigenvalues of H staying on the same side of the imaginary axis on the complex-plane. As such, if H represents a linearized dynamical system around an equilibrium point, then its stability properties also remain invariant under such transformations. Two particular cases here are: (1) (small) perturbation of H ; (2) multiplication of H by a positive diagonal matrix - - a standard modeling of price dynamics in economics.

3 Summary

The study of qualitative matrices has been a special field in linear algebra for decades. Our paper here has contributed to the knowledge of a special class of matrices $\{H\}$; as many relations are mutual, $\{H\}$, being symmetric in signs, constitute a large class of matrix modeling in applications. Furthermore, once a matrix H is ascertained to be of full rank, then it is hyperbolic - - some information that is very pertinent to dynamical systems.

4 References

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