

ON SOME INTEGRODIFFERENTIAL EQUATIONS OF FRACTIONAL ORDERS

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Abstract

In this note the solutions of some integrodifferential equations with fractional orders in a Banach space are considered. Conditions are given which ensure the existence of a resolvent operator for an integrodifferential equation in a Banach space.

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1. Introduction

In this note we shall be concerned with the fractional integrodifferential equation of the form

$$\frac{d^\alpha x(t)}{dt^\alpha} - Ax(t) = \int_0^t B(t-s)x(s)ds + f(t), \quad t > 0 \quad (1.1)$$

with the initial condition

$$x(0) = x_0 \in X. \quad (1.2)$$

where X is a Banach space, $0 < \alpha \leq 1$, A is a linear closed operator defined on a dense set $D(A)$ in X into X , $[B(t) : 0 \leq t \leq T_1]$ is a family of linear closed

operator defined on a dense set in X into X with domain at least $D(A)$ while the function $f : R^+ \rightarrow X$ is absolutely continuous.

Without loss of generality we can assume that $x_0 = 0$. It is assumed also that A generates an analytic semigroup $Q(t)$. This condition implies $\|Q(t)\| \leq K$ for $t \geq 0$ and $\|AQ(t)\| \leq K/t$ for $t > 0$, where $\|\cdot\|$ is the norm in X and K is a positive constant [1-6]. It is also assumed that $x_0 \in D(A)$ and $B(t)x$ is strongly continuously differentiable on $[0, T]$ for $x \in D(A)$. It is further assumed that $[T(t)]_{t \geq 0}$ defined by $T(t)f(s) = f(t+s)$ is a C_0 semigroup on \mathfrak{N} with generator D_s on domain $D(D_s)$ where \mathfrak{N} is a subspace of the set of bounded uniformly continuous functions on R^+ into X . Let us suppose that $B(t), B'(t) : Y \rightarrow D(D_s)$ where Y is the Banach space formed from $D(A)$, the domain of A , endowed with the graph norm $\|y\|_Y = \|Ay\| + \|y\|$. As A and $B(t)$ are closed operators it follows that A and $B(t)$ are in the set of bounded operators from Y to X $B(Y, X)$ for $0 < t \leq T$ assume further that $B(t)$ is continuous on $0 < t \leq T$ into $B(Y, X)$. It is also supposed that $D_s B(t), D_s B'(t)$ is continuous on $[0, \infty)$ into $B(Y, \mathfrak{N})$ [7]. The theory of fractional calculus is essentially based on the integral convolution between f^* and the following generalized function, introduced by Gelfand and Shilov, $\phi_\lambda(t) = t_+^\lambda / \Gamma(\lambda)$, where λ is a complex number, $t_+^\lambda = t^\lambda \theta(t)$, $\theta(t)$ being the Heaviside step function, and $\Gamma(\lambda)$ is the gamma function.

Following Gelfand and Shilov we can define the integral of order $\alpha > 0$ by

$$I^\alpha f^*(t) = \frac{1}{\Gamma(\alpha)} \int_0^t (t - \theta)^{\alpha-1} f^*(\theta) d\theta. \quad (1.3)$$

If $0 < \alpha \leq 1$, we can define the derivative of order α by

$$\frac{d^\alpha f^*(t)}{dt^\alpha} = \frac{1}{\Gamma(1 - \alpha)} \frac{d}{dt} \int_0^t \frac{f^*(\theta)}{(t - \theta)^\alpha} d\theta, \quad (1.4)$$

(see [8-10]). If $n - 1 < \alpha < n$, then it is easy to see that

$$\frac{d^\alpha f^*(t)}{dt^\alpha} = \frac{1}{\Gamma(n - \alpha)} \int_0^t \frac{f^{*(n)}(\theta)}{(t - \theta)^{\alpha+1-n}} d\theta + \sum_{k=0}^n f^{*(k)}(0^+) \phi_{k-\alpha+1}(t), \quad (1.5)$$

where

$$\frac{d^\alpha f^*(t)}{dt^\alpha} = \frac{d^{n-1}}{dt^{n-1}} I^{n-\alpha} f^*(t) = \frac{1}{\Gamma(n-\alpha)} \frac{d^n}{dt^n} \int_0^t \frac{f^*(\theta)}{(t-\theta)^{\alpha+1-n}} d\theta, \tag{1.6}$$

(comp[11-13])

We shall first consider the fractional evolution equation of the form

$$\frac{d}{dt} \left(\frac{d^\alpha x(t)}{dt^\alpha} - Ax(t) \right) = B_1 x(t) + \int_0^t B_2(t-s)x(s)ds + f(t) \tag{1.7}.$$

with the initial conditions

$$x(0) = 0, \quad \frac{dx(0)}{dt} = 0. \tag{1.8}$$

then we obtain the solution of the problem (1.1),(1.2).Finally an application is considered

2.Existence of solutions

Theorem 2.1

Assume that B_1 and $B_2(t)$ are closed linear operators defined on dense sets in X into X with domains at least $D(A)$,and $B_2(t)x$ is strongly continuous in t on $[0,T]$ for $x \in D(A)$.It is also assumed that the domain of $B_2(t)$ does not depend on t .If $B_1, B_2(t) : Y \rightarrow D(D_s)$ and $f_1 : R^+ \rightarrow X$ is continuous,then the problem (1.7),(1.8) has a unique solution

$$x(t) = \alpha \int_0^t \int_0^\eta \int_0^\infty \theta \zeta_\alpha(\theta) (t-\eta)^{\alpha-1} Q((t-\eta)^\alpha \theta) R(\eta-v) f(v) d\theta dv d\eta. \tag{2.1}$$

Proof:

First we assume that

$$\frac{d^\alpha x(t)}{dt^\alpha} - Ax(t) = U(t). \tag{2.2}$$

Hence formally, from [14]:

$$x(t) = \alpha \int_0^t \int_0^\infty \theta \zeta_\alpha(\theta) (t - \eta)^{\alpha-1} Q((t - \eta)^\alpha \theta) U(\eta) d\theta d\eta, \quad (2.3)$$

where $\zeta_\alpha(\theta)$ is a probability density function defined on $(0, \infty)$. From (1.7), (1.8), (2.2) and (2.3) we get

$$\begin{aligned} \frac{dU(t)}{dt} &= \alpha \int_0^t \int_0^\infty \theta \zeta_\alpha(\theta) (t - \eta)^{\alpha-1} B_1 Q((t - \eta)^\alpha \theta) U(\eta) d\theta d\eta \\ &+ \alpha \int_0^t \int_0^\phi \int_0^\infty \theta \zeta_\alpha(\theta) B_2 (t - \phi) (\phi - \eta)^{\alpha-1} Q((\phi - \eta)^\alpha \theta) U(\eta) d\theta d\eta d\phi \\ &+ f_1(t), \end{aligned} \quad (2.4)$$

$$U(0) = 0. \quad (2.5)$$

We rewrite equation (2.4) as

$$\begin{aligned} \frac{dU(t)}{dt} &= \int_0^t B_3(t - \eta) U(\eta) d\eta + \int_0^t B_4(t - \eta) U(\eta) d\eta + f_1(t) \\ &= \int_0^t B_5(t - \eta) U(\eta) d\eta + f_1(t), \end{aligned} \quad (2.6)$$

where

$$\begin{aligned} B_3(t - \eta) &= \alpha \int_0^\infty \theta \zeta_\alpha(\theta) (t - \eta)^{\alpha-1} B_1 Q((t - \eta)^\alpha \theta) d\theta, \\ B_4(t - \eta) &= \alpha \int_\eta^t \int_0^\infty \theta \zeta_\alpha(\theta) B_2 (t - \phi) (\phi - \eta)^{\alpha-1} Q((\phi - \eta)^\alpha \theta) d\theta d\phi, \\ B_5(t - \eta) &= B_3(t - \eta) + B_4(t - \eta). \end{aligned} \quad (2.7)$$

Equation(2.6)has a unique resolvent operator $R(t)$ which satisfies

$$\frac{\partial R(t - \eta)}{\partial t} = \int_\eta^t B_5(t - r) R(r - \eta) dr. \quad (2.8)$$

Then equations (2.5),(2.6) has a unique solution

$$U(t) = \int_0^t R(t - \eta) f(\eta) d\eta. \quad (2.9)$$

By differentiating (2.9) and using (2.8).Hence by Fubini's theorem we obtain (2.4).

Then

$$x(t) = \alpha \int_0^t \int_0^\eta \int_0^\infty \theta \zeta_\alpha(\theta) (t - \eta)^{\alpha-1} Q((t - \eta)^\alpha \theta) R(\eta - v) f(v) d\theta dv d\eta.$$

Theorem 2.2

The problem (1.1),(1.2) has a unique solution

$$x(t) = \alpha \frac{d}{dt} \int_0^t \int_0^\eta \int_0^\infty \theta \zeta_\alpha(\theta) (t-\eta)^{\alpha-1} Q((t-\eta)^\alpha \theta) R_1(\eta-v) f(v) d\theta dv d\eta. \tag{2.10}$$

Proof:

Let $v(t) = \int_0^t x(\theta) d\theta$.

We can rewrite equation (1.1),(1.2) as

$$\begin{aligned} \frac{d}{dt} \left(\frac{d^{\alpha} v}{dt^{\alpha}} - Av(t) \right) &= \int_0^t B(t-s) \frac{dv}{ds} ds + f(t) \\ &= B(0)v(t) + \int_0^t B'(t-s)v(s) ds + f(t), \end{aligned} \tag{2.11}$$

$$\frac{dv(0)}{dt} = 0. \tag{2.12}$$

By using the previous theorem ,we get

$$v(t) = \alpha \int_0^t \int_0^\eta \int_0^\infty \theta \zeta_\alpha(\theta) (t-\eta)^{\alpha-1} Q((t-\eta)^\alpha \theta) R_1(\eta-v) f(v) d\theta dv d\eta, \tag{2.13}$$

where

$$\begin{aligned} \frac{\partial R_1(t-\eta)}{\partial t} &= \alpha \int_\eta^t \int_0^\infty \theta \zeta_\alpha(\theta) B(0) (t-r)^{\alpha-1} Q((t-r)^\alpha \theta) d\theta dr \\ &+ \alpha \int_\eta^t \int_\eta^\phi \int_0^\infty \theta \zeta_\alpha(\theta) B'(t-\phi) (\phi-r)^{\alpha-1} Q((\phi-r)^\alpha \theta) d\theta d\phi dr. \end{aligned}$$

Hence the required result .

3.Application

As an application we consider the following equation:

$$\frac{\partial^{\alpha} u(x, t)}{\partial t^{\alpha}} - \sum_{|q| \leq 2m} a_q(x) D^q u(x, t) = \int_0^t \sum_{|q| \leq k} b_q(x, t-s) D^q u(x, s) ds + f(x, t), t > 0 \tag{3.1}$$

with the initial condition

$$u(x, 0) = u_0(x). \quad (3.2)$$

where $x = (x_1, \dots, x_n) \in S$, S is a bounded domain in the n - dimensional Euclidean space R^n with smooth boundary ∂S , let $L^2(S)$ be the set of all square integrable functions on S . Denote by $C^m(S)$ the set of all continuous functions defined on S , which have continuous partial derivatives of order less than or equal to m , and by $C_0^m(S)$ we denote the set of all functions $f \in C^m(S)$ with compact support. Let $H^m(S)$ be the completion of the space $C^m(S)$ with respect to the norm $\|f\|_m$,

$$\|f\|_m = \left[\sum_{|q| \leq m} \int_S [D^q f(x)]^2 dx \right]^{1/2}.$$

By $H_0^m(S)$ we denote the completion of the space $C_0^m(S)$ with respect to the norm $\|f\|_m$. Let A and B be the differential operators defined by

$$A = \sum_{|q| \leq 2m} a_q(x) D^q, \quad B = \sum_{|q| \leq k} b_q(x, t) D^q.$$

It is assumed that:

- (1) The domain of definition $D(A)$ of A is defined by $D(A) = H^{2m}(S) \cap H_0^m$.
- (2) $(-1)^{m-1} \sum_{|q|=2m} a_q(x) \xi^q \geq \delta |\xi|^{2m}$, for all $x \in S \cup \partial S$ and for all $\xi = (\xi_1, \dots, \xi_n) \neq (0, \dots, 0)$, where δ is a positive constant independent of x and ξ , ($|\xi|^2 = \xi_1^2 + \dots + \xi_n^2$, $\xi^q = \xi_1^{q_1} \dots \xi_n^{q_n}$).
- (3) The coefficients a_q are continuous on S , for all $|q| \leq 2m$ and the coefficients on $S \times [0, T]$, for all $|q| \leq k$, where $T > 0$.
- (4) f is continuous on $S \times [0, T]$.

Under these conditions the differential operator A generates an analytic semi-group $Q(t)$, where:

$$Q(t)u_0 = \int_{R^n} G(x - \xi, t) u_0(\xi) d\xi,$$

where $d\xi = d\xi_1 \dots d\xi_n$ and G is the fundamental solution of the Cauchy problem:

$$\frac{\partial u(x, t)}{\partial t} = \sum_{|q| \leq 2m} a_q(x) D^q u(x, t),$$

$$u(x, 0) = u_0(x)$$

Now as an application of theorem 2.2, we can prove that the Cauchy problem (3.1),(3.2) has a unique solution.

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