

Option Pricing Model with Stepped Payoff

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Abstract

This paper shows how to obtain a valuation for an exotic call option using the well-known Black-Scholes model. The financial derivative that we will consider here is constructed from a European call option or (vanilla call option), where we have changed the final payment $S - K$ by one defined from a stepped function. Once the theoretical price of the contract has been determined, some specific cases are analyzed.

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1 Introduction

In May 1973 the economists Fisher Black and Myron Scholes published an paper in the Journal of Political Economy entitled "The Pricing of Options and Corporate Liabilities" [2], which is considered by many as the greatest theoretical support of the great industry of the financial markets, see [3, 6, 10]. Is defined as an exotic option any contract, which differs in some term of the European option or vanilla option. In recent years, a great variety of these instruments have been created and are currently traded in the different stock markets around the world. To evaluate these instruments, many methods have been proposed, see [4, 7, 11]. Some of them use numerical methods [1, 5], in others we can find written solutions in terms of non-elementary functions.

In this paper, a contract with a stepped payoff that allows a fairly flexible level of risk exposure, which depends on the risk profiles of the two contract parties, the buyer and the writer is shown.

This paper is divided into 5 sections. In the second section an option is modeled with a constant payoff; in the third section the main model is proposed, which is the objective of the paper; in the fourth section some examples are presented and finally in the last section some comments of the study are made.

2 Call option with a constant payoff

Let $V(S, t)$ be a non-negative function, that represents the price of a call option on an asset where, $S > 0$ is the price of the underlying asset, $0 \leq t \leq T$ is the time that elapses from the moment the contract is issued, $K > 0$ is the strike price, $T > 0$ is the Time to Expiration and $f(s)$ the payoff received by the contract holder if this is exercised at time T . As we can see, in this way we have defined an exotic option based on a european call option, where the final payment is expressed generically with a function of S . Suppose also that here also all the conditions that are required in the Black-Scholes model [2] are fulfilled. So the following model allows us to find the fair price of the call option.

$$\left. \begin{aligned} \frac{\partial V}{\partial t} + \frac{1}{2}\sigma^2 S^2 \frac{\partial^2 V}{\partial S^2} + rS \frac{\partial V}{\partial S} - rV &= 0 \\ V(S, T) &= f(S) \end{aligned} \right\} \quad (2.1)$$

Where r and σ positive constants, correspond respectively to risk-free rate and volatility of the underlying asset. Note that if in (2.1) we do $f(S) = S - K$, we have the classic model for a vanilla option developed by Black and Scholes in [2]. For this reason we have called this contract "call option", although in the strict sense it is not. Now let's see what is the fair pricing of a binary option, see [6].

Theorem 2.1. *Be $V(S, t)$ the price of the call option defined in (2.1) with payoff $f(S)$ given by,*

$$f(S) = V(S, T) = \begin{cases} 0 & \text{if } S < K \\ L & \text{if } S \geq K \end{cases}$$

where L is a positive real number, then $V(S, t)$ can be expressed as,

$$V(S, t) = L e^{-r(T-t)} \Phi \left(\frac{\ln \left(\frac{S}{K} \right) + \left(r - \frac{1}{2}\sigma^2 \right) (T-t)}{\sigma \sqrt{T-t}} \right),$$

Where Φ is the normal standard distribution.

Proof. To start in the equation (2.1) let's do:

$$w(x, \tau) = \frac{1}{K}V(S, t), \quad x = \ln\left(\frac{S}{K}\right), \quad \tau = \frac{1}{2}\sigma^2(T - t) \quad \text{and} \quad \lambda = \frac{2r}{\sigma^2} \quad (2.2)$$

Now, since $\tau(T) = 0$ the boundary condition $V(S, T)$ becomes the initial condition,

$$w(x, 0) = \begin{cases} 0 & \text{if } x < 0 \\ \frac{L}{K} & \text{if } x \geq 0 \end{cases} \quad (2.3)$$

And consequently problem becomes,

$$\left. \begin{aligned} \frac{\partial w}{\partial \tau} - \frac{\partial^2 w}{\partial x^2} - (\lambda - 1)\frac{\partial w}{\partial x} + \lambda w &= 0, \quad x \in \mathbb{R}, \quad \tau \in \left[0, T\frac{\sigma^2}{2}\right] \\ w(x, 0) &= \begin{cases} 0 & \text{if } x < 0 \\ \frac{L}{K} & \text{if } x \geq 0 \end{cases} \end{aligned} \right\} \quad (2.4)$$

Now, let's make the following substitution,

$$w(x, \tau) = e^{-\frac{\lambda-1}{2}x - \frac{(\lambda+1)^2}{4}\tau} u(x, \tau), \quad (2.5)$$

so, the initial condition of (2.4) becomes:

$$u(x, 0) = u_0(x) = \frac{L}{K}e^{(\frac{\lambda-1}{2})x}, \quad \text{if } x \geq 0, \quad \text{and } 0, \quad \text{if } x < 0$$

and most importantly, problem (2.4) is transformed into the widely known model of heat equation.

$$\left. \begin{aligned} \frac{\partial u}{\partial \tau} &= \frac{\partial^2 u}{\partial x^2}, \quad \text{with } x \in \mathbb{R}, \quad \text{and } \tau \in \left[0, T\frac{\sigma^2}{2}\right] \\ u(x, 0) &= u_0(x) = \begin{cases} 0 & \text{if } x < 0 \\ \frac{L}{K}e^{(\frac{\lambda-1}{2})x} & \text{if } x \geq 0 \end{cases} \end{aligned} \right\} \quad (2.6)$$

As we can see in [9], a solution to problem (2.6) is given by:

$$u(x, \tau) = \frac{1}{2\sqrt{\pi\tau}} \int_{-\infty}^{\infty} u_0(y) e^{-\frac{(x-y)^2}{4\tau}} dy \quad (2.7)$$

Now, to express the solution given in (2.7) in a simple way, let's fix x and make the following substitution, $y = v\sqrt{2\tau} + x$, therefore $dy = \sqrt{2\tau} dv$. In addition, considering that u_0 is canceled when his argument is negative, we have to $x + v\sqrt{2\tau} > 0$ and consequently of (2.7) it follows that,

$$u(x, \tau) = \frac{1}{\sqrt{2\pi}} \int_{-\frac{x}{\sqrt{2\tau}}}^{\infty} u_0(v\sqrt{2\tau} + x) e^{-\frac{1}{2}v^2} dv \quad (2.8)$$

In this way we have the following,

$$u(x, \tau) = \frac{L}{K\sqrt{2\pi}} \int_{-\frac{x}{\sqrt{2\tau}}}^{\infty} e^{-\frac{1}{2}[-(\lambda-1)(v\sqrt{2\tau}+x)+v^2]} dv \quad (2.9)$$

developing the expression (2.9) and completing square,

$$u(x, \tau) = \frac{L}{K\sqrt{2\pi}} e^{\frac{1}{2}(\lambda-1)x + \frac{1}{4}(\lambda-1)^2\tau} \int_{-\frac{x}{\sqrt{2\tau}}}^{\infty} e^{-\frac{1}{2}[v - \frac{\sqrt{2}}{2}(\lambda-1)\sqrt{\tau}]^2} dv \quad (2.10)$$

Making the substitution $\rho = v - \frac{1}{2}(\lambda-1)\sqrt{2\tau}$, it has to be $d\rho = dv$. Now, if we do $d = \frac{x}{\sqrt{2\tau}} - (-\frac{1}{2}(\lambda-1)\sqrt{2\tau})$ we have,

$$u(x, \tau) = \frac{L}{K\sqrt{2\pi}} e^{\frac{1}{2}(\lambda-1)x + \frac{1}{4}(\lambda-1)^2\tau} \int_{-d}^{\infty} e^{-\frac{1}{2}\rho^2} d\rho \quad (2.11)$$

and therefore,

$$u(x, \tau) = \frac{L}{K} e^{\frac{1}{2}(\lambda-1)x + \frac{1}{4}(\lambda-1)^2\tau} \Phi(d) \quad (2.12)$$

Where Φ see [8], is the normal standard distribution. Returning the substitution (2.5) we have,

$$w(x, \tau) = e^{-\frac{\lambda-1}{2}x - \frac{(\lambda+1)^2}{4}\tau} \left[\frac{L}{K} e^{\frac{1}{2}(\lambda-1)x + \frac{1}{4}(\lambda-1)^2\tau} \Phi(d) \right] = \frac{L}{K} e^{-\lambda\tau} \Phi(d), \quad (2.13)$$

and from substitutions (2.2) you have to,

$$V(S, t) = L e^{-\lambda\tau} \Phi(d) = L e^{-\frac{2r}{\sigma^2}(\frac{1}{2}\sigma^2(T-t))} \Phi(d) \quad (2.14)$$

and finally we have,

$$V(S, t) = L e^{-r(T-t)} \Phi(d) \quad (2.15)$$

Where,

$$d = \frac{\ln\left(\frac{S}{K}\right) + (r - \frac{1}{2}\sigma^2)(T-t)}{\sigma\sqrt{T-t}} \quad (2.16)$$

3 Payoff with a finite number of steps

If in Problem posed by the theorem (2.1), we consider the parameters K and L as variables and rename the variable $V(S, t)$ as $C(S, t, K, L)$, we can rewrite

the problem as,

$$\left. \begin{aligned} \frac{\partial C}{\partial t} + \frac{1}{2}\sigma^2 S^2 \frac{\partial^2 C}{\partial S^2} + rS \frac{\partial C}{\partial S} - rC &= 0 \\ C(S, T, K, L) &= \begin{cases} 0 & \text{if } S < K \\ L & \text{if } S \geq K \end{cases} \end{aligned} \right\} \quad (3.1)$$

So, for (2.15) and (2.16) we have that the solution of (3.1) is given by

$$C(S, t, K, L) = L e^{-r(T-t)} \Phi \left(\frac{\ln \left(\frac{S}{K} \right) + (r - \frac{1}{2}\sigma^2)(T-t)}{\sigma\sqrt{T-t}} \right) \quad (3.2)$$

Theorem 3.1. *If $V(S, t)$ is the price of the call option defined in (2.1) where $f(S)$ is given by,*

$$f(S) = V(S, T) = \begin{cases} 0 & \text{if } S < K_1 \\ L_1 & \text{if } K_1 \leq S < K_2 \\ L_2 & \text{if } S \geq K_2 \end{cases}$$

where $0 < K_1 < K_2$, and L_1, L_2 are two arbitrary real numbers, then $V(S, t) = C(S, t, K_1, L_1) + C(S, t, K_2, L_2 - L_1)$.

Proof. Consider a portfolio P consisting of long positions in call options with constant payoff as those described in the theorem (2.1) with the same underlying asset and the same expiration time T . Suppose that the portfolio is formed by a unit of each of two options $P = \{O_1, O_2\}$, where O_1 is an option with strike K_1 and payoff L_1 and O_2 is an option with strike K_2 and payoff $L_2 - L_1$. Consider another portfolio $Q = \{O_3\}$, formed by a unit of the option whose payoff is given in the theorem (3.1). The payoff of portfolio P is the sum of f_1 and f_2 .

$$f_1(S) = \begin{cases} 0 & \text{if } S < K_1 \\ L_1 & \text{if } S \geq K_1 \end{cases} \quad f_2(S) = \begin{cases} 0 & \text{if } S < K_2 \\ L_2 - L_1 & \text{if } S \geq K_2 \end{cases}$$

And the payoff of portfolio Q is,

$$f_3(S) = \begin{cases} 0 & \text{if } S < K_1 \\ L_1 & \text{if } K_1 \leq S < K_2 \\ L_2 & \text{if } S \geq K_2 \end{cases}$$

So we can see that $f_3(S) = f_1(S) + f_2(S)$ this is, the two portfolios have the same payoff, and consequently by the principle of non-arbitrage, see [6] the portfolios P and Q have the same value. So finally we have to

$$V(S, t) = C(S, t, K_1, L_1) + C(S, t, K_2, L_2 - L_1).$$

That which was to be demonstrated.

Let's consider now a finite partition of $\mathbb{K} = \{k_1, k_2, \dots, k_m\}$ of interval (S, ∞) and a set $\mathbb{L} = \{l_1, l_2, \dots, l_m\}$ of real numbers, and suppose that the function $f(S) = f_m(S)$ is given by,

$$f_m(S) = \begin{cases} 0 & \text{if } S < k_1 \\ l_1 & \text{if } k_1 \leq S < k_2 \\ l_2 & \text{if } k_2 \leq S < k_3 \\ \cdot & \\ \cdot & \\ \cdot & \\ l_m & \text{if } S \geq k_m \end{cases} \quad (3.3)$$

And again consider the call option given in equation (2.1), where the boundary condition is given by (3.3). If we denominate as $V(S, t)$ the price of the option thus defined then, doing induction with the result obtained in Theorem (3.1), we have

$$V(S, t) = C(S, t, k_1, l_1) + \sum_{n=2}^m C(S, t, k_n, l_n - l_{n-1}).$$

4 Example of application

Here are two examples. In both cases, be $T = 1$, $r = 0.03$ and $s = 0.15$. Let's name $C_1(S, t)$ the price of a call option with strikes at $k_1 = 10$, $k_2 = 12$ and $k_3 = 13.5$, with staggered payments $l_1 = 1$, $l_2 = 1$ and $l_3 = 3$. In the second example, let's name $C_2(S, t)$ the price of a call option with strikes at $k_1 = 10$, $k_2 = 11$ and $k_3 = 12$, with staggered payments $l_1 = 1$, $l_2 = -2$ and $l_3 = 3$.

The following figure shows the graphs of $V_1(S, t)$ and $V_2(S, t)$ call options with three-step payoff.

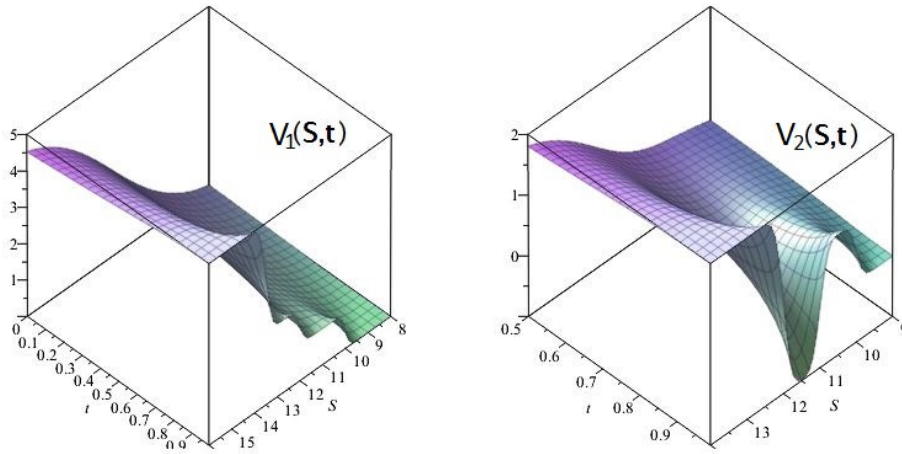


Figure 1: V_1 and V_2 call options with three-step payoff

For V_1 we can observe as the times are approaching in which the payments are presented, the price of the option accelerates quickly and assumes said payment. V_2 the second case is still more strange. Since the second payment is negative ($l_2 = -2$), the price of the option temporarily becomes negative. In this case we can see that if the payments are not close to the $S - K$ value, the contract should not be called a call option, it would be more convenient to call it a financial derivative, more appropriate instrument for speculation, which would allow to assume short positions.

5 Conclusions

The model considered here shows us that financial instruments allow great flexibility. Since the values that make up the set \mathbb{L} can be negative or positive, allows the parties to take long or short positions according to the profiles managed by the investors. If $\|\{k_1, k_2, \dots, k_m\}\| \rightarrow 0$, what it implies as a necessary condition that $m \rightarrow \infty$, then we can observe that practically any condition of boundary $f(s)$ can be approximated by a stepped function like that presented in equation (3.3).

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